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USERS MANUAL FOR STREAMTUBE CURVATURE ANALYSIS

ANALYTICAL METHOD FOR PREDICTING THE PRESSURE DISTRIBUTION ABOUT A NACELLE AT TRANSONIC SPEEDS

VOLUME I

by J.S. Keith, D.R. Ferguson, and P.H. Heck

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1.0 INTRODUCTION

Aircraft have been designed with the NASA-developed supercritical wing to fly at cruise Mach numbers approaching one. The need for low-installed drag and high-drag-divergence Mach number nacelle installations is necessary to the success of this design. Design techniques are required to evaluate these nacelles on an isolated basis and then on an installed or integrated basis.

For this reason NASA has a program underway to provide design information for low-drag, high-drag-divergence Mach number isolated nacelles suitable for use with advanced high bypass ratio turbofan engines. One element of such a program was the development of a method to predict the inviscid presure distribution and flow field about an arbitrary axisymmetric ducted body at transonic speeds. The prediction technique will provide the means to conduct parametric studies so that the nacelle design criteria could be evaluated to select configurations for further experimental investigations. The prediction technique would provide guidance during wind tunnel testing to develop nacelle shapes which would minimize drag within given design restraints.

Several techniques of solving the inviscid equations of motion about arbitrary two- or three-dimensional bodies at transonic speeds are presently available; however, there are no computer programs available which treat air inlet or nacelle configurations. The objective of the development of this computer analysis was the prediction of flow fields about isolated nacelles at transonic conditions. The solution technique was further specified to give accurate results consistent with the requirement of relatively short computing time per input case as compared to that required for a time dependent finite difference method of solution. The method utilized to compute the flow field is the Streamtube Curvature Relaxation technique.

The Streamtube Curvature Method (STC) of solving external flows has not been discussed significantly in the literature; however, the method is a very natural one. For example, engineers frequently rely on one-dimensional compressible flow relationships for a first-order solution to ducted flows.

The STC approach is similar except that a number of confluent streamtubes, with slightly different properties, are added together to obtain the total flow in the channel. Each streamtube is handled in much the same way as is the one streamtube in the one-dimensional problem. In the limit, as the size of the individual streamtubes approaches zero, the STC method satisfies the inviscid equations of motion exactly.

This report describes the structure of the computer program, Streamtube Curvature Analysis (STC), and the program usage and operation. Two types of information are included in this User's Manual, 1) user oriented input sheets and output definitions along with one example case, and 2) programmer oriented descriptions showing program structure, program nomenclature, program messages and error codes, and operating instructions. The program listing is included as a separate document.

2.0

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3.0 PROBLEM DESCRIPTION

The Streamtube Curvature Analysis was formulated as a computer program to solve the inviscid equations of motion over a two-dimensional body (plane or axisymmetric) at transonic speeds. The computer program determines the flow field properties, streamlines, and pressure distribution over typical isolated nacelles and calculates the external pressure drag and the additive drag. (The additive drag is defined as the integral of pressure multiplied by the axial projection of the area taken along the entering streamtube from the undisturbed free stream conditions to the stagnation line on the cowl lip.) The solution is the direct type in that nacelle shape, mass flows, and flight Mach number shall be the prime input data.

The computer program is capable of analyzing the following geometries:

- a. Two-dimensional inviscid inlet problems without side spillage at zero or finite angle of attack.
- b. Axisymmetric zero-angle-of-attack isolated nacelle problem with:
 - 1. Short cowl nacelle in which fan duct air of a turbofan engine exhausts upstream of the primary air nozzle, and the pressure distribution on the aft nacelle (waist cowl) must be determined.
 - Long duct nacelle in which the exhausts of both streams are confluent at the exit or mixed upstream at the exit.
- c. In all cases, the flow field may be calculated in the presence of a centerbody (or ramp) whose leading edge may be positioned either forward or aft of the cowl lip plane.

The flow field boundaries can be located as far upstream, and laterally displaced from the nacelle as far as practicable, to ensure minimum disturbances at the boundary and as far downstream as necessary to ensure correct nacelle trailing edge flow conditions. The program is capable of computing the inlet internal flow up to the assumed location of the engine face. The exhaust nozzle weight flow and aerothermodynamic properties of the exhaust flow shall be input quantities. The velocity of the exhaust shall be sonic or greater.

The computer analysis is capable of predicting the approximate location of any embedded normal shock in the transonic flow field over the nacelle. It was also desired that the analysis include free-stream Mach numbers greater than one by using the approximate method of Moeckel for the bow shock shape, but the STC approach was not compatible with the approximate bow wave definition.

The computer program was structured so that two separate computer source decks can be set up. One deck was limited by the requirement that the central memory storage could not exceed 70,000₈ (octal) locations on a CDC 6400 and/or 6600 computer and was thus restricted to a relatively coarse computational mesh network. The second deck utilized a finer computational mesh and included refinements in the stagnation line region and in regions of high velocity gradients. The refined version was limited to a central memory storage not to exceed 140,000₈ (octal) locations. In actuality, the most useful deck utilizes 768 grid intersection points and uses a central memory storage of 106,000 octal locations.

The size of central memory storage required is a function of the defined table sizes. These table sizes may be changed to meet the user's needs. The method to change the table size is included in this User's Manual. Otherwise, the basic logic of the STC program is identical and all the capabilities defined above are always available.

The coding of the computer program meets the following requirements:

- 1. The program has been written to run on the LRC's CDC 6400 and/or 6600 computers, or any similar CDC 6400 and/or 6600.
- 2. The bulk of the computer program has been coded in CDC FORTRAN 2.3 language. At least one subroutine has been coded in CDC Compass 1.1 language. The programs have been written to run under the SCOPE 3.1 operating system.
- 3. All input/output has been accomplished with CDC FORTRAN 2.3 statements. The standard system file names of INPUT for card reading and OUTPUT for printing have been used. In addition, input from tape files and output to tape files has been used.

The description of the required capabilities of STC do not include all possible features that are included in the computer analysis. The user has control over the amount of grid refinement or computational mesh size, both by specifying local areas of mesh refinement and by setting the number of overall flow field refinements. The input geometry may be specified as coordinates only or coordinates and local surface angles on any boundary. Multiple channels may be defined so that inlets with acoustic splitters can be analyzed.

4.0 METHOD OF SOLUTION

4.1 Basic Equations

The STC Program is designed to solve the equations of motion along streamlines, ψ = constant lines, and along lines which are orthogonal to the streamlines, ξ = constant lines. The variable ξ is introduced to avoid confusion with the velocity potential ϕ which is only applicable when the flow is irrotational.

Across the streamlines, the continuity and Crocco form of the momentum equation are written:

Continuity:
$$\partial A = \frac{\partial \psi}{\partial V}$$
 (5 = Const) (1)

Momentum:
$$\frac{1}{2} \frac{\partial (v^2)}{\partial n} = -\frac{v^2}{rm} + \frac{\partial H}{\partial n} - T \frac{\partial S}{\partial n} \qquad (5 = Const) \qquad (2)$$

Along the streamlines the following forms of the energy and momentum equations apply:

Momentum:
$$\frac{DS}{Ds} = 0$$
 $(\psi = Const)$ (3)

Energy:
$$\frac{DH}{Ds} = 0 \qquad (\Psi = Const) \qquad (4)$$

where:

A = Flow cross-sectional area = $\int 2^{\Pi} r \partial n$

C = Curvature of the streamline

H = Stagnation enthalpy

n = Distance along the orthogonal

p = Static pressure

r = Radial coordinate

s = Distance along the streamline

S = Entropy

T = Static temperature

V = Velocity

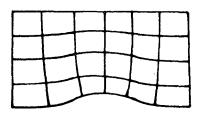
 ψ , W = Stream function, cumulative flow rate

 ρ = Density

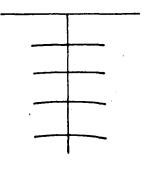
The solution method is an extension of the streamline curvature method. It may be briefly described as follows: First a crude grid of streamlines and orthogonal lines are assumed. (Please refer to Fig. 4-1). Second, the curvature of the streamlines at each of the grid points is evaluated. Third, the momentum equation is integrated along a line normal to the streamlines to obtain velocity and the continuity equation is integrated to determine the "correct" streamline positions (for the assumed curvature field). These are indicated by the "x" in Fig. 4-1. Fourth, an adjustment, on, is computed by considering (1) the difference between the computed and assumed streamline positions and (2) the effect of the implied curvature modification in the integrated momentum equation. Finally, the streamlines are repositioned by the on values.

Because the movement of any one grid point alters, through a change in curvature, the velocity at nearby points, it is highly desirable to account for these interrelating point adjustments simultaneously. The utilization of a simultaneous solution procedure, employed here, is not part of the classical streamline curvature method [1, 2, 3]. In comparison, the classical method yields calculation times which are very slow, especially for a closely spaced calculation grid. In concept, the set of simultaneous equations for

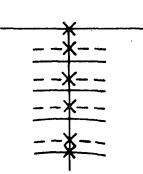
1. Assume a Crude Grid



2. Evaluate Curvature



3. Integrate The Crossstream Momentum Eqn. and Continuity Eqn. To Determine The "Correct" Streamline Positions.



4. Solve The Matrix Equation for δn and Move The Grid Points.

the normal streamline adjustments are formulated from the finite difference equivalent of the following equation:

$$\frac{\partial^{2} (\delta \mathbf{n})}{\partial \psi^{2}} + \frac{(1 - \mathbf{M}^{2})}{(\rho \mathbf{v})^{2}} \quad \frac{\partial^{2} (\delta \mathbf{n})}{\partial \mathbf{s}^{2}} = \mathbf{F}$$
 (5)

where:

on = Required streamline adjustment in the normal direction

 Ψ = Stream function

s = Curvilinear distance along a given streamline

M = Mach number

 $\rho V = Flow per unit area$

F = Driving (or error) function derived from the solution to the integral continuity and normal momentum equations.

This equation is derived in (Ref. 4) for the special case of isentrepic 2-dimensional flow. (These limiting assumptions are utilized only to maintain simplicity of illustration; they are not part of the computer program.) From a mathematical point of view, the above equation is similar to the conventional equations for velocity potential or stream function, namely,

$$\frac{(1 - M^2)}{y} \frac{\partial^2 \emptyset}{\partial y^2} - \frac{2M}{x} \frac{M}{y} \frac{\partial^2 \emptyset}{\partial x \partial y} + \frac{(1 - M^2)}{x} \frac{\partial^2 \emptyset}{\partial x^2} = 0$$
 (6)

$$\frac{(1 - M_y^2)}{y^2} \frac{\partial^2 \psi}{\partial y^2} - \frac{2M_x}{x} \frac{M_y}{y} \frac{\partial^2 \psi}{\partial x \partial y} + \frac{(1 - M_x^2)}{x} \frac{\partial^2 \psi}{\partial x^2} = 0$$
 (7)

where

x and y are coordinates in a two-dimensional rectangular system and \emptyset and ψ are the velocity potential and stream function, respectively. (Again, all of the equations have been restricted to isentropic flow for illustration.)

However, for the purpose of calculating transonic flow, the use of Eq. (5) offers a distinct advantage over Eqs. (6) or (7) for the following reason: Because the grid is always alligned in the streamline and normal to streamline directions, no cross-derivatives appear. In consequence, the finite difference star is simply switched from a subsonic representation to a supersonic representation illustrated in Fig. 4-2.

Notice that for supersonic flow, no points downstream of the orthogonal line are included. This reflects the physical reality that disturbances downstream will not affect the flow upstream. It is, of course, because the coefficient term, $(1-M^2)$, passes through zero and changes sign that the star-switching noted in Fig. 4-2 is appropriate.

If the grid system is not alligned with the flow direction, a cross derivative appears in the equation, as in Eq. (6). Unfortunately, the mixed derivative coefficient, $M_{X,Y}^{M}$, does not have the same sign change property and, therefore, star-switching with this equation is more difficult for general flows with some angularity.

The extended streamline curvature method, here referred to as the Streamtube Curvature (STC) method, has then the following features:

- o No additional complexities arise when the flow is rotational.
- o The slip lines between the exhaust jet and the external flows can be handled precisely. (The procedure is to consider two coincident streamlines. Their position and pressure are the same; their velocity and stagnation properties may be different.)
- o From a numerical point of view, the streamline/orthogonal line oriented grid facilitates the analysis of transonic fields, as described above.
- o The streamline/orthogonal line grid also provides a mapping of the flow field into a rectangular domain. This is helpful from the standpoint of computer program organization.

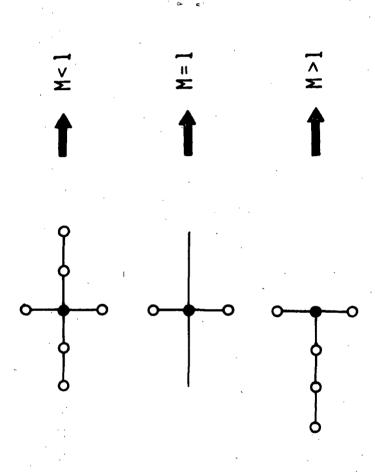


Fig. 4-2 Finite Difference Stars for Subsonic & Supersonic Flow

The STC Program has also been designed

- o to handle multiple streams,
- o to adjust the flow rates of the jet exhaust streams to meet the (2-dimensional) choking condition,
- o to place grid points at locations in the flow field where they are needed, as determined by local variations of the dependent variables, and
- o to allow external flow analysis by incorporating matched near-field and far-field solutions. The far-field solutions are obtained analytically, utilizing small perturbation theory.

4.2 An Outline of The Calculation Steps

The operations performed by the STC Program may be outlined as follows:

- 1. Define the flow regions and locate (approximately) the "primary" orthogonals and the streamlines which divide the internal and external flows.
- 2. Refine the grid as required by inserting additional streamlines and orthogonal lines between those already existing.
- 3. Compute the streamline angles and curvatures.
- 4. Compute the orthogonal line angles and move the grid points along the streamlines to obtain orthogonality.
- 5. Compute the velocities on the "far-field" boundary.
- 6. Adjust the flow rates in the exhaust streams, if any, to meet the calculated choking flow rate.
- 7. Integrate along each orthogonal the momentum and continuity equations $\begin{bmatrix} \text{Eqs. (1)} & \text{and (2)} \end{bmatrix}$.
- 8. Determine if the streamline positions are within a "rough tolerance".

 If so, return to Step 2 for additional grid refinement (unless grid refinement limits have already been reached). Otherwise, continue to Step 9.

- 9. Determine if the streamline positions are within final tolerance.
 If so, jump to Step 13. Otherwise continue to Step 10.
- 10. Set up the matrix equation for the streamline correction. δ_n .
- 11. Solve the matrix equation.
- 12. Modify the streamline positions by δn , and return to Step 3.
- 13. Calculate and print the output quantities; then return to Step 1 for the next case, if any.

The first operation includes reading the card input for a description of the geometry and flow properties. The computer program has been written to have general capability for analyzing a great variety of configurations. The first step in the programmed logic is to develop a table of orthogonals or calculation stations for each of the several flow regions. The regions are determined as illustrated in Fig. 4-3 so the calculation can proceed from upstream to downstream. The boundary of each region is defined as a primary orthogonal. As shown in Fig. 4-4, the initial grid which is developed contains only the primary orthogonals and the double streamlines which separate the various streams.

The second step in the computational procedure is the grid refinement. The very crude grid, obtained in Step 1, is refined before the first solution of the flow field equations is executed. A new orthogonal is placed within each region and, likewise, a streamline is inserted in the middle of each channel. In the external channel, additional streamlines are placed close to the body. After the solution has been obtained for this net, the grid intervals are halved as required. This may be likened to the steps taken when one "flux plots" a flow field by hand. First, major flow lines and normals are sketched in, and then more and more streamlines and orthogonal lines are added until the desired resolution is obtained. At each step in the process the positions of the lines are adjusted to meet the correct solution requirements. The procedure automatically provides for grid refinement in regions of high curvature and high acceleration or deceleration. The streamline and orthogonal lines which are added between existing lines are not required to span the field if

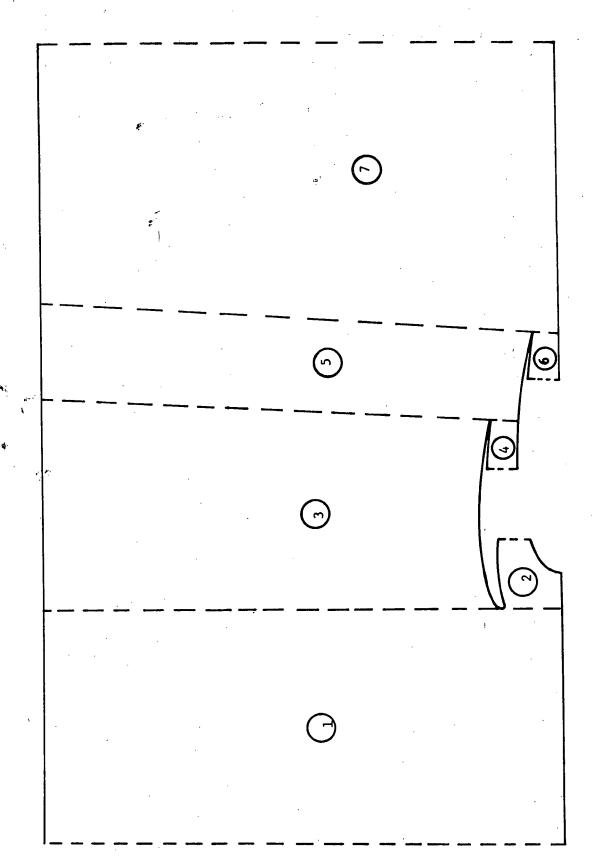


FIGURE 4-3 SUBDIVISION OF THE FLOW FIELD INTO REGIONS

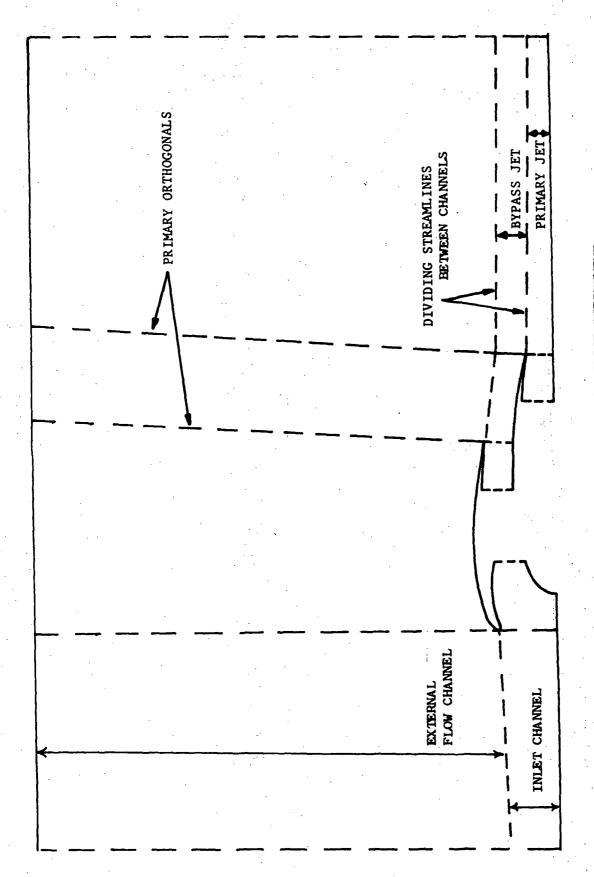


FIGURE 4-1 INITIAL STREAMLINE/ORTHOGONAL GRID BEFORE THE FIRST REFINEMENT

only local refinement, near the body, is required. The refinement procedure presently built into the program uses a criteria involving the distance and velocity increment between grid points. These refinement criteria are discussed in detail in Section 10 and 12.

The third step in the method is to determine the angles and curvatures of the streamlines at each grid point. For subsonic portions of the flow field this is performed by fitting a piecewise continuous cubic polynominal in a coordinate system which is locally rotated for each interval. The resulting fit is analogous to the curve produced by a beam which is loaded by discrete forces so as to pass through the given grid points. The locally rotated coordinate system removes the restriction that requires the slope to be small. For grid points located in a supersonic region, backward difference formulas are employed. Either 3-point, 4-point, or 5-point formulas may be optionally selected. Again the coordinate system is rotated so that slopes in the curve fitting coordinate system are small.

In the fourth step the orthogonality of the grid points is checked and points are moved along the spline curve as required to achieve normal intersections between the two sets of lines. Also, the normal distance, n, is computed for each grid point as measured from the lower boundary of the orthogonal.

When the initial grid is set up, a boundary is placed some distance away from the body. This boundary becomes the interface between the near-field and far-field solutions. The near-field is computed by the streamtube curvature method and the far-field is computed by linear small perturbation theory. In the process of iterating, this boundary (which is also a streamline) will float so that its shape and velocity distribution are matched by both the inner and outer solutions. In practice, the shape of the interface streamline (also referred to as the far-field boundary) is first assumed. Using the far-field equations, the velocity distribution is calculated. This is Step 5. These velocities are subsequently employed in the near-field analysis and from this comes a revised shape for the interface streamline. Revised velocities will then be computed in Step 5 during the following iteration cycle, and so forth.

Step 6 is the modification, as required, of the flow rates of the exhaust streams. For boattail analysis of nacelles, the internal geometry of the exhaust passage is required input to the STC program. Because of streamline curvature effects, the discharge coefficient for the nozzle will be somewhat less than unity. The user, however, may input a flow rate based on unity discharge flow coefficient or, for the matter, any approximate value. Determination of the velocity distribution across the throat of the nozzle will be determined within the STC framework and the evaluation of the maximum "choked" flow rate is Step 6 of the calculation procedure.

Step 7 is the solution of the flow field equations per se. This section of the program is referred to as the "flow balance"; Eqs. (1) and (2) are integrated. In the external regions of the field, the momentum equation is integrated from the far-field interface boundary to the body (or to the centerline or lower boundary, whichever exists). The integral form of the momentum equation is:

$$\ln V_o^2 - \ln V_{FF}^2 = 2 \int_{n_o}^{n_{FF}} c_{dn}$$
 (8)

where:

 $V_{\rm FR}$ =. Velocity as determined in Step 5 along the far-field streamline.

 V_0 = Velocity at any streamline with orthogonal distance n_0 .

 n_{FF} = Distance measured along the orthogonal to the far-field streamline.

Although not reflected in Eq. (8), the effect of varying total pressure behind a shock wave is also included. Also, if a slip-line occurs in the field, the velocity jump equations,

$$P_{S} = P_{T_{+}} \left[\frac{T_{S_{+}}}{T_{T_{+}}} \right]^{\frac{\gamma}{\gamma - 1}} = P_{T_{-}} \left[\frac{T_{S_{-}}}{T_{T_{-}}} \right]^{\frac{\gamma}{\gamma - 1}}$$
(9a)

$$c_{P} + T_{T} + v_{2}^{2} = H_{+}$$
 (9b)

$$C_{P} - T_{T} + V^{2} = H_{D}$$
 (9c)

are employed where the subscripts (+) and (-) denote conditions on the streamlines above and below the slip-line, respectively.

The velocity, total temperature and total pressure allow determination of the density at each grid point, and the inverse product of density and velocity is integrated to find flow area.

$$A_2 - A_1 = \int_{\psi_1}^{\psi_2} \frac{\partial \psi}{\partial V}$$
 (10)

The cumulative flow areas calculated by Eq. (10) are compared with the geometric areas of the streamlines used in Step 3. The difference between these two values is used as a convergence check (Steps 8 and 9) and in the streamline correction equation, Step 10.

For internal flow orthogonals, the velocity at the outer boundary $(v_{FF} \text{ in Eq. (8)})$ is not known. Instead, an iteration process is employed whereby the outer boundary velocity is varied to obtain a match in the calculated geometric passage area.

In Steps 10 and 11 the proper adjustment of the streamline positions is determined and in Step 12 the grid points are moved in the normal direction by this computed adjustment.

The iterative sequence is to start with a crude grid, as noted above, and to repeat Step 3 through 12 until the flow balance error is small. This is often accomplished in one or two iterations. The grid is then refined to the next level and the field is reconverged. The refinement/convergence process is continued until the grid refinement criteria is satisfied, or alternately, until computer storage limits are reached. At this point, additional loops through Steps 3 to 12 may be performed until the flow balance error is satisfactory.

A complete description of the details of the numerical procedure is contained in Reference 4.

5.0 PROGRAM DESCRIPTION

5.1 Data Storage Tables

The framework of the STC program is designed to allow flexibility as to the configuration to be analyzed. For example, very weak limits are placed on the number of flow boundaries and the number of channels into which the flow is split. And no specific limits are placed on the number of streamlines or the number of orthogonal lines in any given region of the flow. To acomplish this, the bulk of the calculation data is saved in arrays which are singly dimensioned. Within each array the data are packed together to maximize storage efficiency. Descriptions of these tables are provided below.

5.1.1 Field Tables

Flow field data are stored in singly subscripted arrays, one for each variable. The quantities saved at each streamline -orthogonal line grid intersection are as follows:

Z .	axial position, abscissa
R	radial or vertical position, ordinate
VM	velocity
PHI1	streamline angle, measured from horizontal
CURV	curvature of the streamline, $-d\phi/ds_{\gamma}$
S1	curvilinear distance along the streamline
S2	curvilinear distance along the orthogonal line
В	coefficient in matrix equation for DS2,
	indicator of subsonic (B>O) or supersonic
	(B<0) velocity
RHS	right hand side of matrix equation for DS2
DS 2	correction of streamline positions

In the Fortran coding M is the symbol commonly used as the subscript for the above arrays and NM is the number of field points (or maximum value of M). The points are grouped by orthogonals starting at the upstream orthogonal. Points along the orthogonal are grouped together.

Hence, the point below and above the Mth point are (M-1) and (M+1) respectively. The neighbors in the streamwise direction, however, are determined by referring to the JMS-table described in Section 5.2.

5.1.2 Channel Input Data Table

Information such as the boundary coordinates and flow properties is compactly stored in a single array, TABLES, so that only the total amount of information saved is limited by the array size. No limit is placed on the amount of information to be placed in any one Table of which there are six:

- o channel input table
- o boundary table
- o table of convected properties
- o table of wake displacement thickness
- o flow adjustment table
- o station table

In the first table, CHDATA, input information read from page STC/ sheet-3 is stored. The information is stored in subtables, one subtable for each channel, and the arrangement of each subtable is as follows:

CHNAM	channel name (BCD)
LHNEXT	length of subtable
WTFLOW	flow rate (if input)
TTO	total temperature
PTO	total pressure
TSO	static temperature
PSO	static pressure
масно	Mach number
AO	flow cross-section area
VARY	indicator as to whether the
	flow rate may be varied
RG	gas instant
GAM	ratio of specific heats

NR not operational

NC "

TAB " "

BB(NR&NC) not operational, zero length array

Except for the first two words, CHNAM and LHNEXT, all of the above input items are optional input and they are all equal to BITS unless values are supplied according to input instructions for STC/Sheet-3. If data for a second channel are supplied, these data will follow the first channel and so forth for any number of channels. The first word of the CHDATA table is at location LHO and the last word is at location LHE relative to the origin of the TABLES-array. If LHE=LHO-1, no channel data has been input and the channel data table has zero length. In the Fortran coding, the subscript LH is used to refer to the channel data.

Channel information is read into the STC program by subroutine RCD; the stored channel data is utilized by routines RTCFI, BCONV, ADJWF and ISBOT.

5.1.3 Boundary Table

Directly following the channel data are the coordinates of the boundaries. Again a subtable for each boundary is constructed and the information is stored in the following order:

BDT boundary name

LBNEXT length of subtable

LBZ1 index increment to first coordinate

in ZBT, RBT, ANGBT-lists

CHNAME channel with which the boundary data

is associated

UP upper or lower boundary indicator

(if the boundaries around a leading edge have been collated together, then

CHNAME(2)=UP is the name of the channel

above the leading edge and CHNAME(1) is the name of the channel below the leading

edge).

LEDEX index (relative to ZBT, RBT, ANGBT) of the leading edge point when boundaries are collated

ZBT(1) axial coordinate (x)

RBT(1) radial coordinate (y)

ANGBT(1) surface angle (measured from x-axis in

radians)

ZBT(2)

RBT(2)

ANGBT(2)

C

0

0

O

BDNAME

name of a specific boundary when several boundaries are collated together in one subtable

LBA, LBB

index limits relative to ZBT, RBT, ANGBT of the coordinates for BDNAME

(NOTE - the above 3 items are repeated for each boundary where LBZ1/3 is the number of collated boundaries. The existence of this information results in the displacement of the ZBT, RBT, ANGBT coordinates to higher memory locations. BDNAME, LBA and LBB are equivalenced to ZBT, RBT and ANGBT respectively).

Boundary coordinates are necessary input to the program so two or more subtables will always exist, stacked one after another. The first word of the BDYTAB table is at location LBDO and the last word is at location LBDE. LB is the subscript used to refer to the boundary data.

Boundary coordinates as supplied on page STC/Sheet-2 of the input sheets are read by routine RBD. This routine converts the angles from degrees

to radians, translates and rotates the coordinates as required and stores the points so that as one proceeds from one point to the next (or walks along the contour) one's left arm is next to the flow field. Thus, the ordering of points on an upper flow boundary will be reversed and the angles incremented by 180 degrees.

The several boundaries which may be defined to comprise one continuous contour are collated in subroutine BLDTAB. The boundary table is referenced in routine BDYPTM.

5.1.4 Table of Convected Properties

For each channel, a subtable of convected properties and channel flow data is built by subroutine BCONVT from data in the channel input table (if it exists) and input data from STC/sheet 1. This table contains some of the same information as the CHDATA table. Information contained in the CONVTB table is complete and follows a consistent format.

СН	channel name
LTNEXT	length of subtable
NPT	not operational (=1)
LPSI	(=15)
LTT	(=16)
LPT	(=17)
LRCU	(=18)
CRG	gas constant
CPGJ	specific heat at constant pressure
C2CP	twice CPGJ
QGAM	inverse of ratio of specific heats, = $1/\gamma$
FGT	(γ-1)/γ
FGP	γ/(γ-1)
FGR	1/(γ-1)
AREATB	area for calculating flow rate
PSI	flow rate for the channel

TT stagnation temperature
PT stagnation pressure
RCU not operational

Again the data for the several channels are stacked one after another. LTO and LTE are the first and last locations of the table relative to the origin of TABLES. LT is the subscript used to retrieve convected property information in subroutines BLDTBS, RBCONV, ADJWF and TTPT.

5.1.5 Table of Wake Displacement Thickness

The wake displacement table is only constructed if there exists a blunt trailing edge, and is arranged as follows:

X2W	streamline coordinate, ξ_2
LWNEXT	length of subtable, = 2N+2
S1W (1)	list of distances from trailing edge
S1W (2)	
:	
S1W (N)	
DST (1)	list of wake displacement thicknesses
DST (2)	
:	
DST (N)	

This table is built in the subroutine BLDTBS. DST is determined so that the wake thickness equals the trailing edge thickness at S1W=O. Thereafter the wake thickness decrease at the rate of 0.1 times the distance from the trailing edge. At 10 trailing edge thicknesses downstream, the wake thickness is zero.

As many wake thickness subtables are built as there are blunt trailing edges. The wake thickness table begins within the TABLES-array at location LWO and ends at LWE. The table is referenced by the TTPT routine.

5.1.6 Flow Adjustment Table

The flow adjustment table is also created in the BLDTBS routine, one subtable for each trailing edge. The information contained is as follows:

X1F	orthogonal coordinate of the t.e., ξ_1
X2F	streamline coordinate of the t.e., ξ_2
X1BF	ξ_1 coordinate of the choked station of the flow
•	below the t.e. if not X1F
X1AF	ξ_{γ} coordinate of the choked station of the flow
	above the t.e. if not X1F
S1F	curvilinear streamline distance to the trailing
	edge (along the upper surface of the airfoil).
	This value is used for interpolating the wake
	displacement thickness.
NCHB	number of channels below the t.e.
NCHA	" " above " "
JORDER	= -1 if the single channel flow is choked
	= 1 if channel flow rates below the t.e. are known
	= 2 if channel flow rates above the t.e. are known
VNR (12)	12 element storage array used by subroutine
	NEWRAP for the flow iteration

The data stored in this table is used by subroutine ADJWF which adjusts the flow so that at each trailing edge the pressure difference from one side of the trailing edge to the other is reduced to zero (to satisfy the kutta condition). If this condition cannot be satisfied, the flow in one of the channels will be choked and routine ADJWF adjusts the flow to the maximum choked value. The flow adjustment table is located between LFO and LFE. Each subtable is NFCOLS (=20) in length.

5.1.7 Station Table

The station table is the last of the compacted tables (except for the shock point table which is appended to it) and it contains information

for each orthogonal line. The table grows during the calculation process because the number of orthogonals is increased to obtain a refined grid. Because it is the last table it can easily be extended into the unused portion of the allotted memory. The data saved for each of the orthogonals is arranged in the station table as follows:

X1	stat	ion	C001	rd1	na	te,	ξ ₁
*	-		_			_	

LNEXT length of subtable

MLB field point index of first (lower boundary)

point of the orthogonal

MUB field point index of the last (upper boundary)

point of the orthogonal

PRIM primary station indicator, T or F, (a primary

station, is one of the original grid stations

and it will pass through boundary end points).

TYPELB type of the lower boundary, i.e. SOLID,

FIELD, FARFLD, etc. for indicating proper

boundary condition

NAMELB name of the lower boundary used for

referencing the boundary table

ILB boundary (table) interval of the orthogonal

boundary intersection

FLB fractional position in that interval

S1LB curvilinear distance from beginning of the

interval

TYPEUB type of the upper boundary

NAMEUB name of the upper boundary

IUB interval of the upper boundary

FUB fractional position in the interval

S1UB curvilinear distance from the beginning

of the interval

VMB boundary velocity, used as an initial guess

for the velocity iteration in the FLOBAL

routine

DWDV .SCHOKE slope of the flows rate versus velocity curve used for the velocity iteration in the FLOBAL routine, = SCHOKE if flow is choked at this station X2CL ξ , coordinate of the control streamline used for positioning orthogonal lines

in the PTMOVE routine

SLSWI sonic line-shock wave indicator, = 1.0 for

mixed flow, = 0. otherwise

MCL field point index of control streamline,

used in PTMOVE only

This group of 20 items is repeated for each station. starting with the upstream and proceeding to the downstream stations. Field point *calculations are then performed by looping through the station table, starting with the first station at L=LO and proceeding to the last The last word of the last station is at location LESTA.

'The above set of six tables is initially constructed with gaps between each table. The channel data and boundary tables are constructed simultaneously in the RCD and RDC routines called from REDINP. size of the channel data routine is preset by the value of MAXLH. MAXLH is initialized to 400 but may be input as any value if such should be necessary.

After reading the card data input, at the beginning of the BLDTAB routine, the boundary data is moved down in memory so that it is just above the channel data. The gap between the two tables is thus eliminated.

The remaining four tables are then all built in subroutine BLDTBS. Again spaces between the tables are provided so that they can be constructed simultaneously and grow to the following lengths without interfering with each other:

Table Name	Input Variable	Default
	Name	Value
Convected Properties	MAXLT	200
Wake Displacement Thickness	MAXLW	200
Flow Adjustment	. MAXLF	200

At the end of the BLDTBS routine the gaps between the tables are eliminated by moving each table down in memory. The result is that all information contained in these tables is stored compactly, and the last table, the station table, has space into which it may expand. The length of all six tables combined is limited to the length of the TABLES-array, and this value is adjusted at program load time to meet the size requirements of the flow field.

5.1.8 Streamline Table

The streamline table is not stored in a compact arrangement. It consists of three arrays in a labled common SLTAB.

W cumulative flow rate for the channel

 $\xi_2 = \xi_2 - \text{coordinate}$

SLCHN channel name of which this streamline is a part

The streamline number, J, is the subscript used to access information in each of these three arrays. All of the streamlines for a given channel are together and in order (proceeding away from the centerline). However, no special ordering of channels is required.

5.1.9 Table of Leading Edge and Trailing Edge Points

The Leading Edge-Trailing Edge Point (LETEPT) table is constructed in routine BLDTAB and used in routine BLDTBS for the purpose of defining the flow regions and primary orthogonals. The data in this table is not saved after the BLDTBS routine is executed.

The information in this table is obtained from the boundary table. The ends of boundaries and double points contained within the boundaries are listed, together with the boundary and channel names. Each "line" of the LETEPT table contains the following ten items.

XE	axial coordinate of boundary end point or
•	double point
YE	radial or vertical coordinate
ANGE	mean angle of the flow at XE, YE
NLE	number of times the same point has occurred as an up-
	stream boundary end point. Normally NLE=O or 1. If
	NLE=2 then the point is a leading edge.
NTE	number of times point has occurred as a downstream
	end point. NTE=2 for trailing edge point. NLE=NTE=O
	for a double point in the boundary table
CHL	name of flow stream above point
CHU	name of flow stream below point
BDL	name of boundary (UPPER=F)
BDU	name of boundary (Upper=T)
NUSED	number of times the point has been used in developing
	the ORTCHN-table, initially = -1 for a double point

After the table is constructed the points (or lines) are sorted so that the upstream points are first and the points follow from upstream to downstream in order. If difficulty is encountered in the development of the basic grid, the information contained in the LETEPT-table may be helpful in diagnosing the error.

5.1.10 Table of Channels Embraced by Each Orthogonal

The LETEPT-table contains all points through which (primary) orthogonal lines are to pass. From this table the ORTCHN-table is developed as an aid to the construction of the initial grid of streamlines and orthogonal lines. The latter table contains a list of all of the channels embraced by each orthogonal. Specifically each "line" of the table contains:

LEDGE	index of	f the point in the LETEPT-table
LRPREV	previous	s line number (or ORTCHN-table index)
,	of the u	upstream orthogonal
CHNA(1)	channel	names
CHNA(2)	11	11
CHNA	11	11
CHNA(2)	H.	tt .

The above information is tabulated (one line) for each orthogonal. Also, the first two lines are developed as dummies for the purpose of listing all channels. Other dummy lines may also be inserted. LRD is the index increment between lines and is equal to the total number of channels minus two.

5.1.11 Table of Index Limits

The labeled common /IXØRIG/ contains the index limits for each of the above listed tables. The items and order of storage are as follows:

LHO	location of channel table origin
LHE	location of channel table end
LBDO	location of boundary table origin
LBDE	location of boundary table end
LTO	location of convected properties table origin
LTE	location of convected properties table end
LWO	location of wake displacement thickness table origin
LWE	location of wake displacement thickness table end
LFO	location of flow adjustment table origin
LFE	location of flow adjustment table end
LO	location of the station table origin
LESTA	location of the station table end
LSO	location of the shock point table origin
LSE	location of the shock point table end
LDUM(6)	unused
МО	unused
NM	number of field points
NJ	number of streamlines
NFCOLS	number of "columns" in the flow adjustment table
MAXNJ	maximum number of streamlines (dimensional limits are MAXNJ=128)
MAXOL	maximum number of points on any one orthogonal (dimensional
	limits are MAXOL=96)
MAXNM	maximum length of field arrays, calculated in subroutine REDINP
MAXLE	maximum table length, calculated in subroutine REDINP
LEO	location of the first word in the LETEPT-table, (=1)

LEE	location of the last word in the LETEPT-table
LRO	location of the first word in the ORTCHN-table
LRE	location of the last word in the ORTCHN-table
LRD	the ORTCHN-table is subdivided into lines and LRD is the
	length of the lines

5.2 Accessing Data in the Field Tables

The data stored in the field tables consist of the Z, R, S1, S2, PHI1, CURV, VM, B, RHS, and DS2 at each point in the field. An additional array termed the JMS table provides access to the information in the field tables. This information (subscripted M=1,NM) consists of:

J Streamline number

MU M subscript of upstream grid point; MU = 0 at beginning of streamline.

MD M subscript of downstream grid point; MD = 0 at end of streamline.

ISTAG Point type indicator

ISTAG = 0 - Normal point.

1 - Stagnation (or singularity) point.

- 2 Trailing edge point or a point fixed on the body surface used to locate a primary. orthogonal.
- 3 Point adjacent to a stagnation (singularity) point or an end point of a partial orthogonal.

Fig. The word content of each JMS entry is:

GE-635				•	
(36 bit word)	•	J 8 bits	MU 13 bits	MD 13 bits	ISTAG 2 bits
CDC-6400/6600	÷				
(60 bit word)		J	MU	MD	ISTAG
•	24	8	13	13	2
•	bits unused	bits	bits	bits	bits

On the GE-635, the machine word length presents a practical limit to both the number of streamlines (J=255) and the maximum field size (NM - 8191) It was felt that these limits represent a convenient maximum for any problem which might be encountered. Hence, the bit configuration for the JMS word on the CDC 6400/6600 is identical to that on the GE635, resulting in an

unused portion of 24 bits. The subroutines which pack and unpack the JMS table entries (SAVIX, GETIX, and GETRLX) are coded in the CDC assembly language COMPASS 1.1 in the interest of increased computation speed. These routines would have to be modified if a problem required a streamline number J in excess of 255 or a grid point index M greater than 8191.

5.3 STC Calculation Steps, Flow Chart, Overlay Description

The present section outlines the sequence of calculation steps performed by the STC Program and describes the overlay structure on the CDC 6400/6600 computers.

5.3.1 STC Calculation Steps & Flow Chart

The processing flow chart for the STC program is shown in Figure 5-1 and includes the principal subroutines, their function, and their associated output. The general calculation steps performed by the STC Program were outlined in Section 4, Method of Solution. Here the calculation steps will be identified with the subroutine performing that step.

The computer program has been written to analyze many types of geometries and flows. The user must identify the various flow boundaries and channels when the program input is compiled. These sets of flow boundaries (BDY) and channel names (CHN) define flow regions with specified properties of temperature, pressure, and velocity. It is the task of the program user to organize his problem so that each flow region is defined by the proper boundary and channel names (see Figure 4-3 and 4-4).

The first operation in the computer program consists of reading the card input for the description of geometry and flow properties in each flow region (REDINP), and then storing and building the various tables (BLDTAB, BLDTBS, BCONV). The channel data, boundary data, and flow property data are each stored in their respective tables. If necessary, the boundary points are smoothed and local angles at each boundary point are calculated.

The field point table and station table are started with the first unrefined grid of orthogonals and dividing streamlines. The boundary of each region is defined as a primary orthogonal. The dividing streamlines which separate the various streams are called double streamlines.

The next step in the computational procedure is to refine the very crude initial grid (REFINE) after calculating the distances between points along streamlines. A new orthogonal is placed within each region and a new streamline is inserted in the middle of each channel. In the external channel (identified by CHN EXT), additional streamlines are placed close to the body. After the solution for this grid has been obtained, the intervals are again halved as required.

As the calculation procedure continues, grid refinement is automatically provided in specified flow regions or in regions of high curvature and high acceleration and deceleration. The streamline and orthogonal lines which are added between existing lines are not required to span the field if only local refinement near a boundary is needed. These refinement criteria are discussed in Section 10 and 12.

After refining the grid, the next step (SLC) in the solution is to determine the angles and curvatures of the streamlines at each grid point. For subsonic portions of the flow field, this is performed by fitting a piecewise continuous cubic polynomial (beam) in a coordinate system which is locally rotated for each interval (Figure 5-3). The locally rotated coordinate system removes the restriction that requires the slope to be small. The matching conditions are the angles and curvatures at each point. At the end of streamlines which terminate at a flow exit boundary or extend to a flow inlet, the end curvature is specified. Normally the end curvature is zero, but the user may input a constant non-zero value of curvature.

For grid points located in a supersonic region, the subroutine SLC employs backward difference formulas in keeping with the switch to the star with no downstream points (Figure 4-2). Either a 3-point parabola, a 4-point piecewise cubic (beam), or a 5-point formula may be optionally selected. The 3-point parabola is preferred. Again the coordinate system is rotated so that slopes

in the curve fitting coordinate system are small. The end conditions for the supersonic curve fit formulas are a specified angle and zero curvature.

One additional task performed by SLC is the location of stagnation points and the definition of the dividing streamline intersecting the boundary at the stagnation point. At leading edges, the dividing streamline is set perpendicular to the boundary surface at the stagnation point, (Figure 5-4). An orthogonal which goes with the stagnation point is defined and the point on the first streamline is positioned.

PTMOVE checks the orthogonality of the grid points and moves the points along the spline curve as required to achieve normal intersections, (Figure 5-5), between the two sets of lines. Also, the normal distance, n, is computed for each grid point as measured from the lower boundary of the orthogonal.

When the near-field grid is defined, a boundary is placed some distance away from the body. This boundary becomes the interface between the near-field and far-field solutions. The near-field is computed by the streamtube curvature method and the far-field is computed by linear small perturbation theory, (Figure 5-6). In the process of iterating, this boundary (which is also a streamline) will float so that its shape and velocity distribution are matched by both the inner and outer solutions. In practice, the shape of the interface streamline (also referred to as the far-field boundary) is first assumed. Using the far-field equations, the velocity distribution is calculated. These velocities computed by FARFLD, are subsequently employed in the near field analysis and from this comes a revised shape for the interface streamline. Revised velocities will then be computed in FARFLD during the following iteration cycle, and so forth. FARFLD is a selected boundary option when the farfield boundary, BDY, is called FF. A solid boundary may also be specified by renaming the far-field boundary and defining the coordinates.

The next step (ADJWF) is the modification, as required, of the flow rates of the exhaust streams. For boattail analysis of nacelles, the internal geometry of the exhaust passage is required input to the STC program. Because of streamline curvature effects, the discharge coefficient for the nozzle will be somewhat less than unity. The user, however, may input a flow rate based

on unity discharge flow coefficient or, for the matter, any approximate value. Determination of the velocity distribution across the throat of the nozzle will be determined within the STC framework and the evaluation of the maximum "choked" flow rate is ADJWF of the calculation procedure.

The next three subroutines, STALOO, BRHS, and FLOBAL, develop the solution to the flow field equations represented by continuity, Eq. 1, and radial or cross-stream momentum, Eq. 2, (Section 4). At each station (STALOO) along a boundary, the flow equations are integrated along an orthogonal (FLOBAL) and the right hand side and the coefficient B (B = $[(1 - M^2)/^{0}V^2]$) in Eq. 5 are determined (BRHS). In the external regions of the field, the momentum equation is integrated from the far-field interface boundary to the body (or to the centerline or lower boundary, whichever exists). The cumulative streamtube flow areas are then calculated by integrating the continuity equation and compared with the geometric areas of the streamlines defined by SLC. The differences between the streamline position determined by the "flow balance" FLOBAL and by SLC is used as a convergence check. It also defines the right hand side or driving error function in the streamline correction equation, Eq. 5.

If the streamline positions are within a convergence tolerance the program logic loops back to REFINE. Additional streamlines and orthogonals are added as required by the refinement criteria. The refinement procedure presently built into the program uses a criteria involving the distance and velocity increment between grid points.

If the streamline convergence tolerance has not been met, the streamline correction equation is solved by defining a matrix, MCOEF, and by solving this matrix using one of several methods. The solution techniques include IAD, Implicit Alternating Direction, or LRELAX, Streamline Block Relaxation. The user has control of the choice of solution method, but IAD has demonstrated the more stable and faster solutions.

After calculating the streamline correction, &n, the streamlines are adjusted (ADJSL) to their new positions and the program logic loops back to SLC to define new curvatures and geometric streamtube areas. This loop is called an inner solution. Depending on the amount of grid refinement, the inner loop

may take from 2 to 20 passes to reach streamline convergence.

As soon above, the iterative sequence is to start with a crude grid and to go through subroutines SLC to ADJSL until the flow balance error is small. The grid is then refined to the next level and the field is reconverged. The refinement/convergence process is continued until the grid refinement criteria is satisfied, or alternately, until computer storage limits are reached. At this point, additional inner loops may be performed until the flow balance error is satisfactory.

Finally, the output quantities are calculated and the results are printed in any of several forms. The output forms are defined in Section 7.

5.3.2 STC Overlay Description

The STC program has been structured for execution on the CDC 6400/6600 machines under the SCOPE 3.1 operating system. The basic OVERLAY features of SCOPE 3.1 have been utilized to reduce the memory requirements to those currently in use at the NASA Langley Research Center. Shown in Figure 5-2 is the overlay structure including all subroutines and the important data table storage areas. As indicated in this figure, the program consists of a main overlay, four (4) primary overlays, and six (6) subordinate secondary overlays. A brief description of the processing in each overlay is given in the following section. In this description, the word "link" is used interchangeably with the word "overlay".

Overlay (0, 0) - Entry STCA

The main overlay (0, 0) contains the main program STCA, as well as general purpose subroutines which are called by subprograms in the subsequent primary and secondary overlays. The main program STCA provides control for execution of the STC program by loading the appropriate overlays in sequence and testing for completion or convergence of the problem solution.

Also included in the main overlay is the data storage area consisting of the general program tables, the field tables, and the streamline table as discussed in Section 5.1. This storage area represents the largest block of working storage in the main overlay. The sizes of these various regions of memory are initialized by the block data subprogram USECDG. An increase in the number of available field points, stations or streamlines may be effected simply by recompilation of this block data subprogram and the block data USECDM in overlay (4, 0).

Overlay (1, 0) - Entry STCN

Overlay (1, 0) is the primary overlay for the program input and initial construction of the data tables and the unrefined calculation net. Program STCN serves as a driver routine to call in subordinate secondary overlays. These links in turn read the input and build the initial tables and calculation net. Subroutines used concurrently by secondary links also reside in overlay (1, 0).

Overlay (1, 1) - Entry STCNR

Overlay (1, 1) consists of the subroutines to read the card and/or tape input and perform preliminary processing. General input data are read in REDINP and boundary and channel data are read in RBD and RCD respectively. The channel data input table is also constructed in RCD. In the case of the boundary input, if angles are not specified with the coordinates, the SMOTH routines are called to calculate angles by fitting a beam through the specified coordinates. Also, the NACA Series 1 Cowl coordinates are stored internally and may be used to generate an "analytic" contour for a specified boundary segment. The input quantities to select these options are discussed in Section 7.1, and on the input sheets (Section 12.2).

Overlay (2, 1) - Entry STCN2

The principal function of overlay (2, 1) is to build the boundary table and the leading edge/trailing edge table using the coordinate and angle data from the preceding link. This procedure is accomplished in subroutine BLDTAB. If specified by input, this overlay is recalled to initialize the matrix for the solution on the far field boundary (FRFDNZ).

Overlay (1, 3) - Entry STCN3

The bulk of initial table construction is performed in subroutine BLDTBS. Specifically, the orthogonal channel table, the streamline table, the station table, the flow adjustment table, and the wake displacement thickness table are built in this routine. Subroutine BCONV is called to build the convected properties table as an intermediate task. In the process of table construction, the values of Z, R, S₂, and V for the unrefined grid are placed in the field tables.

Overlay (2, 0) - Entry STCB

Overlay (2, 0) is the primary link for calculation of the coefficient B and the RHS of the streamline correction equation using the "flow balance" relations. The subroutine FLOBAL and TTPT are included in this link, since they are used by the output routines to calculate final velocities in the field prior to printing.

Overlay (2, 1) - Entry STCS

Overlay (2, 1) contains the subroutines STALOO and BRHS to loop through the stations and calculate the coefficients B and RHS for the matrix solution of the streamline adjustment equation. Included also is the subroutine ADJWF which adjusts nozzle flow rates prior to entering the flow balance calculation.

Overlay (2, 2) - Entry STCW1

Overlay (2, 3) - Entry STCW2

These two overlays are loaded at the end of the problem solution to produce the printed output and generate a restart tape if requested. Subroutine WRIA prints the parameters defined by input, program storage utilization information, solution convergence level as well as generating the restart tape. Subroutines WRIQUT and WRIBDY print out the solution at the field points and the boundaries respectively.

Overlay (3, 0) - Entry STCXX

Overlay (3, 0) is loaded prior to the execution of the flow balance. The prime functions of this link are to adjust the streamline positions (ADJSL), refine the grid (REFINE), calculate streamline curvatures (SLC), orthogonalize the grid (PTMOVE), and calculate velocities on the far field boundary (FARFLD). The far field routines are only called if these options are in effect. REFINE will not be called if grid refinement limits have been reached, the flow balance error is too large, or the maximum field point limit has been met.

Overlay (4, 0) - Entry STCM

Overlay (4, 0) contains the subroutines MC9EF and IAD to set up and solve the matrix equations for the streamline adjustment.

THE STREAMTUBE CURVATURE PROGRAM

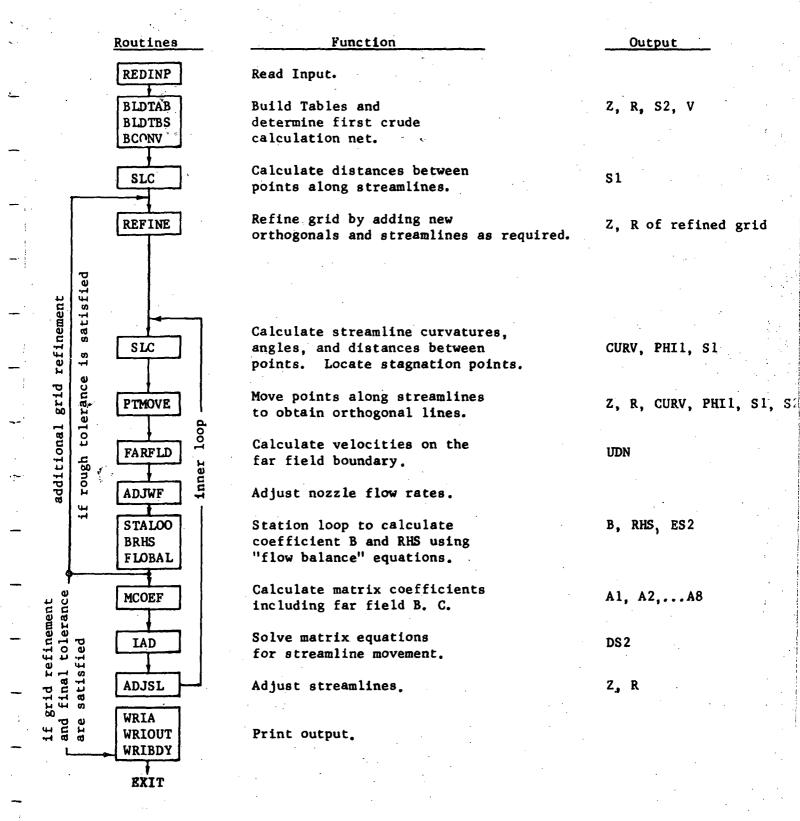


Fig. 5-1 Program Flow Chart

CBOWXY	4,0 STCM CA2-CA8 MCOEF IAD FFINC ATDMRS CUFITR CUFIT CUBE CUBE S55PTI
CIDEX CIDEXR IXORIG SLTAB CHDATA SLTAB2 CBEAM2 CBEAM2 CREAN2 CTINNER CINNER CINNER CIADIN CTABPR CLINES	3,0 STCXX ADDFPT ADDFPT ADDFPT ADDFPT ADFPT BAPTE BFAC BFAC BFAC BFAC BFAC BFAC BFAC BFAC
CPRINT CFRFIN CFRFID ALLCOM CTHICK CCURY CRHS CM CB CPH 11 CS 1 CS 2 CZ CR CX	2,3 STCW2 WRIBDY
	2,0 STCW1 WRIZ
	STCB ERROR1 LFIT2D TTPT ADJWF2 FLOBAL SHKPT SHKPT STCX ADJWF BRHS NEWRAP STALOO
LSUM MBEGIN QIREM TABPRT TAN FHEAD ERRORR LFITI STANQ STAXI BOWXY OLSHK	1,3 STCN3 BCONV BLDTBS BWAKE FTLL JOFCHN OBI RBCONV
	1,0 1,2 STCN2 BLDTAB BPSORT FRINIT FREDNZ MATINV ISBQT TTPT
STCA MOVE SETM FMPYC GETIX IMSPRT ATAN3 BARC BEAM BEND BFI LAC LAC2 LAC2 LAC2	STCN ERRORI ISORT REDBLK LRMDS1 DBSRT1 LOOP LOOP REDINP RBD CSMOOD RCD SMOTH SMOTH SMOINP RELOXY SERS1 XTRUNC SMOXEQ ATDMR BAD BRACES SMOO

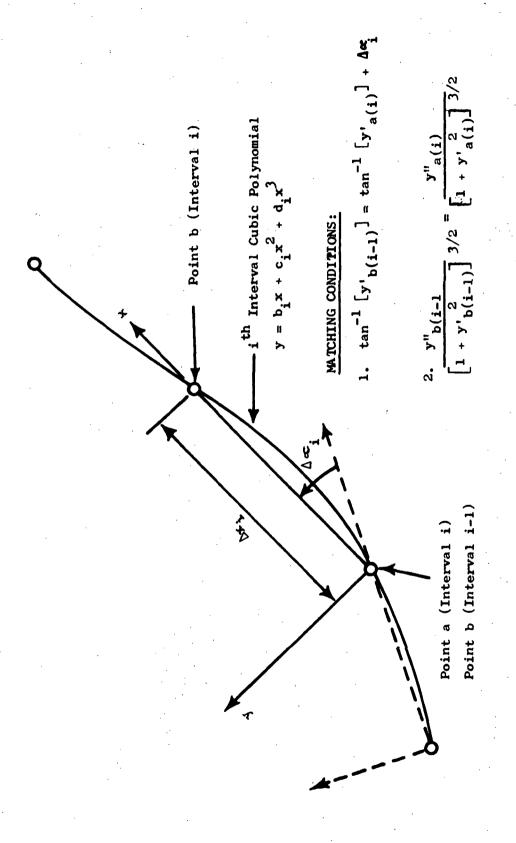
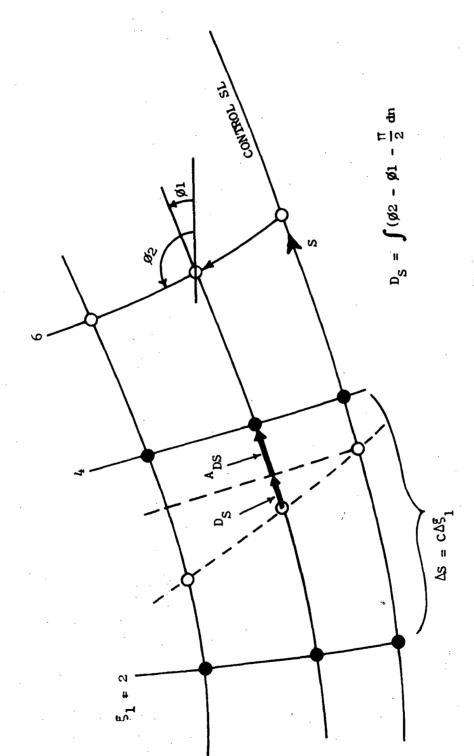


Fig. 5-3 Curve Fit Algorithm

Points Repositioned in the Streamline Curvature Calculation Routine

Fig. 5-4 Stagnation Point Iteration



C = Constant For Each Region

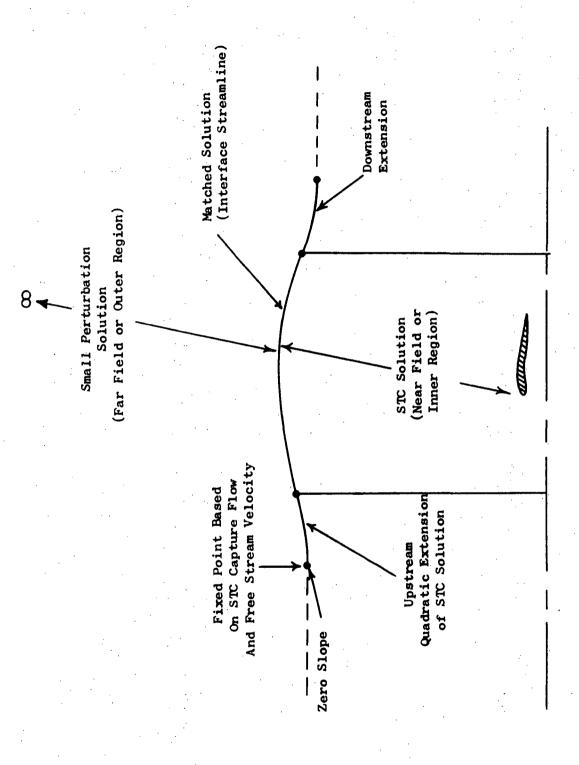


Fig. 5-6 Illustration of Far Field and Near Field Solution Domain

6.0 PROGRAM NOMENCLATURE

Communication between the subroutines in each overlay is accomplished by the use of labeled common. with few exceptions, the majority of labeled common storage areas are located in the main overlay. The size and data in these blocks are initialized by the block data subprograms USECDG and STCBLK. The principal labeled common blocks are given alphabetically in the following section. Labeled commons used by general purpose utility subroutines are not included in the tabulation. In most cases, the use of these commons is given in the listing of the pertinent subroutine (Volume III).

Within each block, variables are listed according to the position occupied in the block. In some cases, the variable name may differ between routines and a typical name is given. Also, several areas are used primarily as erasable temporary storage and are denoted as such in the description of the labeled common. Inspection of the source listing should indicate the particular use of these areas by a given subroutine. The pertinent dimension and type information are included with the variable name ($R \equiv Real$, $I \equiv Integer$, $L \equiv Logical$). Variables normally containing BCD data are typed as $H \equiv Hollerith$, even though they may have real or integer names.

Block	Typical Variable	·	,		
Name	Names	Type	Dimensions	Description	
ADAM01				Identification Block	
	NAME	н	9	User name	
	ADDRES	æ	9	User address	
	MNQ		9		
	IDENT	Ħ	9	Problem identification	
ALLCOM				Contains reference Mach number, pressures, gas properties	temperature
	MACHA	` ≃	-	Reference Mach number (free stream)	·
	PSA	≃	H	Reference static pressure	
	TSA	æ	-	Reference static temperature	
	PTA	~	1	Reference total pressure	
	TTA	~	1	Reference total temperature	
	AXIA	1	1	Problem type; (T) axisymmetric, (F) plane	-
	RGA	œ	Ħ	Gas constant	
	GAMA	~	1	Isentropic exponent	
	DUM	i	10		
	TTE	æ	.	Body closure tolerance	
	CHOTST	ப	П	Input indicator to perform (T) or omit (F) when adjusting flow	choke test
BCOMMIN				Program control common	
	PROGM	æ	r-1	Program name STC	
	TAPIN		.	Input tape indicator (T)	• .
	TAPOT	,	-4	Output tape indicator (T)	
	MNC	1	9		
	FILIN	'n	H	Internal equivalents of TAPIN, TAPOT	
	FILOT	L			

Description	Curvature Influence Coefficient (MCOEF)	Curvature Influence Coefficient (MCOEF)	Influence Coefficient related to flow difference between steamlines (MCOEF)	Curvature Influence Coefficient (MCOEF)	Curvature Influence Coefficient (MCOEF)	Influence Coefficient related to flow difference between streamlines (MCOEF)	Influence Coefficient related to flow difference between streamlines (MCOEF)	Coefficient B of Matrix Equation at field points	General Common for junk words	BITS = 1.E + 15	BLANK = 1H	Angle and curvature of adjusted boundary point (PTMOVE)	Angle at adjusted boundary point	Curvature at adjusted boundary point
Dimension	300	300	300	300	300	300	300	300		1	H		-	
Type	×	æ	æ	æ	æ	~	8	24		×	н		œ	~
Typical Variable Names	A2	А3	A4	A5	A6	A7	A8	ø		BITS	BLANK		ANGD	CURVD
Block Name	CA2	CA3	CA4	CA5	CA6	CA7	CA8	eg CB	CBITS			CBDYPT		

Description	Control common for insertion of orthogonals and streamlines during grid refinement	New streamline extension	New orthogonal lines across a subsonic region	New orthogonal lines across a supersonic or mixed region	New orthogonal lines which cross a sonic line	New orthogonal lines which cross a supersonic to subsonic compression line	Curvature at field points	Streamline adjustment at field points	Flow Balance Communication Block	Current station index	Lower boundary field point index	Upper boundary field point index	Flow rate if different from value in the streamline table	Desired pressure on lower boundary (if known), otherwise $=\ 0$	Desired pressure on upper boundary (if known), otherwise = 0
Dimensions	٠.		H	.	н		300	300		.	-	H	H	H	
		٠.	•												
Type		æ	×	æ	æ	, # .	æ	,		Н	I	Н	æ	x	~
Typical Variable Names		CRXSL	CRXOL	CRXSS	CRXE	CRXC	CURV	DS2		Ļ	MA	· BE	WF	PLB	PUB
Block Name	CCRX		• .				CCURV	CDS2	CFB	*					:

	Dimensions Description	1 = T for calculation of maximum (choked) flow	1 = T for subsonic branch, * F for supersonic branch	l Number of streamlines at given station (L)	1 Calculated lower boundary pressure	l Calculated upper boundary pressure	1 BCD word SCHOKE	l Total passage area for all streamtubes	l Calculated velocity on upper boundary	1 Requested flow (from SLTAB)	l Calculated flow	8 Flow balance iteration history vector	8 Pressure balance iteration history vector	l Indicator used for detecting a change in the channe	
	Type	ы	1	H	~	&	~	æ	æ	2	&	æ	æ	H	
Typical Variable	Names	CHOKE	SUBSON	NK	PLBC	PUBC	XCHOKE	TAREA	VMBC	WRQST	WCALC	ΛÒ	QVP	JSUM	
Block	Name											٠.			

Block N <i>a</i> me	Iypical Variable Names	Туре	Dimension	Description
CFRFIN		•		Far field initialization
	ATINE	æ	-	Free stream stagnation speed of sound
	MINF	ĸ	7	Free stream Mach number
	RFFREF	æ	.	Reference (R,Y) location of far field
	UNIF	~		Free stream velocity
	ZDN1	_ 	-	Upstream limit of far field
	ZDN25	24	~	Downstream limit of far fleld
CFRFLD				Far field solution - communication
· · _	NFF	H	.	No. of STC points on far field boundary
	MAXFF	Ħ	1	Maximum No. of STC points on far field boundary
	ZFF	×	79	Streamwise coordinates of STC points on far field boundary
	RFF	æ	79	Transverse coordinates of STC points on far field boundary
	ZDN	æ	25	Streamwise coordinates for far field solution
	DRDN	æ	25	Interpolated far field flow angles at ZDN

al ble Type Dimension Description	R 25 Calculated velocity on far field boundary @ ZDN	R 25,25 Zij matriz for far field solution		R 1 CG = 32.174 ft - $1bm/1b_f$ sec ²	CHDATA contains the STC tables described in Section 5.	Control Common for matrix solution	S R l Base acceleration factor, $\rho_{ m B}$	P R lalf amplitude of the acceleration factor, $^0\mathrm{A}$	= 0 for IAD I Sweep parameter, = 1 for orthogonal block relaxation =-1 for streamline block relaxation	Communication common used by GETIX and SAVIX to store and retrieve data from JMS array	I Current field point index	I Streamline number	I Field index of upstream point	
Type	œ	~		24			~	2	H		ы	₩,	ı	
Typical Variable Names	NOD	ZIJ		ဗ္ဗ			RHOBAS	RHOAMP	ІАДМ		×	, D	MU	
Block Name			GGRAV		CHDATA	CIADIN				CIDEX			:	

CIDEXR 58	ISTAG M DUM M3 DUM M5 DUM M2 M2	н нініні		Point type indicator 1 - Stagnation point 2 - Primary orthogonal 3 - Partial orthogonal termination 3 - Partial orthogonal termination Communication used by GETRLX to retrieve data from the JMS array Current field index Field index of point upstream of M (ISTAG = 3 points skipped) Field index of point downstream of M (ISTAG = 3 points skipped) Field index of point upstream of M3 (ISTAG = 3 points skipped)
	M6 DUM	H I	1 4	Field index of point downstream of M5 (ISTAG = 3 points skipped)

Description

Dimension

Type

Typical Variable Names

> Block Name

Block Name	Variable Names	Type	Dimension	Description
CINNED				in the second section is a second sec
CTIMER				COULTO COMMON TOL THREE TREESTRONS
	INRCTR	H	1	Counter for inner iterations (set to 0 when grid is refined)
	Mnd	ı	7	
	NIMNER	H	16	Number of inner iterations at a given refinement level. Inner iterations continue until INRCTR = NINNER(MAJCTR) or ES2MX < ES2LIM
	CNVF	~	16	Fractional percentage of total point movement to be used at a given refinement level (0. < CNVF(MAJCTR) < 1.)
CISBOT				Common for special boundary types
	FARFLD	щ	2	Boundary names specified as far field boundaries
	FREE	н	2	Boundary names specified as free streamlines
	PRES	н	7	Boundary names where pressure is specified
	MOG	· 1	7	
	NZP	I	7	No. of entries in ZP, PPS tables
	ZP	~	10	Table of $\mathbf{Z}(\mathbf{X})$ values for interpolation of pressure on boundaries where pressure is specified
	PPS	~	(10)	Table of pressures PPS (ZP)
	MUG	i	7	

Typical

Block Name	Variable Names	Type	Dimension	Description
·	ADUM	∝		Additional storage for special boundary information ADUM(1) = fractional extension of far field in streamwise direction; ADUM(2-6) not used
E	JMS	H	~	Table of packed words containing pointers to field tables
CMAXIT		٠		Control common for grid refinement levels
	MAXIT	н	1	Maximum number of grid refinement
	MAJCTR		. 1	Current refinement level
	GREFIN	ы	H	Indicator set by subroutine REFINE to indicate that a grid refinement has occurred (T)
	DUM	t	• - - :	
CPH11	PHI 1	~	300	Flow angle at field points (radians)
CPI			·	Table of constants
	PI	~	1	$PI = \pi = 3.14159265$
	TWOPI	∝	. T	2 * PI
	P102	æ	1	PI/2
	PIQ4	e4	ч	PI/4
	TODEG	æ		TODEG = 57.2957795 deg/radian

Block Name	Typical Variable Names	Type	Dimension	Description
	TORAD	K	r	TORAD = .0174532925 radians/deg
CPRINT	-		,	Diagnostic print and control array
	PRTES2	×	Н	
	PRTB	æ	H	
	PRTA	æ	. ,	Variables in this common will be described
	PREFIN	æ	1	Section VII A Program Input
	PREFIN2	æ	7	
	SSONIC	Æ	7	
	PDUM	æ	20	
CPRPRN				Print control for field (WRIOUT)
	PRPRN	H	1	PRPRN = -1 Field printout at each station delete
: 8	æ	~	300	Transverse coordinate (R,Y) at field points
CREFIN				Grid refinement control
	MOD	1	2	

Block Name	Variable Names	e Type	Dimension	Description
	VMG1	æ	-	Maximum Mach number increment between grid points in streamwise direction
	VMG2	6 4	.	Maximum Mach number increment between grid points in normal direction
	NGR	H		No. of entries in GR, SGR tables
	NGZ	н		No. of entries in GZ, SGZ tables
	¥	~	10	Grid radius
	SGR	æ	10	Grid size in radial direction
	23	æ	10	Streamwise grid distance
	ZOS	æ	10	Grid size in axial direction
CRHS	RHS	æ	300	Right hand side of matrix equation at field points
CS1	S1	æ	300	Cumulative distance along streamline at field points
CS2	S2	æ	300	Cumulative distance along orthogonal line at field poins
CSS				Supersonic Calculation Control
	SSFML	H		Supersonic curvature formula number
	SSEF	ı	. 	Supersonic entering flow, T or F

Typical

	Description	Entering flow angle for $SSEF = T$ (Degrees)	flow (T or F)	supersonic beam downstream end condition	ream end condition	Supersonic flow below and aft of a leading edge point (T				sweep control	Tolerance on matrix solution relative to maximum streamlin movement	Sweep limit for relaxation solution of matrix equation	size	ovement
	e e e e e e e e e e e e e e e e e e e	Entering flow angle	Supersonic discharge flow (T or F)	supersonic beam down	Supersonic beam upstream end condition	Supersonic flow belo				Solution tolerance, sweep control	Tolerance on matrix movement	Sweep limit for rela	Characteristic grid size	Maximum streamline movement
	Dimension	H		-	-	H		÷			-	Ė	г	1
	Type	%	LJ.	24	6 4	,			;		~	H	24	æ
lypical Variable	Names	SSEANG	SSDF	SSFEND	SSFND1	SSDLE	A4FACT	BRLX	CURRLX		TOLRL	MAXSWP	CLEN	DS 2MX
Block	Name	÷			•		•			CTOLRL				

	Description	Relative tolerance on point movement predicted by flow balance	Number of sweeps required for convergence of matrix solution	Damping factor on point movement along streamlines	Maximum point movement along streamlines	Maximum calculated point movement along streamlines before damping	RMS value of the calculated point movements along streamlines	Maximum streamline position error as determined by flow balance	RMS value of the calculated point movements along streamlines after grid refinement	Minimum grid size as determined by REFINE	Inner iteration tolerance on streamline movement	Velocity at field points	Streamwise coordinate at field points		Temporary storage areas	
	Dimension	~	-	T	4	.	1	-		7	П	300	300	800	1536	
	Type	~	H	æ	æ	æ	Æ	2 4	æ	æ	, ~	æ	⊯			
Typical Variable	Names	TOLES2	NSWP	DS1	DS1MXA	DSIMKB	DS 1RMS	ES 2MAX	INS I RWO	SGIMIN	TOLINR	MA.	2			
Block	Name											CVM	23	ERASE	ERASE2	

	:ion		out table (CHDATA)	channel input table (CHDAIA)	able (CHDATA)	able (CHDATA)	convected property table (CHDATA)	property table (CHDATA)	(CHDATA)	(CHDATA)	adjustment table (CHDATA)	ment table (CHDATA)	le (CHDATA)	station table (CHDATA)	(CHDATA)	(CHDATA)				
	Description	Table of Index Limits	Lower index limit for channel input table (CHDATA)	Upper index limit for channel inp	Lower index limit for boundary table	Upper index limit for boundary table (CHDATA)	Lower index limit for convected p	Upper index limit for convected p	Lower index limit for wake table (CHDATA)	Upper index limit for wake table	Lower index limit for flow adjust	Upper index limit for flow adjustment table (CHDATA)	Lower index limit for station table (CHDATA)	Upper index limit for station tab	Lower index limit for shock table (CHDATA)	Upper index limit for shock table	Dummy - future growth	Initial point in field tables	Number of field points	Nombon of otheron lines
	Dimension	Ta	1 LO	Up Up	1 Lo	J UP	1 Lo	1 Up	1 Lo	1 Up	1 Lo	1 Up	. 1 Lo	1 Up	1 Lo	1 Up	bu Du	1 In	I Nu	;
	Type		H	ı	H		н	H	H	ы	: H	н	H	н		H	н	⊢ 4	H	
Typical	Variable		OHT	LHE	LBDO	LBDE	LTO	LTE	LWO	LWE	LFO	LFE	01	LESTA	TS0	LSE	LDUM	¥Q.	MN	111
# 700	Name	IXORIG													. '					

я 7001	Typical				
Name	Names	Type	Dime	Dimension	Description
	MAXNJ	H		-	Maximum number of streamlines
	MAXOL	ı		-	Maximum number of orthogonals
	MAXNM	. I			Maximum number of field points
	MAXLE	H	÷	-	Maximum number of leading edge/trailing edge points
	LEO	H	• -	1	Lower index limit for leading edge/trailing edge table
	LEE	I		, न	Upper index limit for leading edge/trailing edge table
	LRO	H			Lower index limit for orthogonal/channel table
	LRE	H		-	Upper index limit for orthogonal/channel table
	LRD	H		1	No. of channels +1
LETEPT					Table of leading edge/trailing edge points
	XE	¤	ż	-	Streamwise coordinate
	YE	#		т	Transverse coordinate
	ANGE	æ	÷	-	Angle
	NLE	H		· - 1	No. of leading edge coincident points
	NTE	I		1	No. of trailing edge coincident points
	CHI	Ė		· ·	Channel name below point
	СНО	Ħ	* *		Channel name above point
	BDL	H		-	Lower boundary name associated with point
	BDU	Ħ		-	Upper boundary name associated with point
	NUSED	. 1	4	167	Additional tables having the preceding format

Block Name	Typical Variable Names	Type	Dimension	Description
MOMFLX				Storage for momentum flux calculation (channel) (WRIOUT)
	STXU	ĸ	128	Entering channel axial momentum flux
	STXD	K	128	Leaving channel axial momentum flux
	STYU	~	128	Entering channel normal momentum flux
	STYD	æ	128	Leaving channel normal momentum flux
SELECT				Communication common between main overlay and primary overlays
	LENTRY	н	T	Select key for different entries
SLTAB	:			Streamline table
	3	~	128	Flow rate
	X2	æ	128	£2 coordinate
	SLCHN	н	128	Channel name
SLTAB2				
	PTR	e	128	Total pressure ratio

7.0 STC PROGRAM INPUT/OUTPUT

The following sections are concerned with the input to the STC program, special user instructions, and the output produced by the STC program. The standard system files INPUT and OUTPUT (TAPE6 = OUTPUT) are used for card input and printed output respectively. Additional data files designated as TAPE1 (input) and TAPE2 (output) may be used by the programs. In general, these files will reside on magnetic tape.

7.1 Program Input

Input sheets for the STC program are given in Section 12.0, along with special notes pertinent to the use of these sheets. Optional program input, not normally required, will be described in this section. Input data may be in the form of punched cards or a magnetic tape file (output file from a previous execution of the STC program). Data read from a magnetic tape file may be selectively over-ridden or augmented by input cards. Four (4) distinct card input sets are read by the program and are:

- 1.) Input sheet 0 Identification information
- 2.) Input sheet 1 Overall input data
- 3.) Input sheet 2 Boundary coordinates
- 4.) Input sheet 3 Channel flow properties

The first input set, consisting of identification information, is read once in a given run using fixed field format (6AlO). The remaining input sets consist of a header card followed by a NAMELIST input list \$A. Standard FORTRAN IV NAMELIST (Volume III) is used to read these latter lists.

Successive cases may be run using only input sets 2.) through 4.). In all cases, the channel flow properties (input set 4) may or may not be present.

The input parameters for each set are given in the following section.

Included in these descriptions are the input items appearing on the input sheets as well as controls for special program options and the modification of preset tolerances.

7.1.1 Identification Information Input Sheet 0

The first three (3) cards of the input deck consist of the name and address of the user and the problem identification.

Card No.	Cols.	
1	2-61	User name (1-60 alphanumeric characters)
2	2-61	User address or location (1-60 alphanumeric characters)
3	2-61	Problem identification (1-60 alphanumeric
		characters)

Blank cards may be substituted for input quantities not required.

7.1.2 Overall Input Data Input Sheet 1

The first card of this input set is a header card consisting of a 1 in column 2, the word STC starting in column 4, and a T or an F in both columns 14 and 24.

Card Column		Description
2 .		1 - Denotes overall data input
4-6	•	STC - Denotes program name
14		Input tape? (T or F)
24		Output tape? (T or F)

The header card is followed by the NAMELIST \$A and the associated overall input data. The NAMELIST input is terminated with a \$ in column 2.

Input	Parameters	for	General	Usage

Parameter	Description		Preset Value
масно	Mach Number	•	
TSO	Ambient Temperature		1.0
PSO	Ambient Pressure		1.0
RG	Gas Constant		1.0
GAM	Ratio of Specific Heats		1.4
RHL	Highlight Radius		1.0

Parameter	Description	Preset Value
RM	Maximum Body Radius	1.0
TTE	Body Closure Tolerance	0.
AXI	Problem Type T = Axisymmetric F = Plannar	T
GR(1)	Table of Transverse Coordinates for Grid Refinement Tables (up to 10 values)	
SGR(1)	Table of Transverse Grid Refinement Criteria (up to 10 values)	1.
NGR	Number of Entries in the GR, SGR tables	1
GZ(1)	Table of Axial Coordinate for grid Refinement Tables (up to 10 values)	
SGZ(1)	Table of Axial Grid Refinement Criteria (up to 10 values)	
NGZ	Number of entries in the GZ, SGZ tables.	0
VMG1	Maximum Mach Number Increment Between Grid Points in Streamwise Direction	0.1
VMG2	Maximum Mach Number Increment Between Grid Points in Normal Direction	0.1
MAXIT	Maximum Number of Grid Refinements	* *

Optional Input

The following input quantities are considered optional input in that they are not normally required for execution of the STC program. These items consist, in general, of input controls for special program options and input data to modify preset or initialized constants and parameters.

Stagnation Properties, Optional

Parameter	Description	Preset Value
PTO	Stagnation pressure	1.0
TTO	Stagnation temperature	1.0

The total pressure and total temperature may be input by specifying PTO and TTO normalized by the free stream static temperature and pressure. Alternately, the total conditions are calculated from the Mach number, MACHO, and the ambient pressure and temperature, PSO and TSO.

Special Controls for Supersonic Flow, Optional

Parameter	Description	Preset Value
SSFML	Formula number for calculation of supersonic curvatures	1
	= 1 for 3 point parabola	
	= 2 for 4 point piecewise cubic (i.e. bear	n)
	= -1 for 3 point parabolas for both subsonic and supersonic points	
SSEF	Supersonic entering flow along the upstream boundaries? T or F	F
SSEANG	Entering flow angle for SSEF = T (degrees)	0.
SSDF	Supersonic flow downstream of a choked station? T or F	F
SSFEND	Supersonic beam downstream end condition (SSFML = 2)	.75
•	0. = Parabola 1. = Cubic	ı
SSFND1	Supersonic beam upstream end condition (SSFML = 2)	.75
	0. = Parabola 1. = Cubic	
BRLX	B - Relaxation factor	1.
TSIC	Number of points to be used for transonic interpolation of curvature	2.
		e .
Boundary Co	nditions for Streamline End Points, Optional	
<u>Parameter</u>	Description	Preset Value
NBC	NBC(1) ≡ Upstream, NBC(2) ≡ Downstream;	2
	NBC = 0 Angle specified	
	NBC = 1 Curvature specified NBC = 2 Ratio of the rate of	
	curvature at the end point	
*	to the value at the next	
	end point is specified	
AFC	AFC(1) = Upstream, AFC(2) = Downstream; Angle, curvature or ratio of rate of change in curvatures	0.

Matrix Solution Controls, Optional

Parameter	Description	Preset Value
IADM	Sweep parameter	0
	<pre>0 = IAD 1 = Orthogonal block relaxation -1 = Streamline block relaxation</pre>	•
RHOBAS	Base acceleration factor parameter, ρ _R	0,5
RHOAMP	Half amplitude of the acceleration factor, ρ_{A} Note:	0.5
	$\rho = \rho_{B} + 2\rho_{A} \sin^{2} \frac{n\pi}{2\sqrt{NM}}$	
MAXSWP	Maximum number of sweeps	200
TOLRL	Relative tolerance for matrix solution;	.001
	\DS2 \leq TOLRL*DS2 max.	
Flow Balan	ce Solution Controls, Optional	-
Parameter	Description	Preset Value
TOLES 2	Relative tolerance on maximum point movement predicted by the flow balance	
TOLINR	Inner iteration tolerance on streamline movement	
NINNER(1)	Number of inner iterations (without grid refinement). Specify up to MAXIT values	16*10
CNVF(1)	Fractional percentage of total point movement to be used at a given refinement level. Specify up to MAXIT values.	10*1.0
NODENS	Grid refinement level through which incompressible flow properties $(\gamma=\infty)$ will be assumed.	0

Grid Refinement Parameters, Optional

The following input items may be used to control the length of orthogonal lines and streamlines as the grid is refined. The use of these parameters is discussed in the following section on "special user instructions"

Parameter	Description	Preset Value
CRXSL	Used for extending new streamlines	.375
CRXOL	Used for extending new orthogonal lines across a subsonic region	. 375
CRXSS	Used for extending new orthogonal lines across a supersonic or mixed region	.125
CRXE	Used for extending new orthogonal lines which cross an expanding flow sonic line	0
CRXC	Used for extending new orthogonal lines which cross a supersonic to subsonic compression line	0

Optional Print and Control Options

Optional diagnostic print and special logic controls are located in common /CPRINT/. Normally these variables are set to 0.. As indicated in the following section, the print controls will provide output from a number of routines. The setting, pertinent subroutine, and resulting printout are indicated. Several variables control logic flow only.

Parameter	Description
PRTES 2	Subroutine BRHS
	=2 Print B,RHS,DS2,Z,R,PHI,CURV, and ES2 for the two stations with maximum ES2. (DS2 is the value computed during the previous iteration.)
	>2 Print the above information for PDUM(8) $\leq \xi_1 \leq$ PRTES2. (B,RHS and DS2 are the values computed during the previous iteration.)

PRTA

Subroutine IAD

Frint matrix solution for DS2 at end of each sweep. This indicator is turned on internally if NSWP > MAXSWP - √NM - 2

PREFIN

Subroutine REFINE

≠0 Print diagnostic during streamline refinement for PDUM(8) <ξ2≤ PREFIN

PREFN2

Subroutine REFINE

Frint diagnostic during orthogonal line refinement for PDUM(8) <ξ₁ < PREFN2</p>

SSONIC

Subroutine BRHS

=2 Suppress area scaling for ES2 calculation

PDUM(1)

Subroutine SLC

- Print ZB,RB,ANGD,CURVD during iteration for stagnation point location
- =1 Print results of curvature calculation
- =2 Print results of supersonic curvature calculation
- =4 Print curvature results if point is a stagnation point or the termination of a partial orthogonal

PDUM(2)

Subroutine IAD

≠0 Print final matrix solution for DS2

PDUM(3)

Subroutine MCOEF

 $\neq 0$ Print influence coefficients $A_2, \dots A_8$

PDUM(5)

Subroutine MCOEF

- Print influence coefficients, G, relating streamline point movement to the negative of curvature
- =3 Print above information for partial orthogonal points only
- =4,5 Print above information for 1st and 2nd points upstream of leading edge

PDUM(6)

Subroutine ADJWF

#0 Print results of flow adjustment iteration

Parameter	Description
PDUM(7)	Subroutine REFINE
·	≠0 Print velocities, stream-function after refinement
PDUM(8-9)	Subroutine FLOBAL
	Print flow balance related data if PDUM(8) $\leq \xi_1 \leq PDUM(9)$ and PDUM(8)*PDUM(9) $\neq 0$
PDUM(10)	Subroutine BUILDT
	<pre>#0 for printout of tables described in Section 5.1 after they are first constructed</pre>
	=2 for printout of all tables at end of solution
PDUM(11)	Subroutine FARFLD
	<pre>#0 Print coordinates, slope, velocity on the far field boundary</pre>
PDUM(12)	Subroutine MCOFF
	<pre>#0 Use spline influence coefficients even if SSFML = -1</pre>
PDUM(13	Subroutine FARFLD
	#0 Use "linear" interpolation on the far field boundary
	#0 Use "least squares parabolic" interpolation on the far field boundary
PDUM(18)	Subroutine FLOBAL
	#1 for calculation of normal shock total pressure loss for transonic compressions
PDUM(20)	Subroutine FRFDNZ
	≠0 Print matrices used in far field solution
PRPRN	Subroutine WRIOUT
	≠-1 Print field information at each station

7.1.3 Boundary Coordinates

Input Sheet 2

The first card of this input set is a header card containing a 2 in column 2, the word BDY starting in column 4, the boundary name in column 14, and the channel name in column 24.

Card Column	Description	
2	2 - Denotes boundary input	
4	BDY - Denotes input type	
14	Boundary name, 1-6 alphanumeric characters	
24	Channel name, 1-6 alphanumeric characters	

The header card is followed by the NAMELIST \$A and the associated input for the specified boundary. The NAMELIST is terminated with a \$ in column 2.

Descripti	on
Boundary position	
UPPER = T	Upper boundary
UPPER = F	Lower boundary
Geometry indicator	
ZRONLY = T	No surface angle input
ZRONLY = F	Surface angle input
	Boundary position UPPER = T UPPER = F Geometry indicator ZRONLY = T

Two options are available for the input of the boundary geometry. Either the coordinates and the surface angle (measured from the positive x-axis) may be input, or the coordinates alone may be input. In either case the points must be input accurately. The first option (ZRONLY = F) is preferred. With the second option (ZRONLY = T), a beam is fit to the input points to determine the angles and, in the process, the beam fit angles and curvatures are printed. To determine whether a suitably smooth curve has been fitted to the points, the user should examine the curvatures and make sure they are reasonable. In general, the points should not be closely spaced except as required in regions of high curvature. In these regions, the angle change between points should be less than 25 degrees.

The NACA Series 1 cowl coordinates are stored internally, and may be selected by specifying ZRONLY = T and B(1) = 991, 1, followed by the high-light coordinates and the coordinates of the maximum diameter. If the cowl is to be extended beyond the end of the Series 1 contour, the "maximum diameter" coordinate is repeated and then other coordinates are listed.

Boundary coordinates are normally input in tabular form using the B block as specified on input sheet 2. All points must be listed in the streamwise direction for each boundary. Points at sharp corners must be listed twice, once for each angle which exists at the point. Normally, pressure and Mach number distributions will be printed at each orthogonal intersection with the boundary. Orthogonals may be forced to coincide with boundary points by listing the point twice in the input and setting DBLPTS = 0. (see optional boundary input).

The column names in the B arrary are Z (or X), R (or Y), and ANGD.

Parameter	Description
B(1)	Input block for boundary data
	column 1 Z or X coordinate
	column 2 R or Y coordinate
·	column 3 Angle or slope of surface

If desired, the data in the B array may be input in "free form" using the symbolic names associated with the appropriate columns of the B block.

Parameter.	Description
R	Normal (radial) coordinate (axisymmetric)
Y	Normal (vertical) coordinate (Planar)
Z	Axial coordinate (axisymmetric)
X	Axial coordinate (planar)
ANGD	Angle or slope of surface

Boundary data input via the B block will override corresponding data input in the "free form".

Optional Input

Optional input parameters, not shown on input sheet 2, are available to apply linear transformations to the input coordinates. Also, input control may be specified to force orthogonals to be placed at selected boundary input

points. This is accomplished by repeating the coordinates in the boundary input and specifying DBLPTS = 0. Normally, DBLPTS = .01 forces removal of extra orthogonal stations where the angle discontinuity is less than .01 degrees.

Parameter	Description	Preset Value
DBLPTS	Double point tolerance. Double points will be deleted if the angle discontinuity is < DBLPTS (degrees)	0.01
ROTATE	Angular rotation in degrees	
ZPIVOT RPIVOT	Coordinates of the pivot point of rotation	•
SCALE &	Multiplicative constant to be applied to the coordinate data	
ZTRANS	Translation increment in axial direction	
RTRANS	Translation increment in radial/vertical direction	·

7.1.4 Channel Flow Properties

Input Sheet 3

The first card of this input set is a header card containing a 3 in column 2, the word CHN starting in column 4, and the channel name starting in column 14.

Card Column	Description
3	3 - Denotes channel input
4	CHN - Denotes input type
14	Channel name, 1-6 alphanumeric characters

Channel flow properties are specified in the following NAMELIST A, which is terminated with a \$.

Parameter	Description	Preset Value
GAM	Ratio of specific heats	1.4
RG	Gas constant	1.0
TTO	Total temperature normalized by freee stream static temperature	
PTO	Total pressure normalized by free stream static pressure	
MACHO	Mach number	•
TSO	Static temperature normalized by free stream static temperature	1.0
PSO	Static pressure normalized by free stream static pressure	1.0

Specify either TTO and PTO (if known) or MACHO, TSO, and PSO if the Mach number is known. When these options are not used, the second option is employed with the free stream values of PTO and TTO computed from the MACHO supplied in the overall input data (sheet-1).

Parameter	Description	Preset Value
AO	Nondimensional flow area normalized by the product of π and the square of the highlight dimension. For plane cases input ΔY _O / ΔY _{HL} . For inlets ΔY _O mass flow ratio.	

The flow is computed using the total properties as determined from the supplied Mach number, MACHO, and the flow area AO. If input data are not supplied for a given channel, the reference properties on input sheet-1 will be employed with the area calculated at the entrance station.

Individual sets of boundary and channel data need not be input in any particular order. For example, boundary input for the upper and lower surfaces bounding a given channel (input sheet 2) may be followed by the input for the pertinent channel (input sheet 3). While arbitrary placement of these input sets may be used, it is well to develop some standardized conventions for the sequential input of boundaries and channels. This will be discussed further in the following section on special user instructions.

7.2 Program Output

The output from the STC program may be logically divided into the following six sections:

- 1.) Card input and preliminary printout.
- 2.) Input and calculated boundary coordinates and angles.
- 3.) Solution history
- 4.) General input and output data
- 5.) Flow field data along orthogonal lines
- 6.) Calculated flow data along field boundaries and final channel momentum balances.

The above sections appear sequentially in the output except when PRPRN = -1. In this case, the print of the flow field data along orthogonal lines is eliminated and the calculated boundary information follows the general input/output section.

7.2.1 Card Input and Preliminary Printout

The initial section of output consists of a card image print of the problem input and a designation of the tape input/output file selections; viz, TAPIN = $\frac{T}{F}$ and TAPOT = $\frac{T}{F}$. Upon completion of the card image print, the file TAPE5 is rewound to its original position.

7.2.2 Input & Calculated Boundary Coordinates & Angles

Boundary coordinates are processed and printed as they are read. The columnar output displayed for each boundary consists of the input coordinates (X,Z), (Y,R) and the input or calculated body slope (ANGD) in degrees. Preceding these items is a bold heading specifying BOUNDARY COORDINATES, the boundary name (BDY = name), the adjacent channel (CHN = name), and whether the surface is an upper (UPPER = T) or a lower (UPPER = F) boundary. When the ZRONLY = T option is in effect, intermediate printout will be produced defining the results of the beam curve fit to the input coordinates. Since no smoothing is applied to these coordinates, the only meaningful output is

the (X,Z) (Y,R) and the calculated angles (ANGD). Break points in boundaries (double points) enable the curve fit of a boundary in segments. The consolidated output, consisting of the collated boundary data for all segments, follows the above intermediate printout. The NACA Series 1 cow1 coordinates (ZRONLY = T) appear as 40 points in a form similar to that described previously.

Normally, the solution history (described in Section 7.2.3) is printed as the next section of output. When far-field boundary conditions are applied, however, a comment is inserted in the output designating the original transverse location and streamwise extent of the far field boundary. Prior to calculation, the upstream and downstream limits of the far field streamline are extended to insure that the velocities are well behaved at the streamwise ends of the STC integration region. The coordinates of the resulting far field boundary are printed below the above comment.

7.2.3 Solution History

The solution history output provides a convenient summary of the problem history as the solution proceeds through major grid refinements and inner iterative improvements of the flow balance. Included in this section are the parameters defining the grid refinement, the inner iterations, the grid othogonalization, the flow balance errors, and the matrix solution. The pertinent variables in their literal order of appearance in the solution history list are:

<u>Variable</u>	Description
NREFIN	Grid refinement level
GRID PTS	Number of field points
INRCTR	Inner (flow balance) iteration level
CNVF	Convergence factor on streamline movement
RMS-DS1	Root mean square point movement along streamline before damping
MAX-DS1	Maximum point movement along streamline before damping
MAX-DS1	Maximum point movement along streamline after damping

<u>Variable</u>	Description
LIM-ES2	Limiting streamline ES2 for satisfactory solution of the flow balance
MAX-ES2	Maximum ES2 predicted by flow balance
MAX-DS2	Maximum streamline correction predicted by the matrix solution for DS2. = 0. when INRCTR = 0
NSWEEPS	Number of iterative sweeps for solution of the matrix equations. = 0 when INRCTR = 0

7.2.4 General Input and Output Data

The output in this section consists of general input and a summary of selected output parameters. All of these items have been defined previously in Sections 7.1 and 6.0, hence only the general subdivisions of this printout will be listed.

Congral Innut	Section 7.1
General Input	Section 7.1
Streamline End Conditions	Section 6.0
Supersonic Curvature Parameters	Section 6.0
Subsonic/Supersonic Branch Selection	Section 6.0
Grid Size Criteria	Section 7.1
	Supersonic Curvature Parameters Subsonic/Supersonic Branch Selection

f.) Memory Utilization

The memory usage in terms of field points, STC table storage, and number of streamlines is compared with the maximum available values of these parameters.

g.) Convergence Data Section 7.1

h.) Special Boundary Options

The GE version of STC contains a number of special boundary options in addition to the hard wall and the far field. Only the hard wall and far field have been explicitly implemented in the NASA Langley version of STC, due to limitations on the hollerith input capabilities of CDC NAMELIST input.

i.) Matrix Solution Section 6.0

- j.) Contents of Channel Section 6.0 Input Table
- k.) Channel Flow Rates,
 Pressures and Temperatures

Included in this output are the channel flow rates and the pressures and temperatures in each individual channel. Note that the flow rate in a given channel may be adjusted to satisfy the Kutta condition at a trailing edge. When dimensional properties are input, the columns denoted PT/PSO and TT/TSO have units compatible with the dimensions of the input gas constant RG.

7.2.5 Flow Field Data Along Orthogonal Lines

Flow field data on orthogonal lines are printed when PRPRN \neq -1. The first portion of output on each page consists of the program name (STREAMTUBE CURVATURE PROGRAM) and the problem identification. The STC program uses an auxiliary coordinate system (ξ_1, ξ_2) as a numbering scheme for orthogonal lines and streamlines. The coordinates ξ_1 = XII and ξ_2 = XI2 apply to the orthogonal lines and streamlines respectively. Following the problem identification is a heading with the constant station value ξ_1 = XII along with the channels through which the given orthogonal passes. Primary (initial) orthogonals are flagged with ** after ξ_1 . At the extreme right of this line of output is the flow type; viz., SUB = subsonic, SUP = supersonic, or CHOKE = choked. Pertinent data from the field arrays are printed in column format. Stagnation points do not appear in the flow field output.

Variable	Description
XI2	Streamline numbering coordinate ξ_2
STRM FNCT	Dimensionless stream function; fraction of flow in channel
x, z	Streamwise coordinate
Y, R	Transverse or cross stream coordinate
PHI	Flow angle, deg.

Variable	Descripti	on
CURV	Streamline curvatur	e
PS/PO	Ratio of local stat static pressure	ic pressure to reference
PS/PT	Local static to tot	al pressure ratio
TS/TT	Local static to tot	al temperature ratio
CP	Pressure coefficien	t
	$\frac{P_{s} - P_{\infty}}{\frac{1}{2} \gamma P_{\infty} M_{\infty}^{2}}$	Compressible
	$\frac{P_{s} - P_{\infty}}{P_{\infty}M_{\infty}^{2}}$	Constant density (γ = 0)
	0	MACHA ≤ .1

MACH

Mach number

AREA

Flow area

PTQPTO

Channel total pressure ratio

For primary orthogonals, the axial and normal momentum fluxes are printed following the field data. These items are:

Axial Momentum Flux =
$$\int V \cos \phi \, dw + \int (P-P_s) \cos \phi \, dA$$

Normal Momentum Flux =
$$\int V \sin \phi \, dw + \int (P-P_g) \sin \phi \, dA$$

7.2.6 Calculated Flow Data Along Field Boundaries-Final Channel Momentum Balances

The final section of standard output includes the flow parameters on the upper and lower streamlines bounding each channel. Normally the boundary data follows the field data. In the case of PRPRN = -1, however, the boundary information is printed immediately after the general input/output section.

Three lines of identification information head the boundary data, and consist of the program title (STREAMTUBE CURVATURE PROGRAM), the specific case identification, and a designation as to whether the boundary is an upper or lower portion of the given channel. The streamline coordinate (XI2) is given following the channel name. Boundary flow parameters are printed at orthogonal intersection and consist of the following items:

<u>Variable</u>	Description	· · · · · · · · · · · · · · · · · · ·
XII	Orthogonal (station) numbering	coordinate (ξ ₁)
SlW	Distance along boundary	
XW, ZW	Axial coordinate	
YW, RW	Vertical or radial coordinate	
ANGW	Flow angle or surface slope	
CURVW	Streamline or surface curvatur	:e
PS/PO	Local static to reference pres	ssure ratio
CP	Pressure coefficient	
	$C_{p} = 2(P-P_{s})/\gamma P_{s}M_{o}^{2}$	
	$C_{p} = Rg(P-P_{s})/P_{s}M_{o}^{2}$	$(\gamma = 0, constant density)$
	$c_p = 0$	(M _o < .1
PS/PT	Local static to total pressure	e ratio
MACH	Local Mach number	
PT/PO	Ratio of local total to reference pressure	ence static

The cumulative drag/thrust is printed in the column labeled CDPI. The force is normalized by the free stream dynamic pressure (q) and the maximum area based on RM and is given by:

$$CDPI = \frac{(P-P_{ref}) dA}{q A_{max}}$$

The adjacent column (A-AMAX)/AMAX is projected area normalized by the maximum area. Following the column printout is the ratio of boundary total temperature to ambient total temperature. When the boundary is the approach stagnation streamline, the inlet additive drag is printed below the total temperature ratio. This force is also normalized by q and AMAX and is printed for both the upper and lower stagnation streamline.

Momentum Balance

The STC program evaluates the thrust/drag on each boundary surface bounding a given channel and then verifies these forces by performing an "overall" momentum balance for each of the fluid streams. The integral momentum balance output follows the boundary output for a given channel. This information consists of the entering axial momentum, the integrated pressure forces on the boundaries, and the leaving axial momentum. The discrepancy between the leaving momentum and the sum of the inlet momentum and the pressure—area forces represents the net error in the calculation. This error may be attributed to inaccuracies in the computed pressure distributions or, perhaps, to insufficient refinement of the calculation grid for adequate resolution.

8.0 PROGRAM MESSAGES AND ERROR CODES

8.1 Parameters Describing Solution Status

The solution history output, described briefly in Section 7.2.3, contains a summary of how the solution is proceeding. By reviewing this solution status, the level of grid refinement and the degree of solution convergence can be readily determined. In brief, the solution history is like a "hospital patient's history" in that the general health of the calculation procedure is charted here. (See Section 11 - Sample Cases).

The grid refinement level is specified by the number of times the grid has been refined (NREFIN) and by the number of GRID PTS in the flow field. The number of grid refinements is controlled by MAXIT. The number of points in the flow field is dependent on the grid refinement criteria specified and MAXIT.

The number of inner iterations at any grid refinement level is shown by INRCTR. These are controlled by built-in tolerances on the flow balance, but the internal program control can be overridden by inputting NINNER(m) where m refers to the level of grid refinement.

The system of built-in tolerances is shown in Figure 8-1. The iteration tolerances are controlled by TØLINR and by TØLES2 which are input. The system starts with the maximum streamline movement (MAX-ES2) demanded by the "flow balance" in FLOBAL and compares this to a specified limit, L1M-ES2. If the MAX-ES2 is within limits, the "flow balance" is satisfied and more grid refinement is called for (if the limit has not been reached); otherwise, inner iterations continue until the specified tolerance, LIM-ES2, is met (or the specified NINNER limit is met). The specified tolerance, L1M-ES2, is controlled by TOLINR and the current grid size. Thus, the "flow balance" tolerance becomes smaller as the grid refinement proceeds.

If the grid refinement (MAXIT) criteria is satisfied or the field point limit is reached, a second tolerance (TØLES2) defines a final series of inner iterations. This permits a looser tolerance (TOLINR) during the flow field grid development and then a final tight tolerance (TØLES2) for actual flow field definition. The summary of this iteration tolerance is shown as NREFIN, GRID PTS, LIM-ES2, and MAX-ES2. A scan of the two columns in the flow balance

(See Section 11 - Sample Cases) shows the decreasing values of MAX-ES2 as the solution proceeds. Any erratic behavior in MAX-ES2 indicates convergence problems (the patient's heart is behaving poorly).

During an inner iteration, the streamline displacement (or correction) equation is solved to adjust the streamlines in the flow field. The results of the matrix solution are shown as a maximum streamline adjustment (MAX-DS2) which is actually made and the number of sweeps (NSWEEPS) through the matrix solution (IAD or LRELAX) to reach the final solution. Also shown is the cumulative time to complete the calculations at each level of refinement.

Three other columns, titled "orthogonolization", summarize the orthogonal adjustment in PTMOVE. This history is informative, but does not identify solution problems usually.

Under certain output options, the diagnostic printout includes a line of solution history at the end. Since the history is not summarized neatly on one page, care must be exercised in seeking out the solution history interspersed with the diagnostic output.

STC ITERATION TOLERANCE

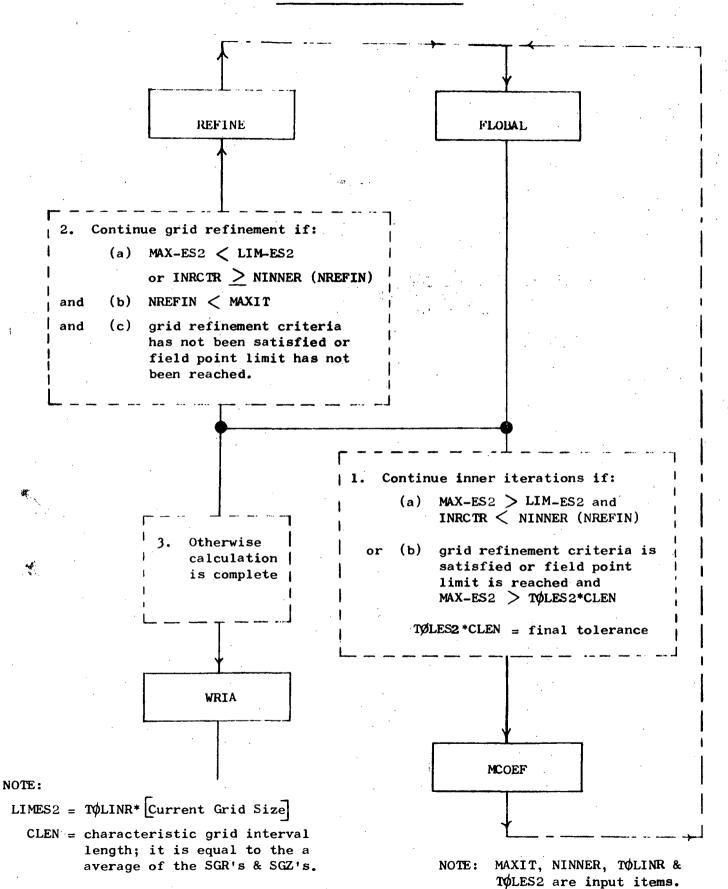


Fig. 8-1 Iteration Tolerance

8.2 STC Error Processing

In general, the occurrence of an error during processing will cause termination of the problem. Each of the main links contain an error print routine which will print the STC tables and the field tables to assist in diagnosing the problem. When the error occurs in overlays subordinate to (0,0), an illegal computed GO TO statement is executed. This will cause a MODE 4 abort and a printout of the sequence of subroutine calls preceding the error.

8.2.1 Description of Table Print Format

In general, the information stored in the STC tables consists of mixed BCD, floating point, integer, and logical data. A special routine (TABPRT) is used to print the arrays which may have a variable data format. The following conventions have been established for the output format on the CDC machines:

Data Type	· • 1	Print Format
Integer		Integer (I12) Format
Floating Po	int	E or F Format, depending on the magnitude of the number.
BCD		Hollerith characters A6 Format
Logical		TRUE. Variables are printed as an integer -0
		FALSE. Variables are printed as an integer 0

Note that a floating point 0, an integer 0, and a logical.FALSE. are all printed as an integer 0 since the data type, in this instance, is indistinguishable. The program listings (Volume III) may be consulted to determine the true type of the data should this situation arise. A junk word BITS = 10^{15} is utilized in the STC program for testing purposes. This quantity is printed using OCTAL format (04) and appears as 0000.

Since the data tables used in each overlay differs, the error print may differ slightly between links. The normal order of printed output consists of the general labeled commons, the STC tables (BDYTAB, STATAB, etc), the JMS table, and the field tables such as R, Z, VM, etc. The error print is best illustrated by an example of the typical output after an error in the flow balance (overlays (2,0), (2,1)). The variables in the printout may be identified by referring to Section 6.0 or directly to the program listings. Referring to the example, the initial output consists of the data in labeled commons/ALLCOM/and/CFB/. This latter common block is used as working storage by the flow balance routines. The STC tables BDYTAB, ADJWF and STATAB appear next. These data are packed in common/CHDATA/, with the location designated by the limits set in common/IXORIG/. Note that the relative location within /CHDATA/ is printed as the extreme left column of numbers. Following the STC tables are the /SLTAB/ streamline table and the JMS table denoting the upstream/downstream print connections through the field. The JMS table is followed by the data stored in the field tables S1, S2, Z, R, PHI1, CURV, VM and B. The final printout consists of the labeled common /ERASE2/, used as temporary storage by the flow balance routines. Following the output, a mode 4 error is initiated to obtain the subroutine backtrace.

Common /TROUBL/ contains two logical variables ERR and INERR which may be set to .TRUE. during processing. In this situation, the job is terminated normally in the main program. The table printout is preceded by the comment ERR = T, ERRLOC = n_1 , LENTRY = n_2 . In this comment, n_1 and n_2 are integers denoting the location of the last overlay call in the MAIN program and the current LENTRY setting (see listings).

8.2.2 Location & Explanation of Specific Error Comments

As mentioned previously, input or calculation errors will result in the termination of the problem. The locations (subroutine name) and description of error conditions are given in the following table. Included are suggested corrective measures (where possible), description of comments preceding the

table print, and a designation of whether the error is FATAL or NON-FATAL. One specific problem deserves further comment. When the iterative solution of the matrix equations for streamline point movement is in trouble (NSWP \rightarrow MAXSWP), a print of the solution matrix (DS2) and the maximum DS2 will start appearing in the printout. Subroutine IAD is structured to detect this problem and provide the iteration history over a complete cycle as the solution proceeds from over-relaxation to under-relaxation. In this case, the problem may usually be detected by inspection of the solution matrix. Appropriate corrections would be to input a RHOBAS larger than the preset value or preferentially sweep the field in a single direction.

Description and/or Corrective Measures		The last overlay call and LENTRY setting are given.	ow angles.	er as X. Will also occur	n specified limit.	the Station Table.	the Station Table.	d not BDY or CHN.	undary.	hannel input table. Change	TH section exceeds allocated	ated. Parameter A not between	Check input.	boundary points cannot be
Description and/	Copp.	ERR=T. The last overlay call and	Check PHIl array for spurious flow angles.	Integration - XC not in same order as X. if only 1 point in X table.	Number of iterations greater than specified limit.	Requested station not present in the Station Table	Requested station not present in the Station Table.	Second field on input header card not BDY or	No coordinate input for given boundary.	Insufficient table storage for channel input table. limits in /USECDG/.	Number of output points from SMOTH section exceeds allocated storage.	Series 1 contour cannot be generated. 0.5 and 1.0.	Boundary table not continuous. (Leading edge, trailing edge, and boundary points cannot
Specific Comment		No	No	No	No	No	No	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Type		ſΞι	Įъ,	F4	ſΞι	ſΞŧ	[E4	[I4	ĵz,	ſ z	[±4	F4	ľΨ	ĹΨ
Location Nearest Statement No.		12	20	119	77	120	120	007	55	950	1030	20	360	7 460
Subroutine Name		STCA	ATAN3	LSPFIT	QIREM	STANO	STAX1	REDINP	RBD	RCD	RELOXY	SERS1	BLDTAB	

Properties for requested channel not present in convected

property table.

Far field solution matrix is singular.

ordered according to orthogonal no.

Coincident orthogonals.

Yes

187

No No

510 125

ISBOT

TTPT

MATINV BPSORT

No

Subroutine Name	Location Nearest Statement No.	Type	Specific Comment	Description and/or Corrective Measures
BCONV	200	Œ	Yes	Flow rate for given channel not defined. Check channel input.
	183	z	Yes	Channel flow rate greater than choked value. Calculation continues.
	185	Ŀ	Yes	Static pressure exceeds total pressure for given channel.
BLDTBS	517	[14	Yes	Connecting edges not found for given channel.
	561	Œ	Yes	Connecting edges not found for given channel.
	009	ĹŦ4	No	
	642	Ĺτι	No	
	654	Į±,	No	
	989	Ē	No	
o	692	Ħ	No	
ac	720	Œ	No	
	730	ſ±4	No	
	820	ĽΨ	No	
	835	ſ±,	Yes	Negative radius encountered
	998	Œ	No	
	87.2	ſщ	N _O	
	968	Ħ	No	
JOFCHIN	70	ſ ε	No	Streamlines bounding channel not found.
OBI	105	; [24	NON	Channel name not present in boundary table.
	150	z	Yes	Boundary intersection not found. Point placed in an end interval.
RBCONV	190	- F 4	Yes	Restart - Table of convected properties exceeds allocated memo

Description and/or Corrective Measures	Unexpected choke at given station.	Lower far-field boundary not permitted.	Negative static temperature during flow balance.	Choked flow rate less than user input flow rate.	Number of iterations for satisfaction of Kutta condition exceeded	Failure to locate proper interval in the boundary table.					No control streamline.	Failure to relocate orthogonal angles and lengths at a double streamline.
Specific Comment	Yes	No	No	Yes	No	No	9	No	No	No	No	No
Type	Z	[14	Ħ	z	ĽΨ	ſΞij	Œ	E4	Ľų	Ħ	ĮΞι	į. Įžų
Location Nearest Statement No.	800	534	290	282	20	75	210	230	310	330	230	318
Subroutine Location Name Nearest Statement	ADJWF2	FLOBAL		ADJWF	NEWRAP	BDYPTM	INSTA				PTMOVE	

	Magnitude of point movement unreasonable. If first grid refinement, calculation terminated (MAJCTR ≤ 1).	Primary stations extend beyond the ends of the boundary.		Station table storage limit does not allow a new orthogonal at given station.	Streamline index of new SL greater than NJ.	Streamline limit reached.
No	Yes	No	Yes Namelist	Yes	No .	Yes
(24)	ZÞ	<u> </u>	[24	Z	Œ	Z
3308	3314	338	324	1440	160	170
			REFINE			

%

3306 3308

Description and/or Corrective Measures	Error in locating position of stagnation point.	No. of meshpoints on an orthogonal line greater than MAXOL.	Far-field boundary supersonic.	Maximum streamline movement greater than characteristic grissize.	Solution sweep limit exceeded.	Interval in X table not located. XC not in same order as X (integration)	Erroneous boundary conditions on cubic spline.
Specific Comment	No	No	Yes	No	No	No	No
Type	ĮΞι	[2 4	E	ļ u	Œ	[24	ſ±ι
Location Nearest Statement No.	148	09	945	100 300	235	120	410
Subroutine Location Name Nearest Statement	SLC	STTOFI	MCOEF	IAD		CUFIT	CUBERS

8.3 Example - Error Print-Out

	TTERATIONS		+ OKINGGNALICATION	NOIL	+ FLOW BALANCE	•	MATRIX	SOLUT 10N	• TIME	
:			- [100		- CSJEANN	M COUNTY			
	אייייייייייייייייייייייייייייייייייייי	•	ORE DA	(AFTER)					(SEC)	
1	0-			.816374	1-111163 I-111103		0.000000.	o 2	23.342	
i	0		ļ	193455	571197	ļ	0.00000.0	0 0	24.901	
	10-	00	.032812 .112704	108103	.287360	159815	0.00000	0 21	28.048	
		:					; ;			;
625	.922400	14.696000	518.700000	1.000000	1.000000	0000	1716.200	00	:	
0000	0	1.000000				1		:		· .
- 1										
370	0	792	12	:				;		. ;
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9.0 OPERATING PROCEDURES

The STC program described herein may be run on any Control Data 6400/6600 machine operating under SCOPE 3.0 or a higher level operating system. In general, operating procedures and control card set-ups will differ from site to site. The following comments on program modifications, deck set-ups, and operating instructions are restricted to the program as installed at the NASA Langley Research Center. Minimal changes should be necessary for successful installation at other CDC sites.

9.1 General Operating Procedures

Two versions of STC are available at the LRC computer site, both residing in source and absolute binary form on permanent file (data cell) disc storage. The first version has a maximum flow field data storage of 300 grid points, and may be run from the LRC remote input stations using a job field size of 70_8 K locations. It is expected that this version will be used to run problems through the first 2 or 3 grid refinements to assure that the program is operating satisfactorily and the input is correct. For problems of nominal size, it will be necessary to run a larger version of STC at the central site (field length < 70_8 K).

The larger version of STC may be created by recompilation (FORTRAN IV RUN compiler) of the two block data subprograms which set the size of the STC table and field point storage (USECDG) and the size of the influence coefficient arrays used in the solution for the streamline adjustment (USECDM). As a guide for setting the size of these labeled commons, a bench-mark field length of 100₈K storage is adequate for a problem of 730 grid points. The commons and arrays which must be altered to increase the problem size are:

1.) Block Data USECDG (overlay 0,0)

Common	<u>Variable</u>	Table/Description	-
/CDS2/	C12	Field Table - Streamline adjustment	
CRHS/	C16	Field Table - Right hand side of matrix equation.	
/CHDATA/	С9	STC Table Storage	
/CCURV/	C11	Field Table - Streamline Curvatures	
/CPHI1/	C14	Field Table - Flow Angle	
/CS1/	C17	Field Table - Distance along streamlines	
/CS2/	C18	Field Table - Distance along orthogonal lines	
/SLTAB/	С8	Streamline Table - Dimension 3* maximum number of streamlines	
/CM/	C13	Field Table - JMS (mesh point connection) array	
/CB/	C10	Field Table - Coefficient B in matrix equa	ition.
/CZ/	C20	Field Table - Axial coordinate (X,Z)	
/CR/	C15	Field Table - Normal coordinate (Y,R)	
/CVM/	C19	Field Table - Velocity	

As indicated in the preceding list, 11 variables comprise the flow field tables. These arrays should be dimensioned to the maximum number of mesh points. The exception is /CDS2/, which must be set to a minimum of 900 locations.

Note also that /CZ/ and /CR/ must reside next to each other in memory, as these quantities are used to determine the maximum limit for the number of field points. For problems with a large quantity of boundary input and/or a large number of anticipated orthogonal stations, it may be necessary to increase the size of the STC Table storage common /CHDATA/ beyond the 2046 locations currently allocated. The streamline storage /SLTAB/ is set to accommodate 128 streamlines; this should be of adequate size for most problems. As in the case of /CZ/ and /CR/, the commons /CHDATA/ and /CEND/ must be located adjacent to one another in memory. These items are used to set the maximum limit for the STC table storage.

2.) Block Data USECDM (Overlay 4,0)

Common	Variable	Description
/CA2/	C42	Curvature influence coefficient A2
/CA3/	C43	Curvature influence coefficient A3
/CA4/	C44	Streamline flow difference influ- ence coefficient A4
/CA5/	C45	Curvature influence coefficient A5
/CA6/	C46	Curvature influence coefficient A6
/CA7/	C47	Streamline flow difference influence coefficient A7
/CA8/	C48	Streamline flow difference influence coefficient A8

The dimension of the arrays in these commons should be the same as the dimension of the flow field arrays.

9.2 Recommended Procedures for Program Maintenance & Modification

As mentioned previously, a source and absolute binary copy of the of the STC program are stored on the permanent disc file (data cell) at the LRC computer center. It is recommended that relocatable binary copies of each version be maintained on tape. As changes are made to the program, only those routines which differ need be recompiled. The relocatable binary tape may be updated using standard COPYL and COPYN functions. Subsequent execution from this file will result in the creation of a new absolute binary file which may replace the one currently on the data cell. The updated source decks may also be updated at this time.

The source copy of STC contains *DECK cards as the first card of each subroutine. In running at other CDC sites, the source file may be used directly to initialize an update tape.

9.3 Standard Execution Deck Setups

Normally, the absolute binary (overlay) program will be reloaded from the data cell for execution. The suggested deck set-up is:

```
(Job Card)
(user Card)

FETCH (A3727, address on data cell, BINARY, STC)

COPYBR (INPUT, TAPES)

STC.

678 (EOR)
[Input Data]

6789 (EOF)
```

As indicated previously, this deck set-up is applicable at the NASA Langley Research Center computer site. At other installations, the absolute binary file may be reloaded from tape. For example, a typical deck set-up for use on the CDC Cybernet System is:

```
1
(Job Card)

LABEL, STCOVLY, R, VSN = UT611, L = CE1.

COPYBF (STCOVLY, STC)

REWIND (STC)

COPYBF (INPUT, TAPES)

STC.

678 (EOR)

[Input Data]

6789 (EOF)
```

9.4 Restart of STC Program from Data Tape

A partially completed STC problem may be restarted using the output data tape from the previous STC execution. The restart tape is obtained by specifying TAPIN as T on the general input header card and using a file card such as REQUEST or LABEL to assign TAPE2 to a given physical device.

Of course, the logical file TAPE2 must be assigned with "write permit" RING option. In the subsequent restart task, TAPIN must be specified as T on the general input header card. Also, the input file TAPE1 must be defined using an appropriate file card (NORING). The input for the restart case should consist of the identification cards, the general input header card, and the first \$A namelist. For example, to restart a job after 3 major grid refinements and run to 5 grid refinements, the example input might appear as:

NAME =J. Smith
ADDRES = LRC
IDENT = NASA 8 INLET
2 4 14 24
1 STC T F
\$A
MAXIT = 5,
S

Intermediate output at a given MAXIT level may be obtained by running a restart case and not assigning TAPE2 and TAPE1. In this instance, these files are assigned to disc and switched at the end of each total set of input. This option is also useful for changing program tolerances at a given stage of the calculation.

The preceding example could be run as one case using the following input:

2

NAME = J. Smith

ADDRES = LRC

IDENT =NASA 8 1 INLET

2 4 14 24

1 STC F

\$A

MAXIT = 3

\$

remainder of case input

1 STC T 1 \$A MAXIT = 5,

Successive restart cases may be stacked in sequence. On all but the final one, use 1 STC T T as the header card.

10.0 HELPFUL USER HINTS

10.1 General Comments

The following section is a compilation of information for the user. Many items have been covered elsewhere, but they will be repeated in this section for emphasis. The intent is to identify key input parameters so that computer solutions can be accomplished with minimum user problems or errors.

The primary items of importance are:

- 1. Smooth input geometry
- Grid refinement definition
- 3. Iteration tolerances
- 4. How to get out of trouble when the solution doesn't converge.

10.2 Smooth Input Geometry

The Streamtube Curvature method uses the boundary or body surface curvature as the geometry parameter which causes velocity and/or pressure gradients. Thus, the computer program is very sensitive to changes in curvature. Hence, an accurate definition of the boundary coordinates and local angles is imperative if surface curvatures are to be smooth and continuous.

There are two methods to insure smooth input geometry; a) use an analytic boundary or function with continuous first (angle) and second derivatives (curvature) or b) smooth specified boundary coordinates by fitting a curve to the surface points. The definition of an analytic boundary is not always possible and, in some cases, the intersection of two analytic functions will have discontinuous second derivatives. (An ASME nozzle is an ellipse followed by a straight line. The discontinuous second derivative causes a pressure "blip"). Hence, a curve fit technique may be necessary in most cases.

The best curve fit to use is a piecewise smooth cubic since the curvatures are evaluated in STC using the same type of curve fit. Hence, the definition of the coordinates and angles should come from some such geometry smoothing method. As part of the geometry definition, the curvatures should be checked for discontinuities or erratic behavior.

10.3 Grid Refinement

The grid refinement criteria is explained in detail in Section 12. Some comments on use are appropriate with reference to Figure 12-3.

First of all, the purpose of the grid refinement criteria is to maximize the grid refinement in areas of interest and to minimize the flow field grid in areas of smooth flow. By forcing flow field grid points to be used efficiently, computer table size and storage space is minimized and computer time is reduced. Also, the flow field grid can develop without over-constraining the streamline.

The best technique is to first identify the region or regions in the flow field where a high degree of resolution is necessary. The geometric grid refinement criteria in this area is set at a value equal to the grid size desired. As shown in Figure 12-3, a rectangular flow field section on the inlet lip is defined with SGZ = SGR. If a subsidiary plot of SGR vs GR and SGZ vs GZ are set up, the input table is readily developed. In the radial direction, SGR is specified at the centerline, decreases linearly to the region of interest, increases linearly to the outer region value and is constant from there out. In the axial direction, a similar plot can be drawn. The coordinates of these two plots become the input tables for GZ/SGZ and GR/SGR.

In some problems, the geometric grid refinement must be redefined if solution difficulties occur. A demand for excessive grid refinement in a local area can over-constrain the development of the flow field. Only experience will allow the user to make the optimum choice of grid refinement criteria for different problems.

10.4 Iteration Tolerances

The iteration tolerances, TØLINR and TOLES2, have been preset at recommended values for most problems. As explained in Section 8.1, these tolerances control the iteration logic for the grid refinement and the "flow balance" or inner loop solution.

Usually, if the input geometry is properly defined and no errors are made in defining the flow properties (such as setting VARY = T in all the channels), the solution proceeds through several grid refinements with no problems.

When the grid refinement criteria and the iteration tolerances are incompatible, i.e., the tolerances are very small and the grid refinement has high resolution in an area of large streamline curvature, the solution will show instability in the definition of streamline adjustment (MAX-ES2 will not decrease continuously). The remedy is to change the tolerances or the grid refinement or both.

One good procedure is to keep the iteration tolerances relatively large during the flow field grid development and then restart the last grid refinement with smaller tolerances. Again, experience in use of the computer analysis will be necessary to provide guidance in how to do this.

10.5 Trouble Shooting

The Streamtube Curvature Analysis has been set up as a user oriented computer program for the solution of relatively complex transonic flow field problems. Many of the control variables have been preset to the most generally useful value. Hence, a majority of problems will be solved quickly and accurately if the inputs (geometry and channel flow properties) have been defined correctly. But, there will be instances when numerical difficulties will occur.

Invariably, a large percentage of the numerical difficulties can be related to errors in defining the geometry or bad judgement in selecting the grid refinement or iteration tolerances. However, when large supersonic bubbles are present in a transonic flow, convergence problems in the inner loop have been experienced. A dump, very similar to that shown in Section 8.3, will result. The solution history gives the first diagnosis in that the level of grid refinement, the number of inner iterations during the last refinement, and the behavior of MAX-ES2 can be quickly reviewed. Often MAX-EST will start to converge and then show instability. By identifying the appropriate NINNER, the solution can be forced to the next level of grid refinement by rerunning the problem with the NINNER control inserted.

One good procedure is to rerun the program with the MAXIT set to the previous level of successful grid refinement and convergence, to get a complete print-out of the flow field, and then to restart the computer program with new iteration tolerances and/or grid refinement controls. The example cases in Section 11 show a problem solution which has been restarted with changes in iteration tolerances.

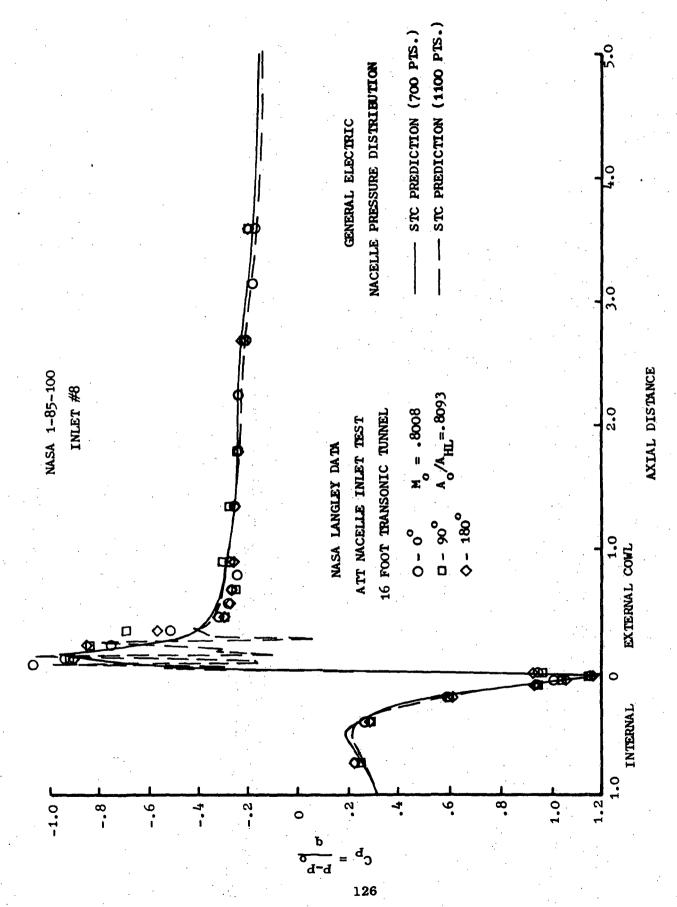
11.0 SAMPLE CASE - PROGRAM OUTPUT

The following sample case is the analysis of an inlet lip at a free stream Mach number of 0.80. The geometry is defined as a straight centerline for the lower boundary of the inlet flow (EDY CNTLN w2 and UPPER = F), the coordinates and angles for the inner surface of the inlet lip, the call for a NACA I external cowl lip (CLEX), and a farfield (FF) upper boundary. The grid refinement has been redefined as shown to eliminate some numerical problems. The iteration tolerance is TOLES2 = 1.0. The output print option is initially set for a summary printout of boundary information only (PRPRN = -1). The grid refinement level is set as MAXIT = 8. The input is printed out as the first pages of the output.

After eight grid refinements, the solution history and boundary flow conditions are printed out. The solution is restarted with MAXIT = 12 and again the same printout is requested.

The final iteration keeps the same grid refinement, but decreases the tolerance TOLES2 = .001 for flow balance convergence. The print option is changed to get the full flow field. These results are printed out as shown.

A comparison with test data is shown in Figure 11-1 for the solution after eight grid refinements (approximately 700 grid points) and after twelve grid refinements with the converged flow balance (1100 grid points). The additional resolution near the leading edge of the external lip surface is evident. This is an inviscid solution so that the oscillations in pressure are defined. A boundary layer solution indicates local separation and the test data agrees with this. Once the inviscid solution gets downstream of the separation region, it matches the test data very well.



Comparison of Predicted and Measured Pressures on Inlet Lip. Figure 11-1.



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.001300	.03880	.02340	7,73314	47.103	47.026	7.307785	.05761
.005003	16140.	•03606	7,74522	40.627	40.613	5.393196	.07512
.003966	.06571	.07140	7.76992	30.349	30.337	2.832944	.11è30
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.015000	.12727	.27000	7.84974	17.51.1	17.483	.437455	.33272
.020000	.14746	.36000	7,87635	15,633	15.619	.255594	.42657
.025000	. 16579	45000	7,90051	14.505	14.518	.156608	.51976
.03000	. 1829B	.54000	7,92316	13,753	13,772	.123801	.61257
.035000	.19930	.63000	7.94468	13.120	13.124	.120739	.70510
.040000	.21483	.72000	7,96514	12.509	15.497	.116369	0761.
.045000	.22959	. A1000	7,98460	11.927	11.915	.104142	89688
.05000	.2436A	00005	8.00317	11.406	11.403	.090636	.98138
.000000	.27013	1.04000	8.03804	10.557	10.563	.069178	1,16473
.070000	82462	1.26000	8.07052	6.922	9.924	.052815	1.34763
.090000	.31804	1.44600	8.10118	9.431	924.6	.042313	1.53023
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.160000	*4688A	2.58000	8.29999	6.486	6.470	.023849	2.9H405
.180000	649879	3.24000	8*33540	6.045	6.051	*01.6564	3.34621
.200000	.52696	3.50000	8.37653	5.721	5.735	.013928	3.70812
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.400000	.74746	7.20000	8.66715	3.708	3.712	-007612	7.32001
.450000	.78948	8.16000	8,72253	3,341	3.337	.006913	8.22171
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3HI + 1		(SEC)	3.695	860.4	5,119	6.002	7,583	9.061	10.627	12,602	17,273	20.452	2A.186	33,209	38,228	47,619	54,060	60,243
SOLUTION	NSWEEPS		0	01	0	10	0	12	0	7	0	91	•	81	18	0	18	0
MATRIX	MAX-052		0.000000	.309104	0.000000	.173140	0.000000	.096257	0.00000	.053074	0.000000	.053916	0.000000	.022294	.009147	0.000000	.025494	0000000
• ICE	MAX-ES2		945844	.085578	.271098	.031976	.198891	.014362	.135963	•027946	.339370	•056816	.296080	,155687	.028410	.193082	.024433	-083202
FLOW	LIM-ES2		1,111143	1,111143	.571258	.571258	.287101	.287101	177647	.177647	.143136	.143136	* 0040.	094054	*50*60	.061348	.061348	.048778
+ NOI1	MAX-DS1	(AFTER)	.950116	.285712	125906	.202396	.115558	,125314	.101838	.073353	.132628	.076424	106429	.073655	.053353	.085941	.054028	*041794
N HISTORY ORTHOGONALIZATION	MAX-DS1	DAMPING)	.950116	59067	, 126851	.222160	.121604	134626	.107857	.078305	.150353	*080*	.114493	.078086	.055621	.092070	.057393	.043764
SOLUTION + ORT	RMS-051	(BEFORE	.339248	.116128	.047688	.077651	.037566	.038743	.023972	.019677	.031355	•018115	•026729	.013026	*006628	.019001	.009169	.006156
INNER TERATIONS	CNVF		1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	00.1	1.00	1.00
INN	INRCTR		0	-	0		0		0		•		0	-	~	၁	5	0
) FNT	GR 10	PTS	20	20	113	113	178	178	221	221	327	327	484	444	494	598	865	656
GRID REFINEMENT	NREFIN		-	-	~	~	m	m	4	4	S	'n	s	٥	.	_	~	co

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(=-1.0.1. FOR STREAMLINE. ALTERNATING. AND ORTHOGONAL LINE RELAXATION)
(ACCELERATION FACTOR. BASE LEVEL)
(ACCELERATION FACTOR. AMPLITUDE OF VARIATION)
(TOLEPANCE RELATIVE TO MAXDS2) MATRIX SOLUTION PARAMETERS-IADM = 0 (==1 RHOAMP= .500 TOLPL = 1.0E-03 RHOAMPE PHORAS=

HIGHLIGHT RADIUS# 7.682 HIGHLIGHT AMEA# 185.395
HAX. BODY RADIUS# 9.000 MAX. BUDY AMEA# 254.469

CONTENTS OF CHANNEL TABLE-

000°000*= PSO = 00000° 00 = 8.0930E-01 VARY WTFLOW= 1.0000E+15 PTO =+000.000 GAM P O =+00000*0 MACHO =+00.0000 RG =+0000.00 7 7 113 113

CHANNEL FLOW HATES. PRESSURES. AND TEMPERATURES-

SPECIFIED ADJUSTED PT/PSO TT/TSO 47.7593 47.7593 1.5243 1.1280 EXT 3552.2407 3552.2407 1.5243 1.1280

IDENT = NASA INLET CONFIGURATION NO. 8

	PT/PT0 1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	3.000	1.000
	AMAX-A)/AMAX	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	3.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000
	00000°	000000	0000.0	000000	0000.0	000000	000000	000000	000000	000000	0000.0	0000-0	000000	0.000.0	0000.0	000000	0000-0	0000-0	0000.0	0.0000	0000.0	0000.0	0000-0	0000.0	000000	0000-0	000000
	MACH . 7979	.7902	.7754	.7586	.7274	.7001	.6847	.6640	.6513	.6450	.6355	.6305	.6222	9509*	.6157	.6137	8609	.6063	.6031	.6001	.5970	.5900	.5709	.5435	.5109	.4782	.4211
	PS/PT	-662	.672	.683	. 703	.721	.731	.741	. 752	.756	.762	.765	770	.781	.774	.176	.778	. 180	. 78?	. 784	. 786	.750	-80≥	.818	.837	.859	• 885
	. CP	.022	•054	260.	.161	.221	•52•	290	.327	.340	.360	.371	. 389	454.	~ 005	104.	.415	.422	.429	.435	2445	•456	967.	.551	.615	.677	.780
.000.0	PS/P0	1.010	1.024	1.041	1.072	1.099	1.114	1.130	1.146	1.152	1.161	1.166	1.174	1.190	1.180	1.182	1.186	1.189	1.192	1.195	1.198	1.204	1.222	1.247	1.276	1.303	1.349
COORDINATE. XIZ=	CURVW 0.00000	0.00000	00000.0	0.00000	00000.0	0000000	0000000	000000	00000.0	0000000	0000000	00000.0	00000.0	0000000	0.00000	0000000	00000.0	0000000	00000.0	0.0000.0	00000.0	00000-0	000000	00000.0	0000000	0000000	0.00000
	ANG#	00000	0.000	00000	0.000	000.0	0.000	0.000	00000	000.0	000.0	00000	0.0.0	0.000	000.0	00000	000.0	000.0	000.0	0.000	000.0	000.0	000.0	0.000	0.000	000-0	0.000
STREAMLINE	YW.RW 0.00000	0.0000	0.000.0	00000.0	0.00000	00000.0	0.0000	0000000	0.0000	0.00000	0.0000.0	0.0000.0	00000.0	0.0000	0.0000.0	00000.0	0000000	00000.0	0.30000	0.0000.0	0.0000	0.00000	00000-0	0.0000	0.00000	0.0000	00000-0
CHN=W2	WZ • MX • Z-	-22.47911	-14.95204	-11.17986	-7.37398	~5.4540B	-4.4H59U	-3.51307	-2.5455B	-2.06487	-1.59193	-1.12761	68301	F.26908	+0110+	45789	1.04790	1.64516	2.20851		3.32194	4.43894	6-71089	9.01711	11.30406	8	17.95257
BOUNDARY TO CHN=W2	S1W	7.517	15.044	18.816	22.422	24.542	25.519	26.443	27.450	27.931	28.434	2H.868	24.313	24.727	30.007	30.454	31.064	31.64]	32.204	. 32,761	=	ů,	20	34.013	39	53	47.948
LOWER BO	×11 0.000	.00	8.000	10.000	12.000	13.000	13.500	1 ** 000	14.500	14.750	15.600	•	20	15.750	• 00	16.250	16.500	16.750	•	17.250	•	14.000		~	'n	2.0	000.72

VIIO = 1.00

PT/PT0

UPPER BC	BOUNDARY TO CHN=W2	CHN=W2 .	STREAMLINE		COORDINATE. XIZ=	8.000°					
XII	S1 w	XM • ZW	YW.RW	ANGA	CURVE	PS/P0	م	PS/PT	MACH	CDPI (AMAX-	-A)/AMAX
000.0	0.000	-30.00007	6.91374	.074	0.00000	1.002	-005	.657	. 7979	0.000	017
000.4	7.515	-22.48506	6.92449	260.	00011	1.009	.021	.662	. 1906	0000	807.
B.000	15.030	-14.97009	6.94612	.277	00073	1.023	.050	129.	.7773	• 0005	*0*
10.000	18.748	-11.21267	6.47119	.515	00148	1.036	.081	.680	.7634	*000	004.
12,000	22.545	-7,45555	7.02262	1,165	00456	1.001	.135	969*	.7389	*00°	166.
13,000	54.454	-5,57744	7.07127	1.876	-,00865	1.078	.174	.707	.7214	.0027	383
13,500	25,363	-4.63870	7.10581	2,337	JOHS0	1.091	.203	.716	7081	.0038	.377
14,000	26,393	-3,70034	7,14932	3,063	01844	1.107	.238	.726	.6922	0055	369
14,590	27.242	-2,76278	7.20738	4.007	01680	1,128	. 2HS	.740	.6706	2800	956
14,750	27.712	-2.29442	7.24266	4,684	03333 ··	1.140	.313	. 74B	.65.76	.0101	352
15.000	24.141	-1.82660	7.28450	5,513	02848	1.159	.356	.761	. 6377	.0126	345
15,250	28,651	-1,35948	7,33352	995.9	04976	1.181	404.	.175	.6150	.0160	.336
15,500	29.121	89366	7,34356	8,231	+1410	1.223	864.	.602	.5698	: 0209	325
15.625	- 94-356	66162	7.42973	9.616	13051	1.248	.553	.818	.5427	•0244	.319
15.750	29.590	-,43075	7.47277	11.567	16395	1.298	•666	.852	.4845	2620°	,311
15,875	29.825	20243	7,52755	16,248	52853	1.396	. 885	.916	.3562	.0371	300
16,000	30.060	.01709	7.61024	-14,117	5.08615	1.524	1.170	1.000	000000	.0529	.285

1.000 = 011/11 ADDITIVE DRAG =

IDENT= NASA INLET CONFIGURATION NO. 8

x11	SIW	WZ • WX	YW.RW	ANGM	CURVE	PS/P0	ပ	PS/PT	MACH	_	AMAX-A)/AMAX	PT
000.9	00000	.01709	7.61024	-14.117	5.08615	1,524	1.170	1.000	000000	.0529	.285	_
6,125	.276	65223	7,43778	-23,752	-1.36780	1.248	.554	.819	.5422	.0253	.317	_
16.187	717.	.35846	7,39329	-14.438	96797	1.136	.302	.745	.6625	.0218	.325	~
16.250	.552	06665	7.36680	-8.081	66497	1.087	.195	.713	.7118	• 0206	.330	_
16.375	.828	.76923	7,34788	797	07227	1.121	.270	.735	.6777	.0198	.333	_
16.500	1.104	1.04536	7.34658	.211	05504	1.146	.327	.752	.6511	9610	,334	_
16.750	1.656	1.59757	7,35525	1.405	02040	1.169	.378.	.767	.6271	.0203	.332	_
7.000	2.209	2.14965	7.37014	1.502	.01425	1.187	.418	61.1.	-6682	.0214	.329	~
7.250	2.761	2.70181	7.38151	166.	00013	1.191	124.	. 181	. 6041	.0223	.327	~
7.500	3,313	3.25401	7.39113	1.001	00013	1.193	.430	.782	. 6025	.0230	.326	
8.000	4.418	4.35840	7.41050	1.009	00013	1.197	044.	. 785	6265	.0246	.325	_
0000.4	6.627	6.56697	7.45769	2.066	01403	1.197	177.	.786	.5975	.0284	.313	7
00000	8.436	8.77300	7.57195	3.655	01322	1.224	.501	.803	.5683	.0384	-292	_
21.600	11.045	10.97488	7.74926	5,263	00876	1.263	.587	.829	.5254	.0566	•52•	_
2.000	13.254	13.17321	7.96660	5.457	00063	1.304	.678	.855	.4781	.0833	.216	~
0000	17.672	17.57273	H. 17065	4.068	101127	1,351	783	886	0617	1428	135	

1/110 = 1.000

(,)						
5						
ORCES						
(AXIAL FORCES UNLY)	134.4362	00000	16.2800	150.7162	150.6165	2660.
	u	Ħ	Ħ		#	ĦĚ
CHN=NE		FORCE	FORCE	•	•	
INTEGRAL MOMENTUM BALANCE, CHN=W2	ENTEPTAG MOMENTUM	LOWER HOUNDARY PRESSURE	UPPER ACUNDAMY PRESSURE FORCE #	SUM OF AROVE	LEAVING MOMENTUM	G0043
Ĭ						

IDENT - NASA INLET CONFIGURATION NO. 8

PS/PT MACH CDPI -657 .7979 0.0000 -662 .79060000 -671 .77730002 -680 .73890004
7979 7906 7773 7634 7389
7773 7773 7634 7389
7773 7634 7389 7214
7634 7389 7214
7389
.7214
. 7081
. 6922
• 90/9•
. 6576
. 6377
• 0519•
. 5698
. 5427
. 4845
. 3562
000000

11/110 = 1.000

ADDITIVE DRAG = -.0529

=	S1 w	XW • ZW	XX.XX	ANGM	CURVE	PS/PO	a O	PS/PT	MACH	COPI (AMAX	X-A)/AMAX
00009	0.000	.01709	7.61024	57.208	5.08615	1.524	1.170	1.000	000000	0529	.285
187	.217	.11628	7.79278	24.377	1.33602	.682	709	.448	1.1360	0610	.250
6.231	.325	.21676	7.83216	19.140	.59286	.767	520	.503	1.0414	0563	.243
. 516.9	.433	.31980	7.45486	16.317	.33684	662.	655	.524	1.0069	0532	.236
644.	541	.42397	7.H9371	14.776	18445	.823	396	.540	41 HG.	0508	.231
.563	779.	.52473	7.92040	13.848	.14307	.850	335	.55A	.9529	6840	•256
16.750	.465	.73930	7.56440	12.367	12131	.863	305	.566	.9391	65+0*-	.216
.125	1.20H	1.16346	8.05336	10.247	• 06106	188	265	.57A	.9204	0411	.199
.500	1.730	1.58979	8:12557	9.076	.03744	. 893	239	.586	. 90B7	0375	.185
. 875	2.152	2.01732	R.19633	8.149	.03877	.896	233	.SAB	905a	0344	.172
.259	5.595	2.445H6	8.24805	7.225	.03330	668.	225	.590	.9020	0317	.160
5,49.9	3.027	2.47560	8.29944	147.9	01410.	606.	203	.596	.8921	0295	.150
000.	3.460	3.30507	8.34626	5,993	.01456	.919	181	.603	. BE18	0276	.140
19.750	4.324	4.16571	8.43117	5.367	.01188	.928	160	609.	.8726	6247	.122
20.500	5.189	5.02720	8.50698	4.762	06600	. 935	144	•614	.8653	0222	.107
0000	6.919	6,75192	8.63730	3,913	.00779	666	-,136	.616.	.8617	0164	610.
0000	10.378	10,20574	8.83071	2,557	.00618	576.	123	.620	.8554	0130	.037
0000	13.438	13,66296	R.54921	1,380	.00587	646	114	.622	.8517	6600*-	.011
000	20.756	20.5A12B	9.00000	000	00000	786	035	949.	.8157	0600*-	000
0000	27,675	C0000 75	0		00000	900	300	, 6	1000		

STREAMLINE COORDINATE, XIZ= 16.000. BOUNDARY TO CHN=EXT UPPEP

σ.									. •				
(-A)/AMAX	-43,482	-43.514	-43,552	-43.572	-43.594	-43.616	-43.635	-43.662	-43.687	-43.711	-43,734	-43,777	-43,813
CDPI (AMA)	00000	.0001	.0003	.0003	*000*	*000	*000	5000	· 0000	*000°	.0003	2000	0000
MACH	. 1979	. 1983	. 7986	. 7988	0662.	7662.	1661.	.8001	. 8005	6009.	.8012	.8017	.8024
PS/PT	.657	.657	.657	.657	.657	•656	• 656	959.	9999	.655	. 655	.655	.654
<u>م</u>	• 005	*00	.003	.003	.002	. 001	.001	000	100	002	-,003	÷00°-	005
PS/P0	1.002	1.002	1.001	1.001	1.001	1.001	1.000	1.000	1.000	666	666	966	966
CURVE	00000	00007	00008	00008	00007	00005	00003	00000	.00003	<00000	90000	80000	00000
ANCM	.163	.179	.211	.227	.242	.253	.260	. 263	.200	.251	042.	212	197
BI OF	60.02524	60.04720	60.07231	60.08621	60.10078	60.11552	60.12853	60.14637	60.16335	60.17975	60, 19542	60,22376	66.24838
MZ+MX	-30,17306	-22.69032	-15.30090	-11.66137	-H-104H0	-4.69826	-1.74097	2.10522	5.47110	9.49756	13,15443	20,31661	27.24820
»1s	000.0	7.483	14.872	18.512	22.068	25.475	28.376	32:279	35.494	39.671	43.32H	50.490	51.4nz
		_	0	0	0	0	0	0	22.000	0	9	0	0

1.000 11/110 =

(AXIAL FORCES ONLY) 9999.0358 -1.0307 CHN=EXT ENTERING MOMENTUM LOWER HOUNDARY PMESSURE FORCE UPPER ROUNDARY PMESSURE FORCE INTEGRAL MOMENTUM BALANCE. SUM OF AHOVE LEAVING MOMENTUM EPROR

EXTENDED FAR FIELD BOUNDARY 2= -44.500 H= 60.000 2= 42.500 R= 60.276

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	+ TIME		(SEC)	74.618	81,363	90,330	97.431	107,588	117,344	137,532	150.647	172,451	188,032	201,750	215,717	233,923
	SOLUTION	NSWEEPS		50	0	25	•	25	20	•	25	20	30	24	0	88
	MATRIX	MAX-052		.019695	0.000000	.009057	0.000000	.008375	.004014	0.000000	.009143	.005289	.002695	.002886	00000000	.002643
٠.	+ CE	MAX-ES2		.036405	.037893	.013682	.056054	.044829	.036987	• 060079	.056829	*04P936	.043777	.019654	.025507	.019994
*	FLOW BALANCE	LIM-ES2	-	.04877B	.042464	*042464	.039085	.039085	.039085	.033993	.033993	.033493	.033993	.033993	.027632	.027632
	· NOI1	MAX-DS1	(AFTER)	.016923	•051546	.023354	.030220	.020100	262410.	.023724	.019579	.013901	.013443	.011349	.013679	.008137
HISTORY	ORTHOGONAL I ZATION	MAX-DS1	DAMPING	.017938	.063318	.024120	.031522	.022596	.015486	.027333	.022107	.01510	.014563	.012131	.014840	.008837
SOLUTION	+ 0RT	RMS-DS1	CHEFORE	-002722	.014953	.006199	•003860	.003701	.002378	.003641	.006082	.00332B	.002858	.002546	591200	.001955
	INNER ERATIONS	CNVF		1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	00.1	1.00	1.00	1.00	1.00
	TER	INHCIR			0	-	0	_	~	0	-	~	m	3	0	-
•	MENT	GR 10	PTS	676	617	719	190	190	. 790	156	451	156	951	951	1601	1601
٠	GP 1D PEF INEMENT	NEF IN		20	Φ	σ	01 :	01	2	11	1	11	11	11	2	12

GENERAL INPUT-

•8000	1.00	1.000	1.52	1.128
u	**	11	tt	11
MACHO	150	PSO	PTO	110
-	00	0.0	00	•-
	-	1.40	000.0	
11	- #	11	Ħ	= <u>1</u> S
AXI	5	SAM.	TTF	CHOTS

STREAMLINF END CONDITIONS-LACIN = 2 2 ACF = 0.000 0.000 CURVATURE CALCULATION FOR SUPERSONIC FLOW-SSFWL = 1 (FORMULA NUMBER). SSFF(1) = .750 (DOWNSTREAM END CONDITION, SSFML=2 ONLY) SSFF(1) = .750 (UPSTREAM END CONDITION, SSFML=2 ONLY) SSFR(0) (10 STREAM END CONDITION, SSFML=2 ONLY)

SUPPRSOLIC ENTERING FLOW. T OR F.)
ISUPERSOLIC FLOW DOWNSTREAM OF CHOKE STATION. T
(SUPPRESOLIC FLOW HELOW AND AFT OF A L.E. POINT. HHANCH SELECTION-SUBSONIC/SUPEPSONIC SSULE 3.55

12.00 5.00 2 0.000 2.00 20.00 3.00 5.00 00000 **VMG2** 8.51 1.00 3.00 04. 0,000 . 125 0, . 50 A.50 -2.00 1.00 .375 -15.00 3.6 .375 . 5 0.00 Size Cultenia-#64/68= NG7/62=. VMSI 36.0 X Y V 267 2105

MEMORY UTILIZATION-

115ED AVAILABLE GPIN POINTS 1091 1500 144LES 1869 3070 5THEAMLINES 44 128

CONVERGENCE DATA-

MAXIT = 12 (MAXIMUM ITERATIONS) NAMETIN= 12 - NUMBER OF REFINEMENT ITERATIONS INACTR= 1 - NUMBER OF ADDITIONAL ITERATIONS AFTER LAST REFINEMENT

TOLINP = 5.0E-02 (INMER ITERATION TOLERANCE ON S.L. MOVEMENT)

TOLES2 = 1.0E+00 (FINAL TOLEMANCE ON S.L. MOVEMENT)

CLEW = 4.733 - CHARACTEPISTIC LENGTH BASED ON GRID SIZE CRITERIA

4.7E+00 - ABSOLUTE TOLEMANCE ON S.L. MOVEMENT

PREFINEMENT LEVEL TO WHICH CONSTANT DENSITY IS ASSUMED

(STREAMWISE PT MOVENENT DAMPING. =0 FOR NO DAMPING)

.020

CSICMP= NODENS=

2.0F-02

MAKESS=

LARGEST S.L. MOVEMENT ON LAST ITERATION

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SPECIAL BOUNDARY OPTIONS-FARFLD= FF

(=-1.0.1. FOR STREAMLINE. ALTERNATING. AND ORTHOGONAL LINE RELAXATION)
(ACCELERATION FACTOR. BASE LEVEL)
(ACCELERATION FACTOR. AMPLITUDE OF VARIATION)
(TOLERANCE RELATIVE TO MAXDS2) MATRIX SOLUTION PARAMETERS-IAAM = 0 (==1 .500 PH()9AS=

PHOAMP= .500 TOLML = 1.0E-03

HIGHLIGHT AREA= 185.395 MAX. HUDY AREA= 254.469 7.6+2 HIGHLIGHT RADIUS=

CONTENTS OF CHANNEL TABLE-

000 0000 = PSO = +0000 000 WTFLOW= 1.0000E+15 PTO =*000.000 AO = 8.0930E-01 VARY GAM =*00.0000

CHANNEL FLOW RATES, PRESSURES, AND TEMPERATURES-

17/750 1.1280 1.1280 PT/PS0 1.5243 1.5243 ADJUSTED 47.7593 3552.2407 SPECIFIED 47.7593 3552.2407

IDENT = NASA INLET CONFIGURATION NO. 8

LOWER BOUNDARY TO CHN=W2

. STREAMLINE COURDINATE, XIZ= 0.000.

\$1W
7W.2W 7W.2W 517 -22.47841 647 -11.17613 654 -11.17613 654 -11.17613 654 -11.17613 654 -11.17613 654 -11.17613 654 -11.17613 655 -11.17613 656 -11.17613 657 -11.17613 657 -11.17613 658 -11.1764 658
XW.ZW YW.RW ANGW 1000 22.47841 0.00000 0.000
XW. ZW. ZW. ZW. ZW. ZW. ZW. ZW. ZW. ZW. Z
######################################
200 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0

x11 S1	XX X	MZ · HX	YESP	ANGM	CURVW	PS/PO	<u>ස</u>	PS/PT	MACH	COPI	(AMAX-A)/AMAX	PT/F
0.000	30.0000	2000	6.91374	.074	000000	1.002	.005	.657	. 7979	0.0000	017.	~
	7.516 -22.48437	8437	6.92447	650.	00011	1.009	. 021	.662	.7905	0000	807.	-
_	131 -14.96870	6870	6.94608	.277	00073	1.023	.050	.671	.7773	.0002	*07	-
10.000 18.749	149 -11.21093	1093	6.97112	.514	87100·-	1.036	.081	089.	.7634	,000	004.	Ä
12.000 22.547	347 -7.45345	5345	7.02246	1.162	00454	1:061	.135	969.	. 7389	*100°	166.	_
13.000 24.4	.26 -5.5751	7516	7.07097	1.870	00863	1.078	.174	.707	.7214	.0027.	.383	÷
25.	366 -4.6363	3633	7.10540	2.369	00840	1.091	.203	.716	.7081	.0038	.377	~
ξ.	305 -3.697H	97H7	7.14H76	3.051	01846	1.107	.238	.726	.6921	.0055	.369	÷
14.500 27.2	244 -2.7402	h020	7.20660	3.490	01643	1.127	. 755	.740	.6708	.0082	9389	-
14.750 27.1	114 -2.29174	61.19	7.24174	4.667	03387	1.141	.314	.748	1750.	.0101	.353	
15.000 24.1	184 - 1.H	1.H2392	7:28342	5.485	02687	1.15A	.354	.760	.6386	.0126	345	~
15.250 28.6	124 -1,35671	5671	7.33206	857.9	07870-	1.180	707	.774	.6157	.0159	.336	~
15.500 29.123	•	89077	7.39146	8.149	07429	1.219	.	.800	.5740	.0207	.326	_
15.625 29.3	•	65859	7.42686	2.207	08311	1.243	.542	.815	.5478	.0240	.319	_
15.750 29.5		2742	7.46824	11.475	25341	1.243	.655	848	*4904	.0286	116.	-
15.812 29.7		-,31263	7.49304	12,773	13315	1.326	.729	.870	.4503	.0318	.307	~
15.875 29.828	-	65861	7,52100	15,331	-,62589	1.372	. 830	006	9360	.0358	305	<u>~</u>
15,906, 29.4		-,14225	7,53753	17,344	57008	1.406	205	. 923	.3413	.0385	662*	~
15,938 29.5	•	08650	7,55595	19,196	53153	1.445	405.	948	.2765	.0417	562.	<u>-</u>
15,569 30.(00- 500	03152	7.57654	22,299	-1.31141	1.488	1.089	976	.1862	.0457	1.62.	~
15,984 30.0	033	00461	7.58R27	24.980	-1.87318	1,513	1.146	666	.1013	.04B2	583	نسن
16,000 30,063	:	02151	7-60147	-16.203	4.74624	1.524	1.170	1.000	000000	.0511	.287	_

11/110 = 1.000

ADDITIVE DRAG = .0511

BOUNDARY TO CHN=W2

UPPER

STREAMLINE COORDINATE. XIZ= 8.000.

X I:1	₹	XM.ZW	YE OF	ANGE	■ へどつつ	PS/PO	<u>გ</u>	PS/PT	MACH	COPI	AMAX-A)/AMAX	<u>a</u>
000	00000	.02161	7.60147	-16,203	4.74624	1.524	1.170	1.000	0.000	.0511	.28	2
.016	•034	.04041	7.57257	-52,801	-3.90439	1.504	1.125	.987	•1394	6550.	62.	~
•031	640.	.06293	7.54647	-45,852	-3.13367	1.461	1.629	. 958	.2472	.0396	62.	_
1000	.103	SIRK).	7.52294	-40.445	-2.38557	1.420	.938	.932	.3195	.0353	.30	~
-062	.138	.11525	7.50161	-36.081	-2.02135	1,375	.837	-902	.3867	.0318	.30	'n
760	102.	.17348	7.46467	-28.933	-1.63463	1.289	. 645	.845	•4956	.0267	16.	~
• 125	.276	.23551	7.43452	-23.111	-1.34743	1.223	964.	.803	9695	.0236	31.	6 0
.156	.345	.30010	7.41030	-18,148	-1.15474	1.163	.364	.763	.6340	.0217	.32	άı
147	717.	.36641	7,39128	-13,985	14246	1.120	.269	.735	.6781	.0206	35.	٠
.250	.552	\$6105	7,36568	-7,775	01679*-	1.097	\$12.	617.	. 7025	0194	. 33	
16,375	85°	15777.	7.34777	-,764	07178	1,121	.271	.736	.6770	.0186	.33	<u>۔</u>
500	1.104	1.05321	7,34661	.236	05455	1.147	,328	. 752	.6507	.0186	Œ.	
.750	1.656	1.60514	7,35544	1.414	61992	1.170	.379	.767	.6268	1610.		C.
000	2.208	2,15494	7,37033	1,496	.01471	1,188	419	.779	.6078	.0202	35.	œ
.250	2.750	2,70883	7,38163	L44.	00013	1.191	124.	.781	-6042	.0211	,327	_
.500	3.312	3,26076	7,39125	10001	00013	1,193	430	. 783	.6024	.0218	38.	'n
000	917.7	4.36460	7,41061	1.009	00013	1.197	044.	.785	.5979	.0234	35.	~
0000	6.624	6.57209	7.45788	2.070	01403	1.197	.441	.784	.5975	.0272	31	
0000	8.832	8.77705	7.57223	3.658	01321	1.225	.501	.803	.5682	•0372	62.	~
000.	11.040	10,47769	7.74454	5.265	00874	1,263	. 587	.829	.5253	• 0555	\$2.	ው
000	13.248	13,17520	7.46680	5,858	00063	1,304	.678	.855	0824	.0821	12.	\$
000.	17.564	17,57273	8,37065	4.008	72110	1.35	783	ABA	4100	7171		ď

(AXIAL FORCES UNLY) 0.0000 INTEGRAL MOMENTUM BALARICE. CHN=42

ENTERING MOMENTUM

LOWER BOUNDARY PHESSURE FORCE =
UPPER BOUNDARY PHESSURE FORCE =
SUM OF AROVE

LEAVING MOMENTUM

EQHOM 1.000 TT/110 =

IDENT= NASA INLET CONFIGURATION NO. 8

LOWER BOUNDARY TO CHN=EXT . STREAMLINE COORDINATE. XIZ= 8.000.

01/7Y	1.000	1.000	1.000	1.000	1.000	1:000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	
AMAX-A)/AMAX	014.	804.	707.	007	.391	.383	.377	.369	956	.353	345	336	326	319	311	307	305	.299	.295	.291	.289	.287	
COPI	0.0000	0000	0002	0004	0014	0027	0038	0055	0082	-,0101	0126	0159	0207	0240	0286	0318	0358	0385	0417	0457	0482	0511	
MACH	. 1979	. 7905	.7773	.7634	.7389	.7214	. 7081	.6921	.6708	.6571	.6386	.6157	.5740	.5478	7067	.4503	3908	.3413	.2765	.1862	.1013	000000	
PS/PT	.657	-662	.671	089.	969.	.707	.716	.726	0740	.748	.760	411.	.800	.815	.848	.870	006	.923	876°	.976	.993	1.000	
d S	.005	.021	.050	.081	.135	.174	.203	. 238	. 2A4	,314	.354	. 402	484.	545	.655	.729	. 830	.907	*66.	1.089	1.146	1.170	:
PS/PO	1.002	1.009	1.023	1.036	1.061	1.078	1.091	1.107	1.127	1.141	1.158	1.160	1.219	1,243	1.293	1.326	1,372	1.406	1.445	1.488	1.513	1.524	
CURVW	0.00000	00011	00073	00148	00454	00863	00840	01846	01643	03387	02687	05450 -	62410-	04311	-,25341	13315	62589	57008	53153	-1.31141	-1.87318	4.74624	
ANCM	.074	260.	. 277	.514	1.162	1.870	2.329	3.051	3,490	4.667	5.445	6.498	8,149	502.6	11,475	12,773	15,331	17.344	19.196	22.299	24.780	73.825	
YW.RW	6.91374	6.92447	6.94608	6.97112	7.02246	7.07097	7.10540	7.14876	7.20660	7.24174	7.28342	7,33206	7.39146	7.42686	7.46824	7.49304	7.52100	7.53753	7.55595	7.57654	7.58827	7.00147	
XW.ZW	-30.00007	-22.48437	-14.96870	-11.21093	-7,45345	-5.57516	-4.63633	-3.65787	-2.74020	-2.29179	-1,42392	-1,35671	84077	65859	-,42742	-,31263	- 1585d	14225	08650	03152	00461	.02161	000
S *	00000	7.516	15.031	14.789	22.547	24.420	25.366	26.305	27.244	27.714	29.184	28.654	29,123	29.358	29,593	29.711	24.428	29.847	54.645	30.004	30.033	30.063	
XII	00000	4.000	8.000	10.000	12.000	13.000	13.500	14.000	14.500	14.750	15.000	15,250	15,500	15,625	15,750	15.812	15,875	15.904	15.938	15.969	15.984	16.000	11/110 =

ADDITIVE DRAG =

-.0511

IDENT= NASA INLET CONFIGURATION NO. 8

LOWER

						,						
LOWER BO	BOUNDARY TO	O CHNEEXT .	STREAMLIN	LLI	COORDINATE. XIZ=	8.000.			,			
-	S1W	XM.ZW	XX.MX	ANGE	CURVW	S/P	à.	ഗ	ပ) I d03	AHAX-A)/AH	PT/PT0
16,000	00	0 2 1	9	4.1	.7462	.52	.17	1.000	000	051	2.	1.0
•	150.	0103	•	116.415		1.508	1.134		N	0	.282	-
16.047	• 054	.00298	Ψ,	0	2300	.43	95	£65°	40	190	717.	1.0
•	.081	+0000·		6	.3000	.27	62	.838	50A	0655	572.	1.00
•	B01.	14400.		9	.4337	96.	3	•63]	838	0669	.267	1.0
16.117	7	.01907		ž	1795.	-842	35	.552	196	990	.263	1:00
16.129	.149	.02830		7	.6905	.733	5,	195	670.	0650	.261	7.0
•	16	.03837		Š	. Z.	50		.32A	37		.259	1.00
. •	.176	10650		Š	•46	• 322	3	.211	.672	190	752.	=
•	9	.06024	-	3	.63	9	5	.660	793	090	•256	1.00
16.176	.203	.07178	7	30	9.	. 196	456	.525	.01	060	.255	-
•	.216	.08359	7.77675	2,5	.41	569.		•456	2	0	•253	1.00
•	.244	.10778		25.12	9	004.	•	.263	.525	057	.251	1.00
16.234	.271	.13249	7.79991	23.	=	165.	914	.387	.247	0546	6,70	1.00
	.298	.15752	P	21.68	3	.865	300	.56R	936	053	742.	1:0
•	.325	.18277	4	20.48	_	.887	251	.582	-	0529	542	-
16,328	.379	.23379	30	18.55	.53773	.785	480	.515		051	242	-
	905.	.25551	3	17.78	ഗ	.717	631	.471	960	0	0,50	
•	617.	.27240	~	17.44	576	.546	-1.013	.35A	.305	050	.239	-
16,375	•433	-28532	7.85452	17.	.42471	. 924	170	909.	.8772	9650	.238	1.000
16.422	. CA7	.33721		15.99	.29250	.83]	377	.545	72	0488		1.0
16.469	175*	.38935	w	15.20	285	.846	344	.555	95.7			*
16.563	679.	60565		14.13	777	.854	-, 326	.560	48	09+0-		1.00
16.750	998.	.70473	٠,	12.00	.11132	. R66	298	•56₽	36	0429		7.00
17,125	\$5.	1.12918	٦,	10.37	633	.880	269	.577	~	038	•	1.00
17.500	1.732	1.55546	7	9.15	.03895	.893	238	.586	.9083	0344	•	1.00
۲.	•16	1.9839B	7	8.22	7	168.	N	.588	6706	0313	•	1.00
14.250	• 54	2.41301	.0	7.28	338	668.	225	.590	.9023	29	191.	1.00
•	.03	2.84288	. 4	6.53	213	806.	0	965.	3	0264	.150	00.
•	3.	3,27329		6.01	142	616.	Œ	.603	82	024	141.	1.000
J.	٣.	4,13503	4	5.32	.01201	.928	160	0	72	0215	.123	1.000
Ö	٦.	916	٠,	4.77	900	.935	7	. 614	.8654	610	107	1.000
ď	٥.	.7246	.~•	3,92	.00777	626	3	•616	5	015	610.	0
25.000	10.392	1829	٦,	'n	.00619	. 945		.620	ŝ	Ş	.037	0
æ	3.8	3.64		.38	•00586	676	-,114	.622	-	0	110.	1.000
4	0.78	72	000	000	9	786	S	4	15	0058	000	
o.	7.71	7.5000	000.	0	9	876.	- 005	• 654	0	05	0	0
11/11	1					,			•		٠	

= 0TT/TT

IDENT = NASA INLET CONFIGURATION NO. 8

	UPPER R	OUNDARY T	ROUNDARY TO CHN=EXT	. STREAMLINE	_	COORDINATE. XI2=	16.000.				·.		
	x 1.1	S1*	MZ.MX	YW. RW	ANGM	CURVE	PS/P0	<u>ئ</u>	PS/PT	MACH	COPI (A)	AX-A)/A-AX	1/14
	0000	00000	-30,17273		.163	-00000	1.002	.005	.657	. 1979	000000	-43,485	_
	000.4		-22,68950	60.04721	.179	00007	1,002	*00	.657	. 7983	.0001	-43,514	_
	8.000	14.873	-15.29974		.211	00008	1001	.003	.657	. 7986	.0003	-43,552	_
	10.000	ά.	-11,06055		.227	00008	1001	.003	.657	. 7988	.0003	-43,572	~
	12,000		-8.10430		.242	00007	100.1	,002	.657	0662	,000	-43.594	_
	14.000	25.	-4.69819	٠	. 553	00005	1001	.001	•656	7667	*000	-43,616	-
	16.000	26,341	-1,83227		.260	00003	1.000	.001	• 959	1997	7000	-43,635	~
	19.000		2,06871		.263	20000	1.000	-,000	959.	8001	*000	-43,661	_
٠.	22,000		5.74989	•	.260	.00003	1,000	001	•656	.8005	,000	-43,687	_
	25.000		4.47239		. 251	50000	666	002	. 655	6009	,000	-43.711	~
	24.000		13,13514	:	.240	00000	666	003	. 655	.801≥	.0003	-43.734	_
٠	34.000		20,30722		.213	.0000	866	+000-	.655	.8017	.0005	-43,777	_
•	000.04		27,28815		198	00000	866	005	.654	, 8024	0000	-43,813	~
										-	•		

6919	S S S S S S S S S S S S S S S S S S S
* 9998.9977	- LACK
9998.3828	
.0052	UPPER BOUNDARY PRESSURE FORCE =
6582	LOWER BOUNDARY PRESSURE FORCE =
9999.0358	n
(AXIAL FORCES (_

1.000

11/110 =

(80Y=FF

EXTENDED FAR FIELD BOUNDARY Z= -44.500 H= 60.000 Z= 42.500 H= 60.276

	TIME		(SEC)	244.659	62,024	80.149	CHC 80
	•			N	~	8	٨
	SOLUTION	NSWEEPS				28	
	MATRIX	MAX-DS2		.002643	.002302	.001423	. 0000
	•			_	۵.	_	
•	SCE.	MAX-ES2		.021713	.015962	.007618	2004345
•	FLOW	LIM-ES2		.027632	.027632	.027632	-027632
	TION	MAX-DS1	(AFTEH)	.007780	.01110	.007738	.004717
HISTORY	ORTHOGONAL IZATION	MAX-051	DAMP ING)	.004416	.012483	.008367	004400
SOLUTION	•	RMS-051	(HEFORE	.001191	. 002345	.001450	20000
	ER TIONS	INRCTR CNVF	٠	1.00	1.00	1.00	1.00
	INN ITERA	INRCTR	:	7	2	e	4
*	•						
	MENT	EFIN GRID	PTS	1001	1001	1641	1001
	GRID REFINEMENT	EF IN		12	75	72	12

GENERAL INPUT-

.000 00.1 1.52 MACHO **TS0** PS0 PT0 0.000 CHOTST= GAM

STREAMLINE END CONDITIONS-

0.000 0.000 NECIN

FOR SUPERSONIC FLOW-(FORMULA NUMBER) CURVATUPE CALCULATION SSFML =

(DOWNSTREAM END CONDITION, SSFML=2 ONLY) (INLET FLOW ANGLE. DEGREES, SSEF=T UNLY) 0.000 .750 SSFEND= SSFNDl= SSFANG=

PRANCH SELECTION-SUBSONIC/SUPERSONIC

(SUPERSONIC ENTERING FLOW, T OR F)
(SUPERSONIC FLUW DOWNSTREAM OF CHOKE STATION, T OR F)
(SUPERSONIC FLOW BELOW AND AFT OF A L.E. POINT, T OR F) SSDLE = SSDF SSFF

3.00 1.00 7.00 0.00 3.00 SIZE CRITERIA-MGR/GR= 203 GRID

20.00

3.00 34. 1.00 -2.00 1.00 12.00 -15.00 #162/62= 295

.125 .375 .375

10

VMC)

100

VM62

00000

0.000

00000

12.00

5.00

HEMORY UTILIZATION-

AVAILABLE 3070 1500 USED 1869 1001 STREAML INES GRID POINTS TABLES

CONVERGENCE DATA-

ADDITIONAL ITERATIONS AFTER LAST REFINEMENT REFINEMENT ITERATIONS (MAXIMUM ITERATIONS) NUMBER OF NUMBER OF 22 4 MAXIT = NREF IN INPCTR=

(IRNER ITERATION TOLERANCE ON S.L. MOVEMENT) (FINAL TOLERANCE ON S.L. MOVEMENT) 4,733 TOLINA 5.06-02 TOLESS= 1.06-03 CLEN

CHARACTEMISTIC LENGTH BASFD ON GRID SIZE CRITERIA ABSOLUTE TOLERANCE ON S.L. MOVEMENT LARGEST S.L. MOVEMENT ON LAST ITERATION 4.7E-03 4.3E-03 MAXES2= (STREAMWISE PT MOVEMENT DAMPING, =0 FOR NO DAMPING) .020 DSI DMP=

NODENSE

(REFINEMENT LEVEL TO WHICH CONSTANT DENSITY IS ASSUMED)

157

SPECIAL ROUNDARY OPTIONS-FARFLD= FF

MATRIX SOLUTION PARAMETERS-

=-1.0.1. FOR STREAMLINE. ALTERNATING. AND ORTHOGONAL LINE RELAXATION) (ACCELERATION FACTOR+ BASE LEVEL)
(ACCELERATION FACTOR+ AMPLITUDE OF VARIATION) RHOHAS= BUNDAMP

(TULF PANCE RELATIVE TO MAXDS2) TOLGL = 1.0E-03

HIGHLIGHT AREA= 185.395 MAX. BODY AMEA= 254.469 HIGHLIGHT RADIUS= MAX. BORY RADIUS=

7.682

CONTENTS OF CHANNEL TABLE-

-*000,000 PSO --00000-= = 8.0930E-01 VARY = 1.0000E+15 =#000.000 WTFLOW= PT() =* # W2 MACHO = €00,0000 RG = €0000.00

CHANNEL FLOW PATES PRESSUPES AND TEMPERATURES-

1.1280 1.1280 PT/PS0 1.5243 1.5243 47.7593 ADJUSTED 47.7593 SPECIFIED 52 Ext

80
0 2
IT ION
I GUR
CONF IGURATION
INCET
NASA
IDENT=

	ווור בי	01.44001.400	0										
STATION COOF	COORDINATE.	XII= 0.000**	** CHANNELS	S- W2	ExT								SUB
×	FNC	X • Z	¥•R	H	CURV	4	σ.	15/11		ACH	ARE	ΡĪ	
00	00	29,9955	0000	0	0000	000	S	.887	0	797	000	00.	•
5 6	ט נ	1966.62	4568	יו ס	0000	3 6	υ 1	, C. C. C. C. C. C. C. C. C. C. C. C. C.	200	75,	\$ 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.0	3 6	
2 6	0 0	0000 00	1888.	5 C		2 6	0 4 0 4	. C. C. C. C. C. C. C. C. C. C. C. C. C.	3 6	707	20.07	3 6	
200		30,000	9137	. 6		200	6,5	8		76	50.16	0.0	
8.125	• 050	-30.00525	10.16614	100	00000-	1.002	.657	.887	• 005	. 7979	324.685	1.000	٠
. 25	04	30.0101	2.6056	12	0000	00	65	.887	00	197	99.20	9	
.50	0.7	30.0197	6.4317	15	0000	00	S	.887	0	197	848.23	00	
00.6	£ .	30.0371	2.1856	6	0000	00	S	.887	0	67	546:30	00	
000	9	30.0679	0.6040	5	0000	00	S	.887	8	67	345.44	00	
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00	00	22.4844	9264	260.	000	00	φ.	689	.021	290	50.63	00	
9	56	44844	9.7244	250	000	ခ္ခ	۰ پ	8 6	120.	200	50.63	9	:
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2.00	20	22.6258	2.7541	-245	000	00	S	Œ	200	96	742.57	00	
14.000	1,000	-22.66273	52.12403	.269	00008 	1.002	.657	7887	200.	7978	8535.437	000	
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• 06	0	14.9789	8.7329	35	*000	02	67	-892	40	778	39.59	00	į
12	200	14.9883	0.2113	9;	9000	200	79	2695	.	8	75.75 (2)	000	
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00	26	15.1462	0.6773	7	4000	0	99	888	5	793	956.54	00	
.00	38	5.1898	7.2314	S	.0003	8	65	.888	0	795	54.81	00	
2.00	20	15.2223	2.7895	3	• 000S	8	65	.887	0	96	752.07	00	:
00.	s,	.2679	2,1535	5	.0001	1.002	ທໍ	.8A7	0 (6	545.11	000	
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IDENT = NASA INLET CONFIGURATION NO. 8

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•	PT/PT0	7.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	3.000	3.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	3.000	1.000	
	AREA	10.436	20.884	41.825	62.436	83.940	105.146	126.444	137,106	147.754	158.360	168.908	168.908	175.002	181.074	193.131	205.057	216.864	228,562	240.166	263,156	353,579	531.349	-
	MACH	.6293	.6279	.6244	.6200	•6146	.6085	. 6042	•6038	•6054	1609.	.6152	.6152	.6182	.6220	.6331	6779.	•6566	.6677	.6781	1569*	.7378	.7650	
	CP	374	.377	.384	.393	• 405	.418	.427	.428	454	.416	• 4:03	.403	.397	• 389	• 365	.340	.315	.291	•569	.230	.138	.078	
	15/11	.927	.927	.928	.929	.930	.931	.932	.932	.932	.931	.930	.930	626	.928	.956	.923	.921	.918	.916	-912	206	.895	
	PS/PT	992	.767	.769	.772	.775	.779	781	.782	.781	.778	.775	. 775	.773	.770	. 763	.756	672.	.742	.735	.724	169.	.679	
	PS/PO	1.167	1.169	1.172	1.176	1.181	1.187	1.191	1.192	1.190	1.187	1.181	1.181	1.178	1.174	1.164	1.152	1.141	1.130	1.120	1.103	1.062	1.035	
ExT	CURV	.00226	.00357	.00634	.00978	.01357	.01533	.00681	00267	01699	03078	04957	04957	02733	05958	06HB0	07161	07079	06901	06325	05044	02427	00839	
S- W2	H	900	.669	1.304	1.732	2.241	2.946	3.956	685.4	5.254	5.918	6.523	6.523	7.068	7.101	7.515	7.768	7.823	7.012	7.676	7.297	5.747	3.874	
CHANNEL S-	Y+R	1.42259	2.57828	3.64873	4.47230	5.16902	5.78524	6.34417	6.60623	6.85796	7.09983	7.33247	7.33247	7.46357	7.59194	7.84063	8.07508	8.30842	8.52956	8.74341	9.15234	10.60885	13.06514	•
XII= 15.250	X+Z	-1.13119	-1.14104	-1.16025	-1.18270	-1:205A9	-1.23431	-1.26685	-1.24664	-1.30795	-1.33204	-1.35696	-1.35696	-1.37275	-1.38870	-1.42043	-1.45265	-1.4H399	-1.51444	-1.54352	-1.59745	-1.76227	-1.96381	
STATION COORDINATE.	STRM FNCT	.062	.125	•250	.375	.500	.625	•750	.812	.875	186.	1.000	.301	-312	.323	• 345	.366	. 3Ad	.410	•432	.476	.650	1.000	
STATION CO	XI2 S1	000.	1.900	2.000	3.000	7.000	2.000	000.9	6.500	7.000	7.500	6.000	8.000	8.004	8.00H	8.016	8.023	8.031	8.039	8.047	8.063	8.125	8.250	

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1,000 0.02 0.02 0.000 0.0000 0.1771 1.76 0.92 0.92 0.92 0.900 0.000	×	STRM FNC	•	•	PHI	CUR	SZP	S/P	5/1	రి	MACH	RE	/PT
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1,000 1,10	S.	•0•	.682	. H270	.539	0025	.17	92	.928	.386	23	• 48	00.
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Color Colo	•	3.5	. 7081	•6583		077	.17	77	.929	• 398	17	40.	00.
1.00 1.00	9 6		4121.	6747	•	121	£ .	77	.930	604.	12	61.	00.
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8.012	00.	•	\$35	.6575	•	. 1263	20	78	6	4	595	84:21	9
8 0.10	5	•	954	.7H+6	•	.0674	٠٦	78	93	4	600	90.38	00.
8.023 . 2216 - 1.0013 8 . 4.013 1 1.0.381 - 1.1851 1.1163 . 783 . 976 . 3463 . 6425 . 214.473 1.0.581 - 1.0013 8 . 4.013 1 1.552 - 1.04137 8 . 4.013 1 1.553 - 7.0426 1.117 . 773 . 922 . 329 . 6501 . 2219.25 1.00 8.039 . 1.0023 8 . 9.932 9 . 9.745 1.0023 8 . 9.932 9 . 9.775 9 . 922 9 . 329 . 6501 . 2219.26 1.000 8.043 9 . 9.932 9 . 9.70 9 . 9.10 9 . 9.10 9 . 215 . 6412 2 . 2219.26 1.000 8.043 9 . 9.10 9 .	5	02.	977	.9085	ċ	.1435	918	7	93	4	608	67.96	00.
8.027 .222 -1.06197 8.26193 10.553 -0.06426 1.1155 758 992 .239 6655 226.344 13.00 8.039 .241 -1.106192 8.93422 10.166 -1.1264 1.117 7.42 915 .292 .6657 231946 1.00 8.047 .226 -1.106192 8.9342 10.166 .1131 7.42 915 .262 7.665 1.00 8.050 .241 -1.10623 8.9342 9.775 -0.0618 1.117 7.42 915 .262 7.665 1.00 8.050 .241 -1.10623 8.9342 9.775 -0.0618 1.117 7.62 916 .713 910 .215 7.065 2.106 1.00 8.050 .241 -1.10623 8.9422 9.775 -0.0618 1.117 7.52 916 .713 910 .215 7.065 2.106 1.00 8.050 .241 .10624 2.592 -0.0618 1.001 .1.016 .001 .001 .001 .001 .001 .	20.	. 21	1.020	.1471	•	1365	• 16	92	<u>ئ</u>	m	634	08.52	8
8.031 .228	٥٠,	*55	1.041	.2619	ċ	• 0642	.15	75	8	G.	642	14.44	00.
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TATION COORDIVATE, XII= 15.625 CHANNELS- W2 EXT XIZ STRM FNCT X.Z Y.H PHI CURY PS/PO PS/PT TS/TT CP MACH PT/PT 1.00 5.000 .750 .54543 S.81490 1.826 .03842 1.201 .788 .934 .448 .5941 106.227 1.00 6.500 .750 .56723 6.38628 2.520 .07647 1.231 .941 .515 .5617 139.267 1.00 7.500 .875 .59863 6.55808 3.245 .07647 1.249 .918 .545 .5483 150.562 1.00 7.500 .875 .59863 6.55808 3.245 .07647 1.249 .918 .545 .5483 150.562 1.00 7.500 .875 .59863 6.5280 .07647 1.249 .819 .944 .551 .5567 101.966 1.00 7.500 .937 .65892 7.42779 9.297 .09006 1.249 .816 .943 .543 .547 173.328 1.00 8.000 .696 .68892 7.42779 9.297 .09006 1.243 .816 .943 .543 .547 173.328 1.00 8.000 .696 .68892 7.42779 9.297 .09006 1.243 .816 .943 .543 .547 173.328 1.00 8.001 .696 .68892 7.42779 9.297 .09006 1.243 .816 .943 .543 .547 173.328 1.00 8.002 .696 .68892 1.0056 1.220 .939 .496 .5788 186.216 1.00 8.003 .496 .68892 1.00569 .1200 .23360 1.206 .932 .466 .5882 192.477 1.00 8.003 .848 .68892 1.0059 .21088 1.160 .761 .922 .932 .456 .5783 199.861 1.00 8.003 .848 .68892 1.0889 .110.34 .11873 .10889 .1103 .7145 .915 .226 .6643 .3371 1.000 7.6556 .8989 .8989 .10889 .10889 .1089 .202 .202 .202 .203 .202 .336 .6655 .10668 .1066 .	0	20.	1.8054	. 7863	•	• 0058	3	٥	. 89	• 035	7	85.24	9
XIZ STRM FNCT X.Z Y.H PHI CURV PS/PD PS/PI TS/IT CP MACH AREA PT/PI 100	TAT	COORDINATE	x11= 15	CHANNEL	S-S							•	
.000 .625 -54543 5.81490 1.826 .03842 1.201 799 .938 .448 .5941 106.227 1.00 .000 .875 -56723 6.38628 2.520 .0764 1.231 .799 .938 .488 .5747 128.129 1.00 .000 .875 -59863 6.586808 2.520 .0776 1.224 .494 .512 1.00 .000 .875 -59863 6.687282 4.625 .07647 1.243 .461 .945 .542 .542 1.00 .000 .875 -7.633 7.42779 9.00 .243 .543 .547 1.00 .001 .005 -7.639 7.42779 9.00 1.243 .816 .944 .553 .5477 1.00 .000 .056 -7.6906 1.243 .816 .944 .553 .5477 173.328 1.00 .001 .056 -7.4277 9.297 -7.0906	_	STRM FNC		•	PHI	CURV	9/2	2/8	1	a.	U	ď	1/7
.000 .75056723 6.38628 2.520 .07071 1.219 .799 .938 .488 .5747 1281.29 1.00 .501 .81258657 6.65808 3.245 .08764 1.231 .807 .941 .515 .5617 139.267 1.00 .502 .81258657 6.65808 3.245 .08764 1.231 .807 .941 .515 .5617 139.267 1.00 .503 .94359863 6.92282 4.625 .07076 1.249 .818 .944 .553 .5427 167.667 1.00 .504 .95765892 7.42779 9.29709006 1.243 .816 .943 .543 .547 173.328 1.00 .505 .968 .968 .96806841 1.243 .816 .943 .543 .5477 173.328 1.00 .506 .968 .968 .968 .968 .968 .968 .968 .96	.00	•62	5454	8149	82	. 2	202	78	6	877	.5941	6.22	00-(
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.00 .875 .5983 6.92282 4.625 .07647 1.243 4615 .943 .542 .5483 150.562 1.00 .500 .937 62349 7.18021 6.819 .00776 1.248 .819 .945 .553 .5427 167.667 1.00 .750 .969 7.2484 .816 .944 .553 .5477 173.328 1.00 .000 1.000 6892 7.42779 9.297 09006 1.243 .816 .943 .5477 173.328 1.00 .000 696 6882 7.4277 9.297 09006 1.243 .816 .943 .5477 173.328 1.00 .004 .722 6882 11.513 -14275 1.224 .816 .942 .523 .5573 179.826 1.00 .012 .722 -6882 11.513 -11893 1.216 .942 .523 .5573 186.216 1.00 .012<	.50	. 81	.5805	.6580	.24	2	23	8	.941	5	.5617	9.56	0
500 .937 62349 7.18021 6.819 .00776 1.249 .619 .945 .556 .5413 161.966 1.00 .750 .969 64033 7.30547 8.064 04841 1.248 .818 .944 .553 .5427 150.00 .000 65892 7.42779 9.297 09006 1.243 .816 .943 .543 .5477 173.328 1.00 .004 5892 7.42779 9.297 09006 1.243 .816 .942 .553 .5477 173.328 1.00 .004 5884 7.56549 11.234 .816 .942 .553 .5573 179.826 1.00 .003 .772 70827 7.549 23360 1.220 2336 1.189 .781 .935 .450 .5882 192.477 1.00 .015 .772 76356 7.95123 1.2606 771 .975 .589 .6508 196.477	00.	.87	.5986	.9228	.62	*	.24		96	3	S	0.56	0
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	5	8	.9452	•8372	54	7770		ť					

TATION COORDINATE.	NATE.	X11= 15.750	CHANNELS-	S- W2	EXT								SUB
STRM FNCT	NCT	X • Z	¥•₽	IHd	CURV	PS/P0	175d	15/11	9	MACH	AREA	PT/PT0	•
•	000.	26422	0.0000.0	00000	0000000	1.175	Ľ.	.928	.390	.6216	0.000	1.000	
•	290	27113	1.83071	.478	.00261	1.176	.772	626.	.393	• 6202	10.529	1.000	
•	125	27841	2.58992	.672	.00423	1.178	.773	626.	.397	.6184	21.073	1.000	
7	250	29333	3.66579	.938	.00781	1.182	.775	.930	.405	.6143	42.217	3.000	•
•	375	30883	4.49431	1.121	.01360	1.187	.779	.931	717.	.6087	63.457	1.000	
•	500	32280	5.19660	1.255	.02309	1,195	. 784	.933	464.	•0009•	84.838	1.000	•
•	625	33767	5.82066	1.343	.04263	1.206	162.	.935	094.	.5881	106.438	1.000	
•	750	35109	6.39400	1.530	.08903	1.227	509.	076.	.506	.5658	128.438	3.000	
•	812	35929	6.66811	1.84.7	.13253	1.243	.815	.943	.542	.5480	139.687	1.000	
•	875	36947	6.93827	2.622	.19743	1.266	. 830	976	.593	.5222	151.235	000-1	
σ•	937	38902	7.20476	5.764	.14795	1.249	.845	.953	.645	.4957	163.166	1.000	
•	646	40512	7.33967	8.359	.00513	1.294	679.	• 954	• 655	6685	169.240	1.000	
.	984	41575	7.40509	9.964	05552	1.293	948.	.954	•654	.4908	172.271	1.000	•
7.0	000	42778	7.46943	11.433	22723	1.289	948.	.953	. 645	*4952	175.277	1.000	
•	301	42778	7.46943	11.433	22723	1.289	.846	.953	• 645	*4952	175.277	1.000	
•	306	02555-	7.54236	13,398	16430	1.284	248.	.952	.633	.5018	178.717	1.000	
•	312	46155	7.6.133R	14.322	43390	1.273	. 835	.950	.610	.5136	182.098	1.000	
•	317	48013	7.68214	15.673	25411	1.262	.828	176.	.585	.5266	185.402	1.000	i
•	323	0.824.	7.74893	15.672	46463	1.250	.820	.945	.557	.5405	188.640	1.000	
•	334	53507	7.87712.	15.830	37567	1.219	.800	938	•489	.5742	194.933	1.000	
•	345	56934	7,49913	15.434	30773	1.194	. 783	.933	.433	.6014	201.018	1.000	
•	366	63070	8.23118	14.205	-114411	1.156	.758	.924	.348	.6412	212.A50	1.000	÷
•	377	65824	8.34255	13.567	15615	1.142	.749	.921	.318	.6553	218.649	1.000	
•	388	68394	8.45163	12.956	13275	1.131	.742	.918	.293	• 6999	554.404	1.000	
7.	410	73074	8.66396	116.11	95960*-	1.114	.730	.914	.253	.6851	235;821	1.000	
•	432	77238	8.86967	11.012	07493	1.100	.722	116.	.224	•6986	247.152	1.000	
7.	476.	84431	9.26463	9.654	E+840	1.082	.709	206.	.182	.7117	269.654	1.000	
•	· 059	-1.03997	10.68695	6.552	01820	1.045	. 685	868	.100	.7550	358.804	1.000	
7.	000	-1,26213	13,05471	4:197	00669	1.028	.674	.893	-062	17721	535.408	1.000	

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178.663 1179.500 180.348 180.348 181.230 181.230 184.819 193.728 193.728 193.728 193.728 205.056 221.888 227.467 238.603 174.656 177.101 178.634 179.628 180.901 181.958 182.572 183.519 CP 948 .030 .030 .084 .141 .141 .108 .050 .050 .050 .050 .050 .050 .050 5/11 998 998 999 999 999 990 990 9575 9759 9759 9759 9759 9759 937 3.16500 6.12728 9.32225 16.29951 -1.91520 -1.91520 -1.67162 -7.31674 1.57298 3.20277 5.39891 6.32288 2.88141 1.08081 EXT -8.291 -6.721 -2.420 24.691 24.691 551.196 48.937 42.549 -7.599 CHANNELS- W2 CHANNELS-54124 57670 57670 57670 60994 618277 73356 73356 .50820 .54063 .56157 .58832 .58832 1.95274 1.96774 8.07907 .37080 .45619 STATION COOPDINATE, XII= 15,969 XII= 15.984 -.02444 -.02404 -.02612 -.03159 -.03159 -.07460 -.19303 .32167 STATION COORDINATE, 9998 9987 9987 8.006 8.016 8.023

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	لنفا	0.00	10.554	1.12	2.31	3.59	5.01	6.42	8.60	9.63	1.39	3.72	0.60	4.61	7.04	8.56	9.54	•	9 0) () () () () () () () () () (æ	70.	55	76.95	78.40	79.28	0.14		AREA	-	3.64	170.463	4.36	65.9	7.80	8.38	8.91	
	MACH	17	•6162	7	2	05	98	87	.5668	48	9	58	86	7	248	90	44	1	1 1	2			MACH	387	317	251	97	157	.1370		ပ	520	462	9	323	270	41	235	45	
		.398	.401	• 405	.413	.424	.439	.462	. 504	.541	009*	.713	.838	946.	9	8	1.121	CONTINUE		MENTIN FILL	-		ď	.836	176.	1.024	1.079	1.112	1.126		පි	29	0		93	00	03	70	~	
	15/11	626.	•26•	.930	. 931	.932	. 933	.935	076	. 943	676	. 096.	91	.981	g.	.993	966	Z Z O O N A	(C) G = G)	20212	בר ו-מכ	. •	11/51	.971	.980	.988	200.	.995	966.		15/11	696	656	.970	616	.986	BAC.	686	.988	;
	PS/PT	.773	.774	.775	.777	.781	. 785	.792	709	.615	.832	998.	-905	.934	. 45A	976	986	71.00			5		PS/PT	.902	ъ.	σ	9	Q.	.987		PS/PT		86	006	93	95	36	96	096.	
	PS/PO	1.179	8	8	1.185	<u>,</u>	6	S	25	• 54	• 26	<u>.</u>	37	.42	46	48	1.502			•			S	1.375	•		•	•	1.504		٠,٩	1.267	.31	37	.41	77.	46	46	1.463	
	CURV	00000-0	•00549	• 00380	.00743	•01211	.02148	.03689	.0H548	1445	.27413	.6548	1.64742	.1611	.7452	.7227	.5764						CURV	.6111	328	.7527	•4388	.1743	.9034		CURV	264	744	•	.925	.291	.297	529	• 135	
LS- W2	РНІ	00000	• 438	.608	.817	. 415	すかお。	684	540.	*65°-	-1.749	-4.239	967.9-	-8.035	٠,٥	-11.940	6.	٠.				LS- W2	PHI	-7.033	-10.103	-13.892	-19.407	-26.792	-52.792	LS- W2	БН	-2.024	-5.013	-8.573	-13.676	-21.111	-30.238	-38.149	-45.845	
* CHANNELS-	æ.≻	00000-0	1.63291	2.59301	3.67002	4.49928	5.20187	5.82574	6.39805	6.67156	6.94200	7.21897	.3691	.4553	.5070	7,53918	865S.	d C		70.07		CHANNELS	×.	7.36850	7.45416	7.50499	7.53571	7.55426	7.57254	CHANNELS	· α.	6.94142	7.21743	7.36615	7.44999	7-49742	7.52330	7.53538	7.54644	
XII= 16.000**	Z•x	.01233	67700	00230	016H7	02860	Z6070°-	04354	05415	05255	- 04B09.	03374	02023	10600-	00043	.005KR	010	=				STATION COORDINATE. XII= 16.016	X•2	01451	00131	96800	.01820	.02553	.04043	XII= 16.031	X+2	03027	01457	.00259	.01816	.03273	.04460	.05299	•06290	
COORDINATE	STRM FNCT	000-0	.063	.125	.250	.376	.501	929.	.751	718.	.877	•666•	.971	, 986	766	906	1.000	VO 1300 (THO) SOCIONATION	CONTRACTOR CONTRACTOR CONTRACTOR	AVIAL MOMENTHE ELLS	AIML HONE	ORDINATE.	RM FNCT		.984	266.	964.	866	1.000	COORDINATE.			.937	696.	986	266.	966.	P66.	1.000	. •
STATION COC	X 12	0000	.500	.000	2.000	3.000	000.4	2.000	6.000 6.000	6.500	7.000	7.500	7.750	7.475	7,938	•	7.984	VANIA	TI WINS	A TOT		STATION CO	X12 STRM		7.875	7.938	7.969	7.984	8.000	STATION CO	XIZ STRM	000	7.500	7.750	7.675	7.438	7.969	7.584	8	

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	ADEA		•	•	ä	ď	۳,	ś	Ġ	ω	139.149	6	6	ທໍ	~	•			RE	5.25	19.90	28.05	8.67	49.17	29	4.57	9.61		1	APE	0.00	0.63	1.27	2.58	3,93	5.29	9.64	7.89	.43	06°8	9.27	4	• 56
	٠,	5 :	*	2	=	9	604	600	594	9	.5916	0	35	68	.6852	95		•	MACH	* 209 *	.6011	• 6065	.6147	•6300	.6533	6999•	.6770		1	3	•6098	6	8	ø	9	4	Ω	.*	.6221	_	-	.6464	• 6507
	á	•	Э	0	_	~	~	m	4	\$	453	3	36	29	S	-	. •		3	C.	43	45	0	.372	.322	.293	.271	-	1		.415	₩.	_	N	N	\sim	~	0	8	•	3	.337	Q.
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	0	, ,	-	77	17	11	Œ	78	78	5	28	78	76	7	17	.719			PS/PI	.782	. 783	.780	.775	.765	.751	.742	.736			Δ.	~	~	~	œ	20	30	ø	~	~	ø	S	.755	S
	9	LC	9	3	3	8	61	3	20	20	1.203	61.	. 16	~	.1.	60		•	SVP	-19	Ç	.18	. 18	٠16	7	1.131	12			જે	∹	٦.	₹.	٦.	٦.	~	7	∹	1.174	7	_	1.151	1.147
	2017	4400	0000000	.00213	.00332	.00566	.00859	201144	.01541	.00485	02048	-11552	-,33135	50923	29560	64903		٠.	CURV	0051	.0024	0315	.0673	1192	16564	• 1652	0717			ر د د	0000	014	.0020	0027	0023	500	0111	.0360	0517	•0629	593	05499	-*05454
S- W2	110	֡֓֓֓֓֓֓֓֓֓֓֓֓֓֓֓֓֓֓֓֓֓֓֓֓֓֓֓֡֓֡֓֓֡֓֓֓֡֓֡	00000	.377	.513	. 645	049	454	650	-1.288	-2.402	-4.160	-6-294	-7.293	-8.314	_	CI I	5 7	Риј	.303	177	-1.044	-1.605	-2.065	-2.04B	-1.702	164	-S-		H H	0000	•316	•420	967.	1770	.267	059	465	598	552	225	• 029	•236
CHANNELS	•		00000	1.83615	2.59747	3.67585	4.50550	5.20719	5.82791	6.39120	6.65526	6.40767	7,14557	7.25804	_	556	Para A M		ו×	5.20923	5.82710	6.38439	6.64380	6-89073	7.12514	7.23781	7.34777	CHANNEL		α ⊁	•	•	•	•	•	•	5.82642	•	•	•	•	7.23452	•
XII= 16.250	۲.7	•	40877	***	.45500	.44239	.43417	06524	. 42477	75227	43775	45116	47381	6H9H7.	[7767 *	5019	X11= 16.375	77.01	X • Z	.74356	.74287	.74811	. 75413	.76209	.71077	.77452	.17725	XII= 16.500		_	1.07623	ä	•	_	1.05019	•	1.004437	1.04674	1.04922	1.05173	•	1.05366	•
COORDINATE.	TOM ENCT	- 2	000.0	. 062	.125	.250	.375	500	675	750	818	.875	.937	696.	されつ。	00	COORDINATE		STRM FNCT	•	•625	75	81	87	.937	696.	1.000	COOPDINATE.		ž	000-0	. 062	.125	. 250	•375	.500	•625	. 750	.812	•875	.937	696.	1.000
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CHANNELS	7		0000	2741.	.6063	•6865	4.51548	•	.H277	.3806	6.63588	1999.	1252	• 24	.3554	CHANNEL	α. ≻	000		Ì		**************************************	•	.2181	.8323	386	7040*	.8959	•	.3703	CHANNEL	α· -	0	8481	2.61350	•6954	.5250	.2237	• 838B	9766	. 5550	.9056	1475	.3816	
xII= 16.750		4633	05550.1	DE 270	1.04445	1.63682	1.63031	1,62556	1.62177	•	1.61639	.613	5	76	•6051	x11= 17.000	X • Z	^	2122	20 BO		****	777	21813 11813		505/1.2	.1/13	1/91.	.1623	.1569	XII= 17.250	X • Z	77	7678	.7634	.7553	.7476	.7404	,7331	.7254	.7214	.7172	7	.7088	
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496 493 491 491 473 473 458 571 933 933 933 933 933 933 933 5717 939 938 938 937 935 .802 .801 .800 .799 .795 .795 SIPT PS/PO 1.204 1.204 1.203 1.199 1.197 57 PO 198 \$780 222 222 223 220 217 205 197 -.00095 -.00118 -.00220 -.00123 -.00044 -.00070 -.00058 CURV 0.00000 1.00139 1.00260 1.00288 1.00162 CURV 0.00000 -.00224 -.00323 -.00485 -.01194 0.00000 0.000 358 .509 542 619 .792 .882 0.000 .603 .847 1.176 1.589 1.831 917 695 .97 60. CHANNEL S-CHANNELS-CHANNEL S-7.8 0.00000 1.85092 2.61728 3.74035 4.53073 5.23031 0.00000 1.87617 2.65235 3.74918 5.29241 6.47075 5.84628 7.15702 0.00000 2.62611 3.71232 3.71232 5.24591 6.42072 6.43337 5.66383 6.5148 STATION COORDINATE. XII= 17.500 x11= 18.000 XII= 19.000 3.30483 3,29331 3.27708 .40059 .38128 .37264 6.71657 6.69678 6.697730 6.647130 6.64012 6.57212 3.26079 .32855 .31891 .32364 .2688b 43352 43941 .36463 .42207 STATION COORDINATE. STATION COORDINATE. 0.000 250 250 375 500 662 662 750 875 750 875 0.000 .062 .125 .250 .500 .750 0.000 125 500 750 875 000 STRM FNCT 000. 3.000 5.000 6.500 7.000 7.500 000. 6.000 175

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	APEA 182-343 182-344 183-709 185-317 191-157 193-974 194-670 205-239 2216-030 2216-030 236-786 887-887 2985-156 836-786 836-786 836-786 836-786 8567-791 1358-209	AREA 182.703 183.108 183.872 185.412 186.310 86.310 183.951 184.027 186.027 186.659 191.455	5.42
	## ## ## ## ## ## ## ## ## ## ## ## ##	MACH • 1738 • 1741 • 2393 • 4096 • 6096 • 2781 • 2781 • 5781 • 5781 • 5556 • 5556	627 652
	CP 1.107 1.067 1.067 1.067 .969 .969 .333 .264 .167 .167 .009 .006 .001 .001 .001 .001 .001 .001 .001	CP 11.039 1.0399 1.0337 1.0337 2.993 2.992 2.992 2.992 2.992 2.993 2.993 2.993 2.993 2.993 2.993 2.993 2.993 2.993 2.993 2.993	.325
	15/TT 995 989 981 968 953 922 915 915 915 915 900 900 897 897 897 897 897 887 887 887	75.11 9999 9999 9989 966 985 985 976 976 976 976 976 976	92 92
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	7 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	PS/P0 1.5505 1.4655 1.2878 1.4439 1.276 1.236 1.236	1.169
	-19.91909 -12.81313 -7.11524 -3.64677 -1.68130 -1.06220 -1.0823 -1.0834 -0.08657 -0.08657 -0.08657 -0.00029 -0.00029 -0.00029 -0.00029	CURV 5.62653 -11.53775 -11.53775 -3.80350 -1.65190 CURV 6.22945 -1.7634 -6.61014 -5.67018 -1.52571 -1.52571 -1.52571	37129
S- EXT	\ \tau \\ \tau	14000000 - 00000000000000000000000000000	3.37
- CHANNELS	0 0 0000000000000000000000000000000000		.0862
XII= 16.000**	X	X.Z -01542 -05871 -09358 -14418 X12 X12 X12 -01299 -01150 -06467 -17252 -17252	25804
COORDINATE.		FNCT -000 -005 -125 -125 -500 -500 -016 -016 -031 -250 -250 -250	1.000
STATION COC		8 0000 8 0000 8 0000 8 0000 8 0000 8 0000 8 0000 8 0000 8 0000 8 0000 8 0000 8 0000 8 0000 8 0000	50

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PT/PT0	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000		P1/P10	1.000	1.000	1.000	1.000	1.000	3.000	7.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	7.000	1.000	1.000	1.000
AREA	185.244	185.281	185.373	185.700	186.730	189.259	191.950	194.676		AREA	186.524	186.642	186.778	187,118	187.534	188,003	189.077	190.242	192,790	195.387	200.A12	206.226	217.307	222.804	228.331	239.377	250.440	272.564	360.956	537.092	888.033
MACH	.5177	.4834	4596	* 4504	.4761	.5353	.5735	*009 *		MACH	.8358	.1756	.7275	.6445	.6098	.5950	.5810	.5865	2609*	• 6266	.6531	.6707	-6945	. 7013	.7070	.7174	.7243	.7360	.7595	. 1748	. 7869
ď	.602	.668	.712	.728	.681	.568	065.	.435		3	079	•054	.160	.341	.415	955.	475	.463	914.	.379	.323	.285	.234	.218	• 506	.183	.167	.142	060.	• 056	•050
15/11	676.	.955	656.	.961	.957	976.	.938	.933	·.	15/11	. 877	.893	*06	.923	.931	. 934	.937	.936	.931	.927	.921	.917	-912	.910	606.	. 404	. 905	-905	.897	.893	.890
PS/PT	.833	.852	. 465	048.	.856	. 823	.800	.784		PS/PT	.633	519.	.703	.756	.778	787	962.	. 792	.778	. 768	.751	.740	.725	.720	.716	.710	.705	869.	.682	-672	. 665
PS/PO	1.270	1.299	1.319	1,326	1.305	1.254	1.220	1.195		PS/P0	796.	1.024	1.072	1,153	1,186	1,200	1,213	1.208	1.186	1.170	1.145	1.128	1.105	1.098	1.092	1.042	1.075	1.063	1.040	1.025	1.013
CURV	6.30030	7.24445	3.05366	64528	-1.86015	-1:17733	79868	-·55869	· ·	CURV	14.43993	6.27010	9,36151	5.27466	1.63926	1.25667	19291	60895	-,46344	38326	25804	-16779	11706	05006	08253	0423 4	04104	03254	00982	00584	00501
Ind	91.182	81,397	75.706						S- EXT	IHd	67.5AB	416.69	64,544	59,728	54,306	50.873	44.599	39,615	33,380	29.321	54.239	21.107	17.250	15.848	14.927	13.253	12.073	10.296	6.777	4.292	2.575
¥•R	7.67887	7.67963	7.08154	7.58431	7.70961	7.10164	7.61662	7.87193	CHANNEL	ו×	7.70536	7.70780	7.71059	7.71760	7.72618	7.73584	7.75791	7.78176	7,43371	7.88630	7.99502	8.10208	8.31691	8.42145	8.52526	8.72903	8:92947	9.31449	10.71895	13.07523	16.81279
X+Z	+00000	50600*-	01837	0366H	06866	11403	15625	16847	x11= 16.094	X+2	62700	0017B	00843	02166	03475	04748	07114	09307	-,12979	16268	21437	26084	32890	36108	38920	560.55	48540	56154	76650	48581	-1.20869
TRM FNCT	000.0	.031	-062	.125	.250	.500	.750	1.000	JORDINATE.	'RM FNCT	000.0	.000	.003	-002	.003	700	900.	800.	.012	910.	.023	•031	.047	• 052	*062	•07₽	760°	•125	• 250	.500	1.000
	8.000	8.000	8.000	A.001	8.002	8.004	8.006	8.008	STATION CO		8.000	8.000	8,000	8.001	8.001	B.002	8,003	9.004	9000	8.008				8.027	8.031	8.039	B.047	A.043	8.125	8.250	8.500
	PHI CURV PS/PO PS/PT TS/TT CP MACH AREA	XIZ STRM FNCT X.2 Y.R PHI CURV PS/PO PS/PT TS/TT CP MACH AREA PI .000 0.000 .00004 7.67887 91.182 6.30030 1.270 .833 .949 .602 .5177 185.244 1	STRM FNCT X+Z Y+R PHI CURV PS/PO PS/PT TS/TT CP MACH AREA P1 0.000 .00004 7.67887 91.182 6.30030 1.270 .833 .949 .602 .5177 185.244 1 .01100905 7.67963 81.397 7.24445 1.299 .852 .955 .668 .4834 185.281 1	STRM FNCT X.2 Y.R PHI CURV PS/PO PS/PT TS/TT CP MACH AREA P1 0.000 .00004 7.67887 91.182 6.30030 1.270 .833 .949 .602 .5177 185.244 1 .01100905 7.67963 81.397 7.24445 1.299 .852 .955 .668 .4834 185.281 1 .06201837 7.68154 75.706 3.0536 1.319 .845 .959 .712 .4596 185.373 1	STRM FNCT X+Z Y+R PHI CURV PS/PO PS/PT TS/TT CP MACH AREA P1 0.000 .00004 7.67887 91.182 6.30030 1.270 .833 .949 .602 .5177 185.244 1 .01100905 7.67963 81.397 7.24445 1.299 .852 .955 .668 .4834 185.281 1 .06201837 7.68154 75.706 3.05366 1.319 .845 .959 .712 .4596 185.373 1 .12503664 7.68431 64.08369528 1.326 .870 .961 .728 .4504 185.700 1	XIZ STRM FNCT X.2 Y.R PHI CURV PS/P0 PS/P1 TS/T1 CP MACH AREA P1 000 0.000 .00004 7.67887 91.182 6.30030 1.270 .833 .949 .602 .5177 185.244 1 000 .001 .0.005 7.67963 81.397 7.24445 1.299 .852 .955 .668 .4434 185.281 1 000 .0.620.1837 7.68154 75.706 3.05366 1.319 .865 .959 .712 .4596 185.373 1 0.001 .1250.3668 7.68185 1.326 .870 .961 .728 .4504 185.700 1 0.1250.3668 7.70961 50.285 -1.86015 1.305 .856 .957 .681 .4761 186.730 1	STRM FNCT X+Z Y+R PHI CURV PS/PO PS/PT TS/TT CP MACH AREA P1 0.000 .00004 7.67887 91.182 6.30030 1.270 .833 .949 .602 .5177 185.244 1 0.000 .0000 .00005 7.67963 81.397 7.24445 1.299 .852 .955 .668 .4434 185.281 1 0.05201837 7.64154 75.706 3.05366 1.319 .865 .959 .712 .4596 185.373 1.2503658 7.64441 64.08364528 1.326 .870 .961 .728 .4504 185.700 1 0.25066466 7.70961 50.285 -1.86015 1.305 .856 .957 .681 .4761 186.730 1 0.25011803 7.76164 37.974 -1.17733 1.254 .823 .946 .568 .5353 1899.259 1	STRM FNCT X+Z Y+R PHI CURV PS/PO PS/PI TS/TI CP MACH AREA PI 0.000 .00004 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STORM</th><th> Name</th></t<>	X12 X12 X12 X12 X12 CP MACH MACH APPT 100 8.000 0.000 0.000 7.67963 1.270 .833 .959 .662 .4814 1.000 8.000 0.000 1.000055 7.67963 11.270 .833 .959 .668 .4814 18.000 8.000 .0062 01837 7.67963 1.270 .875 .668 .4814 1.000 8.001 .0062 01837 7.61464 37.236 1.319 .865 .959 .712 .4594 1.000 8.001 .006 01837 7.61464 37.236 1.319 .865 .959 .716 1.000 8.002 .11863 7.61464 37.974 -1.18613 1.256 .959 .966 .4594 1.000 8.002 .11863 7.6146 37.974 -1.18613 .746 .959 .160 8.002 .1186 7.6149 2.8519 -1	Name	Y.R PHI CURV PS/PD PS/PT TS/TI CP MACH AREA PT/PTO 7.67887 91.182 6.30030 1.270 .833 .949 .668 .517 185.244 1.000 7.64154 75.24455 1.319 .465 .959 .712 .4594 1.000 7.64154 75.706 3.05366 1.319 .465 .955 .4594 .4594 1.000 7.64164 75.706 -1.40528 1.376 .470 .961 .4594 1.000 7.64164 37.974 -1.47733 1.256 .957 .458 .957 .1000 7.6164 37.974 -1.47733 1.256 .957 .450 .5735 191.950 1.000 7.6164 37.974 -1.17733 1.256 .957 .490 .5735 191.950 1.000 7.61767 32.246 1.195 .784 .934 .490 .5735 191.950 1.000	Name	Name	Name	Name	KIE STRH FNIT N.Z. 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	_ I O N M O J M N	7394 71185 7152 7152 7152 7153 7151 7153 7153 7153 7153	MACH 1.2770 1.1951 1.1951 1.0528 .8978 .7358 .7358 .7256 .7256 .7266 .7266 .7266
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			CURV 4.46753 2.69528 2.69528 2.02514 3.25756 1.01115 1.01528 1.02339 1.02339 1.02339 1.00525 1.00525
S-' EXT	PHI 39.709 41.361 43.641 42.471 40.637	22.2.2.2.2.2.2.2.2.2.2.2.2.2.2.2.2.2.2	S- EXT 35.091 39.089 40.0886 40.0599 39.097 35.098 24.098 25.098 35.008 35.008 35.008 35.008 35.008 35.008 35.008
CHANNELS	7 • R • 74715 • 75773 • 76781 • 77778 • 40422		Y-R 7-75543 7-75699 7-75699 7-7758 7-7758 7-81935 7-81935 7-84096 7-86695 7-84096 8-13721 8-34400 8-54839 18-54839 18-54839 18-54839 19-72926 13-08153
XII= 16.141	x•Z •03834 •02944 •01052 •01052 •01743	1.06405 1.14762 1.19256 1.32518 1.42038 1.49583 1.49583	X11= 16.152 X Z X Z 04003 04007 02188 021968 011958 01
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S- EXT	H	32.786	29.565	ð.	J.	۲.	₹.	ň.	3	7.	٦,	~•	v.	~	Ŋ	4.0	Φ.	~	ຶ	•		Ţ	0.28	4.64	61.6	8.68	•	75.4	9.70	4.37	7.13	3.97	1.25	7.57	5.23	2.29	0.50	.65	4.334	• 29
CHANNELS	χ•κ	7.76306	.1749	7.78714	1667.	7.61099	7.H3449	7.45767	7.90423	7.95158	•	•	•	8.55HU4	•	9,33682	10.73350	m	-		CHANNEL	× • ¥	7.77013	•	7.79374	•	7.81755	7.84117	•	7.41138	7.95858	8.05630	8.15646	8.3002	8.56230	8.95841	9.33975	J	13.08533	w
XII= 16.164	X•2	0602	• 05295	• 04626	.03965	.03315	.0200	.006ny	02036	04693	09453	-,13713	20770	26788	-,36281	-,43987	79779-	467	-1.04730		A11= 10•176	X • 7	.07175	*6790*	.05822	.05165	.04511	.03153	.01859	00781	0337	08022	-:12254	-19219	25223	3464	.4240	287	• 851	-1.07142
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2	1000	OT A ME	-						,				
X.Z. Y.R. PHI CURY PS/PD PS/PI TSYTI CD PHI CURY PS/PD PS/PI CLITA HACH AREA PHI CURY PS/PI CLITA PS/PI	Ξ.	OINA!E.	XII= 16.187		.s- Ext							٠	
0.0702 7.78640 29.059 .61473 .922 .005 .005 .006 .006 .00702 7.78670 29.059 .61473 .922 .005 .00702 7.78670 29.059 .61473 .935 .914 .917 .0119 .9539 199.591 190.591 17.00549 29.590 .22618 .947 .012 .914 .917 .0119 .9539 199.591 199.592 190.00315 7.487415 29.590 .22618 .947 .013 .914 .917 .9179 29.050 .22618 .947 .013 .914 .917 .9179 29.050 .22618 .947 .9179 .9179 .9170 .9172 .923 .006 .947 .9179 29.050 .924 .917 .9179 29.050 .924 .917 .9179 .924 .917 .9179 29.070 .924 .917 .9179 29.070 .924 .917 .9179 29.070 .924 .917 .9179 29.070 .924 .917 .9179 29.070 .924 .917 .9179 29.070 .924 .917 .9179 .924 .9170 .924 .9170 .9174 .9174 .924 .9170 .924 .9170 .9174 .924 .9170 .9174 .924 .9170 .9174 .924 .9170 .9174 .924 .9170 .9174 .924 .9170 .9174 .924 .9170 .9174 .9170 .9174 .9170 .9174 .924 .9170 .9174 .9170 .9170 .9174 .9170 .9174 .9170 .9170 .9174 .9170 .917	ă	# FNCT	X • Z	Y.R	IHd	CURV	PS/PO	S	11/21	ن ئ	MACH	Æ	T/PT
0.0702 7 7.48470 2.9.049		0.000	.08355	7.77674	28.258	.4147	.922	• 605	Ð	-,173	818	•	1.000
. 0.057.9 7.84615 29.846 - 7.42518 9.947 - 0.21 193 - 0.15		.001	-07702	.7887	59.069	.61858	.941	.617	.871	131	859	•	•
0.0345 7.4474 5.94.86 -77423 .935 .914 .870 -114 .8654 192.320 1.0447 7.4474 5.94.86 -77335 .934 .914 .870 -1144 .8654 192.320 1.03015 7.4476 5.94.86 -7732 .933 .914 .870 -1147 .8655 194.479 1.03015 7.4972 .9472 .943 .913 .866 .947 .916 .867 .117 .8655 194.479 1.00134 7.9473 7.742 .9425 1.001 .861 .848 .017 .7725 199.395 1.00134 7.9413 1.249 .1973 1.0013 .848 .017 .7725 .923 1.99.395 1.00134 .9401 .7725 .923 1.0013 .9401 .1725 .923 .901 .1727 .923 .903 .903 .903 .903 .903 .903 .903 .90		-005	.07033	7.H0058	24.590	w	146.	.621	.873	119	853	•	•
. 0.0335 7.44769 28.328 . 6.934 . 619 . 867114 . 8665 193.4.79 1. 0.0335 7.44769 28.022 . 6242.00 . 624 . 617114 . 8665 194.536 194.53		·00.	.05679	7.82415	29.860	_	.935	·014	.870	145	865	•	•
		.004	.04347	7.84769	29.328	_	. 436	.614	.870	144	865	•	•
02147 7.99749 25-012 31212 923 666 8671171 64774 196-956 1102147 7.94647 27-192 31212 923 666 8671171 64774 196-956 1102147 7.94647 27-194 197-95 10036 6677 9095 1017 7425 210-221 101815 8-16470 7-1044 1024-95 10034 6677 9095 1017 7425 210-221 101815 8-16470 7-10449 7-105 901 1127 7425 210-231 117741 8.46470 17-54901498 1.057 9-91 1127 7425 210-231 101340 19-34256 10-31601498 1.055 9-91 1127 7425 210-531 101340 10-3726 6-65901490 1.055 9-92 0.018 7.742 25-109 101340 10-3726 6-65901490 1.055 9-90 0.127 7742 25-109 101340 10-3726 6-6590142 1.012 6-64 .899 0.028 7.785 538.015 105647 10-3726 6-6590142 1.012 6-64 .890 0.028 7.785 538.015 105647 10-3726 7-3497 25-128 1-61874 523 343 777826 1.264 1.3365 190-588 105647 10-3726 7-3498 7-2591 6-608 399 7.77826 1.3964 190-224 193-016 6-64 1003 7-106 1.201 10-24-10 1003 7-64-10 10		£00•	• 03015	7.87113	29:145	v.	.934	.613	698.	147	866	•	•
06679		-012	.003H5	7.91789	25.012	.31212	.923	.606	.867	171	H77	196.956	1.000
06679		.016	02147	7.46447	27.192	.64240	156.	,624	.874	109	648	199,305	•
-101741 8,36470 17,5449 .19754 1,036 .679 .895 .040 .7640 206.2843 123730 8,56637 15,237 .00545 1,055 .693 .901 .127 .7425 230,538 123731 8,96173 15,234 .00545 1,055 .692 .900 .122 .7448 252,309 123731 8,96173 15,234 .00545 1,035 .679 .895 .079 .7642 276,291 123730 8,56637 15,234 .00545 1,055 1,035 .679 .895 .079 .7642 276,99123731 8,96173 12,304 .00575 1,035 .679 .895 .079 .7642 276,99123730 8,56637 15,234 .00575 1,035 .679 .895 .079 .7642 276,99123731 8,96173 12,304 .00575 1,035 .064 .890 .028 .7785 538,015 124176 13,0464 4,334 .00674 1,021 .664 .890 .028 .7785 538,015 124177 12,461 2,462 .6263 .429 .779 .484 .1264 194,198 124177 17,461 2,746 .2148 1.16187 .575 .377 .486 194,198 124177 17,461 2,746 .2148 1.16187 .575 .377 .487 1.2101 195,370 124177 17,461 2,746 .2148 1.16187 .631 .429 .769 .409 .1094 194,198 124177 17,461 2,746 .2148 .216,198 .7429 .769 .409 .1094 194,198 124177 17,461 2,746 .2148 .2148 .967 .630 .779 .895 .1094 197,198 124177 17,461 2,746 .2148 .967 .631 .896 .709 .709 .210,02424178 17,461 2,746 .2148 .891 .109 .7564 .276,039 .109 .756424178 15,463 .2148 .214824178 15,46324178 15,46424178 15,46424178 15,46424178 17,46424178 17,46424178 17,49424178 18,49424178 17,49424178 17,49424178 17,49424178 17,49424178 17,49424178 17,49424178 17,49424178 17,49424178 17,49424178 17,49424178 17,49424178 17,49424178 17,49424178 17,49424178 17,49424178 17,49424178 17,49424178 17,494241		.023	06679	8.06223	23,655	.42250	1.007	.661	848.	.017	792	204.202	•
		.031	-10815	.1619	21.09B	. 19754.	1.036	679.	.895	080.	764	209.283	٠
2730		2 7 70 0	17741	.3647	17.549	C	1.054	169.	900	,120	745	219,811	•
33171 B. % % 173 12,30801480 1.055 .692 .900 .112 .7448 252.309 1.016891 9.34256 10.516010495 1.021 .649 .899 .112 .7496 274.209 1.01695 1.020 .049 .899 .112 .7496 274.209 1.01695 1.021 .670 .899 .079 .77642 .326.105 1.016 .079 .899 .079 .77642 .326.105 1.016 .079 .899 .079 .77642 .326.105 1.016 .079 .77642 .028 .77642 .326.105 1.016 .079 .77642 .028 .77642 .326.105 1.016 .079 .77642 .028 .7785 .326.105 1.016 .079 .77642 .028 .7785 .327 .028 .7787 .889.761 1.016 .079 .77642 .028 .7787 .028 .7897 1.016 .079 .77642 .029 .7787 .099 .1.2678 191.822 1.016 .079 .7787 .099 .1.2678 191.822 1.016 .079 .7787 .099 .1.2678 191.822 1.016 .079 .7787 .099 .1.2678 191.822 1.016 .079 .7787 .099 .1.2678 191.822 1.016 .079 .7787 .099 .1.2678 191.822 1.016 .079 .099 .1.2678 191.822 1.016 .079 .099 .1.2678 191.822 1.016 .079 .099 .1.2678 191.822 1.016 .079 .099 .1.2678 191.822 1.016 .079 .099 .1.2678 191.822 1.016 .079 .099 .1.2678 191.822 1.016 .079 .099 .1.2678 191.822 1.016 .079 .099 .1.2678 191.822 1.016 .079 .099 .1.2678 191.822 1.016 .079 .099 .1.2678 191.822 1.016 .079 .099 .1.2678 191.822 1.016 .079 .099 .1.2678 191.822 1.016 .099 .1.209 .2.209 .2.209 .1.209 .1.209 .1.209 .1.209 .2.209 .1.209 .1.209 .2.209 .1.209 .1.209 .1.209 .1.209 .1.209 .1.209 .2.209 .2.209 .1.209 .2.209 .1.209 .1.209 .2.209 .1.209 .1.209 .1.209 .1.209 .2.209 .2.209 .1.209 .1.209 .2.209		-062	23730		15,237	. 0056B	1.057	. 693	.901	.127	742	230,538	•
-40891 9.34256 10.51601505 1.050 .689 .899 .112 .7496 274.209 1.051601505 1.050 .679 .895 .079 .7642 362.190 1.054.7 10.0474 1.036 .679 .895 .049 .785 318.015 1.054.7 15.41967 2.59200182 1.012 .664 .890 .028 .7876 888.761 1.054.7 15.41967 2.59200182 1.012 .664 .890 .028 .7876 888.761 1.054.7 1.054.9 19.757956 1.3365 190.588 1.054.7 1.075 7.78485 25.128 1.61874 .523 .343 .757956 1.3365 190.588 1.075 7.78485 25.128 1.61874 .523 .343 .757956 1.2249 199.822 1.075 7.78485 25.128 1.05487 .523 .343 .757956 1.2249 199.828 1.075 7.78485 25.258 1.19161 .557 .377956 1.2249 199.828 1.075 7.78485 25.258 1.19161 .557 .462 .462 .462 .462 .462 .462 .462 .462		750.	-,33171	8,96173	. 4	01480	1,055	259.	. •	.122	744	252,309	1.000
Total		.125	16807	9,34256	0	01505	1.650	.644	0	.112	.7496	274.209	1.000
X11= 16.211 CHANNELS- EXT X13= 16.211 CHANNELS- EXT X25 Y+H X25 Y+H X25 Y+H X25 Y+H X25 X-106		. 25¢	61340	10.73720	·	00975	1.036	629	o	620	.7642	362,190	1.000
XII= 16.211 CHANNELS- EXT XII= 16.221 CHANNELS- EXT XII= 16.221 CHANNELS- EXT XII= 16.221 CHANNELS- EXT XII= 16.221 CHANNELS- EXT XII= 16.221 CHANNELS- EXT XII= 16.221 CHANNELS- EXT XII= 16.221 CHANNELS- EXT XII= 16.221 CHANNELS- EXT XII= 16.221 CHANNELS- EXT XII= 16.221 CHANNELS- EXT XII= 16.221 CHANNELS- EXT XII= 16.221 CHANNELS- EXT XII= 16.221 CHANNELS- EXT XII= 16.221 CHANNELS- EXT XII= 16.221 CHANNELS-		.500	407EH.	0864	4.33H	00474	1.021	.670	0	.048	.7785	538.015	1.000
X11= 16.211 CHANNELS- EXT X		• 00	-1.05607	961×°	2.592	00182	3	* 99*	σ	.028	.7876	888,761	1.000
FNCT X.2 Y.H PHI CURV PS/PO PS/PT TS/TT CP HACH AREA PT/ .000 .10775 7.788H5 25.128 1.61874 .523 .343 .737 -1.064 1.3365 190.588 1. .002 .09552 7.n1401 27.066 1.19161 .575 .377 -950 1.2678 191.822 1. .004 .04275 7.n4401 27.056 1.19161 .575 .377 -950 1.2678 191.822 1. .005 .04275 7.n4401 27.951 .74204 .608 .399 .769 -876 1.2249 193.016 1. .006 .0700 7.n4525 28.240 .55315 .653 .459 .806 -635 1.0984 194.198 1. .007 .016 .01301 7.93319 26.551 1.16053 .715 .469 .806 -635 1.0984 197.718 1. .016 .01047 7.98056 22.473 .514602 .821 .539 .838 -400 .9434 200.086 1. .017 .01047 7.98056 22.473 .51308 .967 .662 .8878 -607 .7908 210.024 1. .018 .01047 7.98056 22.473 .00542 1.049 .668 .899 .109 .7526 .252.468 1. .007 .007 .0052 .00572 1.049 .688 .899 .109 .7526 .252.810 1. .0042107 8.97061 12.33300572 1.049 .688 .899 .109 .7534 .274.655 1. .00425107 8.97061 12.33300572 1.049 .688 .899 .103 .7534 .274.655 1. .00425107 8.97061 2.33300572 1.049 .688 .899 .103 .7534 .274.655 1. .00425107 8.97061 2.33300572 1.049 .688 .899 .103 .7534 .274.655 1. .009427407 10.0451 1.0017 1.0012 .664 .890 .027 .7759 .888.94 1. .00079641 2.01777 16.42141 2.596 .00177 1.012 .664 .890 .027 .7757 .7759	COOF	ROINATE	= 16.21		ند. ا						*		
000 10775 7.788H5 25.128 1.61874 .523 .343 .737 -1.064 1.3365 190.588 1.200 19757 -950 1.2678 191.82	STR	FNCT	•	2	PHI	CURV	S	PS/PT	15/11	á	MACH	P.E	
1002 .09552 7.n1401 27.066 1.19161 .575 .377 .757950 1.2678 191.922 1.004 .004 .004 .399 .769974 1.2249 193.016 1.004 .004 .004 .399 .777924 193.016 1.004 .005 .005 .005 .005 .005 .005 .005		00000	.10775	. 78KH		1.61874	.523	.343	151.	-1.064	1.3365	58	
.004 .0H275 7.H3830 27.951 .74204 .608 .399 .769874 1.2249 193.016 18.006 .0700 7.H6225 28.240 .630 .413 .777826 1.1984 194.198 18.006 .0700 7.H6225 27.882 .630 .413 .777826 1.1984 194.198 18.008 .05730 7.H6595 27.882 .6331 .429 .785774 1.1701 195.370 18.008 .05730 7.H6595 27.882 .821 .639 .806635 1.0984 197.718 18.008 .001047 7.94056 24.353 2.14602 .821 .639 .808400 .9434 200.086 18.001047 7.94056 22.473 .63318 .967 .634 .878073 .8331 204.979 12.001 .0024 .0027 .7908 210.024 197.718 17.416 .07783 1.038 .662 .889 .109 .7529 231.131 13.0024 .231.731 12.33300572 1.049 .687 .899 .109 .7529 231.131 13.0024 .259 .36804 9.35016 10.54701091 1.046 .686 .898 .103 .7534 274.655 13.00912 1.021 .670 .895 .077 .7534 218.251 1.021 .670 .895 .047 .7790 538.266 13.00079683 13.08951 4.34900451 1.012 .664 .899 .027 .7790 538.266 13.00079683 13.08951 4.34900451 1.012 .664 .890 .027 .7790 888.944 13.000 -1.0177 16.8214 2.559		- 005	.09552	. 1140		1.19161	.575	.377	.757	950	1.2678	92	•
.006 .07000 7.46225 28.280 .56315 .653 .429 .777826 1.1984 194.198 1008 .05730 7.48595 27.482 .82341 .653 .429 .785774 1.1701 195.370 1012 .03301 7.93319 26.551 1.16053 .715 .469 .806635 1.0984 197.718 1012 .03301 7.93319 26.551 1.16053 .715 .469 .806635 1.0984 197.718 1013 .01047 7.98056 24.353 2.14602 .821 .821 .831 2.04.979 1023 .033046 8.07756 22.473 .63308 .967 .652 .889 .020 .7908 210.024 1024 .047 .13742 8.37717 17.416 .07743 1.038 .681 .896 .104 .7529 231.131 1052 .19584 9.35016 10.54701091 1.049 .688 .899 .109 .7520 252.810 112536804 9.35016 10.54701091 1.024 .679 .895 .103 .7534 2754 255.810 125057343 13.08951 4.34900452 1.012 .670 .895 .047 .7790 538.266 1250176613 13.08951 4.34900457 1.012 .664 .890 .027 .7878 888.944 1.		*00°	. CH275	7. H3830		.74204	879	999	.769	874	1.2249	0	•
.008 .05730 7.8859 27.882 .82381 .653 .429 .785774 1.1701 195.370 1012 .03301 7.93319 26.551 1.16053 .715 .469 .806635 1.0984 197.718 1016 .01047 7.98056 24.353 2.14602 .821 .539 .838400 .9834 200.086 1016 .01047 7.98056 24.353 2.14602 .821 .634 .878073 .8331 204.979 102303086 8.07756 22.473 .63308 .967 .662 .889 .020 .77908 220.468 102413782 8.37717 17.416 .07783 1.038 .681 .896 .104 .7529 231.131 105219584 9.35016 12.53300572 1.049 .688 .899 .109 .7529 231.131 112536804 9.35016 10.54701071 1.021 .679 .895 .077 .7506 252.810 125057343 10.74207 6.88100912 1.021 .670 .895 .077 .7790 538.266 125079683 13.08951 4.34900451 1.012 .664 .890 .027 .7878 888.944 1.		900	00029	7,46225		.56315	.630	.413	1117	-,826	1.1984	67	•
.012 .03301 7.43319 26.551 1.16053 .715 .469 .806635 1.0984 197.718 11.012 .016 .01047 7.98056 24.353 2.14602 .821 .539 .838400 .9434 200.086 11.023 .831 8.0756 22.473 .8314 .967 .634 .878073 .8331 204.979 11.003 .662 .869 .020 .7908 210.024 11.004 .662 .869 .1065 .7517 7.416 .07783 11.038 .641 .896 .106 .7529 231.131 11.005 .7510 .652 .899 .109 .7529 231.131 11.005 .7510 .899 .109 .7529 231.131 11.005 .7510 .899 .109 .7529 231.131 11.005 .7510 .899 .109 .7524 .7510 .7510 .7524 .7510 .7510 .7524 .7510 .7524 .7510		900.	.05730	7. hH595		.82381	.653	424	. 785	774	1.1701	37	•
.016 .01047 7.98056 24.353 2.14602 .821 .539 .838400 .9434 200.086 11.023		-012	.03301	7,43314		1,16053	. 517.	695.	908.	-,635	1.0984	7.	•
.02303086 8.07756 22.473 .63388 .967 .652 .889 .020 .7908 210.024 1.004 .052 .889 .020 .7908 210.024 1.004 .052 .889 .020 .7908 210.024 1.004 .052 .889 .020 .7908 220.468 1.0052 .1968 .896 .085 .7615 220.468 1.0052 .1968 .899 .109 .7529 231.131 1.00423107 8.97061 12.33300572 1.049 .688 .899 .109 .7506 252.810 1.02536804 9.35016 10.54701091 1.046 .686 .898 .103 .7534 274.655 1.02057343 13.08951 4.34900412 1.021 .670 .892 .047 .7790 538.266 1.000 -1.0177 16.82141 2.59600177 1.012 .664 .890 .027 .7878 888.944 1.000	•	.016	.01047	7.98056		2.14602	158.	.539	.838	007	98H9.	604	•
.04713742 8.37717 17.416 .07783 1.038 .681 .896 .026 .7908 210.024 1. 00413742 8.37717 17.416 .07783 1.038 .681 .896 .085 .7615 220.468 1. 00519684 8.57734 15.200 .02542 1.047 .688 .899 .104 .7529 231.131 1. 00424107 8.97061 12.33300572 1.049 .688 .899 .109 .7506 252.810 1. 12536804 9.35016 10.54701091 1.046 .686 .898 .103 .7534 274.655 1. 25057343 10.74207 6.88100912 1.034 .679 .895 .047 .7790 538.266 1. 25079683 13.08951 4.34900451 1.021 .670 .892 .047 .7790 538.266 1. 000 -1.01777 16.82141 2.59600177 1.012 .664 .890 .027 .7878 888.944 1.		.023	03086	8.07756		.63308	. 967	.634	.87A	073	.8331	6	•
.047 13742 8.37717 17,416 .07783 1.038 .681 .896 .085 .7529 .231,131 1.052 .052 1968+ 8.9761 12,333 00572 1.049 .688 .899 .109 .756 .252,810 1.049 .094 24107 8.97661 12,333 00572 1.049 .688 .899 .109 .7506 .252,810 1.056 .125 36804 9.35016 10,547 01091 1.046 .686 .898 .103 .7534 .274,655 1.0564 .365,455 .362,515 1.0564 .895 .077 .7654 .362,515 1.0564 .899 .047 .7790 .538,266 1.0564 .899 .047 .7790 .538,266 1.057 .7878 .888,944 1.012 .664 .899 .027 .7878 888,944 1.0		.031	12070-	8.17636		.27677	•	.662	8.89	.020	8062	92	•
.0621968+ 8.57734 15.200 .02542 1.047 .687 .898 .104 .7529 231.131 109424107 8.9764 12.33300572 1.049 .688 .899 .109 .7506 252.810 112536804 9.35016 10.54701091 1.046 .686 .898 .103 .7534 274.655 125057343 10.74207 6.88100912 1.034 .679 .895 .077 .7654 362.515 150079683 13.08951 4.34900451 1.021 .670 .892 .047 .7790 538.266 1000 -1.01777 16.82141 2.59600177 1.012 .664 .890 .027 .7878 888.944 1.	•	250.	137A2	8.37717	•	.07783	•	.641	968°	.085	.7615	46	•
.09423107 8.97061 12.33300572 1.049 .688 .899 .109 .7506 252.810 112536804 9.35016 10.54701091 1.046 .686 .898 .103 .7534 274.655 125057343 10.74207 6.88100912 1.034 .679 .895 .077 .7654 362.515 150079683 13.08951 4.34900451 1.021 .670 .892 .047 .7790 538.266 1000 -1.01777 16.82141 2.59600177 1.012 .664 .890 .027 .7878 888.944 1.		.062	1968*	8.57738	Ġ	.02542	. •	.687	868.	.104	. 7529	5	٠
.12536804 9.35016 10.54701091 1.046 .686 .898 .103 .7534 274.655 1. .25057343 10.74207 6.88100912 1.034 .679 .895 .077 .7654 362.515 1. .50079683 13.08951 4.34900451 1.021 .670 .892 .047 .7790 538.266 1. .000 -1.01777 16.82141 2.59600177 1.012 .664 .890 .027 .7878 888.944 1.		760.	24107	8.97061	N	00572	•	.68B	668	601.	. 7506	8	•
.25057343 10.74207 6.88100912 1.034 .679 .895 .077 .7654 362.515 1. .50079683 13.08951 4.34906451 1.021 .670 .892 .047 .7790 538.266 1. .000 -1.01777 16.82141 2.59600177 1.012 .664 .890 .027 .7878 888.944 1.		. 125	-,36804	9.35016	ં	01091	•	.686	868	103	.7534	65	•
.50079683 13.08951 4.34906451 1.021 .670 .892 .047 .7790 538.266 1. .000 -1.01777 16.82141 2.59600177 1.012 .664 .890 .027 .7878 888.944 1.		.250	5734	0	•	00912	•	629	908	.077	.7654	15	•
.000 -1.01777 16.42141 2.59600177 1.012 .664 .890 .027 .7878 888.944 1.		.500	196 B	13.08951	•	06451		9	268*	140.	.1790	26	•
		00.	0	o	•	00177	1.012	.664	068	.027	87	8.94	1.000

SUB

IDENT= NASA INLET CONFIGURATION NO. 8

٠.																	•															,		
	PT/P10	1.000	1.000	1.000	000.1	1.000	1.000	1.000	1.000	0000	1.000	0000	1.000	1.000	1.000	1.000		P1/P10	1.000	1.000	1.000	1.000	1.000	7.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	7.000	• • • • • • • • • • • • • • • • • • • •
	AREA	191.129	192,363	193,608	196.089	198.571	201.036	206,000	211.036	221,391	231,978	253,533	275,303	362,989	538,631	889.213		APEA	191.634	192.858	194.068	196.556	160.661	201.506	206.489	211.529	221.854	232.410	253.904	275.638	363.234	538.851	689.349	
	MACH	.8433	.8402	.8609	.9027	.9259	.9195	9298.	.6248	. 7836	.7679	. 7592	.7590	.7673	1611.	.7880		MACH	.9526	.9311	.9185	.9136	.9149	1506	.8759	.8365	. 1935	. 7747	.7632	.7617	1.891	.7800	.7882	
	G)	960	089	135	226	277	263	149	055	• 036	.071	060.	.091	.073	.045	.027		G G	334	288	261	250	-,253	240	168	085	•014	•056	-082	• 085	.071	770.	• 026	
	15/11	.875	.876	.871	.860	.854	.855	. 869	0 K B •	168	. 895	168	.897	.895	.892	068.		15/11	.846	.852	.656	857	.857	.858	.867	.877	.888	.893	968.	968.	966.	892	.889	
	PS/PT	. 628	.630	.616	290	.575	.579	.612	079.	199.	.677	6H3	.643	.677	699.	.064		PS/PT	.558	.571	.579	.583	.582	.545	.607	.631	099	:672	.680	180.	.677	699	• 664	
	PS/PO	.957	.960	076.	658.	. B76	. A42	. 633	. 975	1.016	1.032	1.041	1.041	1.032	1:020	1.012		PS/PU	.850	.871	.883	•889	.887	-892	.925	-962	1.006	1.025	1.037	1.038	1.032	1.020	1.012	
	CURV	1.13630	-,63799	87478	61129	-,18310	.36131	. 51864	.32790	12921	.05262	.00663	P.00484	00820	00417	00170		CURV	.80286	96819.	.27012	03441	.02637	.17856	.39136	.32873	.15138	.06383	• 01225	00195	00776	00402	00167	
S- EXT	IHd	23,126	21,379	20.596	20,116	20.320	20.749	20.654	19.550	17,065		ŝ		¢		2.601	S- EXT	IHA	21.682	•	÷	ے	ė	•	ċ	ċ	å	•	•	•	•	•	•	
CHANNELS-	Y.R	7.79989	7.82503	7.45030	7.40045	7.95329	0 7 0 0 0 to 0	H. J9765	8.19602	H. 35470	A.5730A		9,35117	10.74910	13,09345	16.62345	CHANNELS	ו	7.81018	7.H3509	7.86004	7.90984	7.95956	A-00884	8-10725	8.20560	8.40348	8.50108	8.99001	9.36687	10.75271	13.09626	16.82524	
XII= 16.234	χ•2	.13245	12216	11257	\$1660.	.07571	70750	10020	0163a	04134	13eru	23245	30896	51536	-, 73850	96182	XII= 16.258	X • Z	.15748	.14765	13797	.11894	.10047	* 08204	•0400•	.01100	05259	95H01	20230	27443	48553	70827	93339	-
COOPDINATE	STRM FNCT		200.	* 00 *	900.	. 210.	.016	.023	.031	.047	590.	760	.125	.250	.500	1.000	COOPDINATE.	TRM- FINCT	0000	-005	700.	600	-015	.016	•023	.031	. 250	-062	460.	.125	.250	. 500	1.000	;
STATION C		000.	8.001	8.00Z	400° 8	9000	B.00A	A.012	6.016	P.023	8.031	8.047	6.063.	8,125	A 250	A.500	STATION C	x 12 S	.000	.003	F. 002	8.004	.900°	8.008	8.012	8.015	8.023	8.031	6.047	H.Ch3	8.125	8.250	6.500	

NASA INLET CONFIGURATION NO. 8

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SUB.

SUB

MACH	1.1737	1 • 1 3 3 3	1.1018	1.0793	1.0267	.9228	.8738	.8235	.7961	.7775	.7715	.7714	. 7815	. 7887
g C	780	704	642	597	065-	270	163	052	+00 •	•050	• 063	.063	.041	• 025
15/11	.784	. 796	-805	-83	958.	.854	868	.881	- BB7	-892	.894	968	.891	688.
PS/PT	124.	グラフ・	197	.480	.512	.577	800.	. 641	.657	.671	.675	.675	. 668	.663
PS/P0	.650	.685	.712	.732	.780	.875	. 427	. 977	1.002	1.022	1.028	1.028	1.018	1.011
CURV	.53785	•48264	.36765	.33889	1.13237	.58307	.34785	81621°	69660.	*******	26800	00648	00340	00154
i I	18.558	18.944	18.931	18,725	17.735	17.552	17.109	15.843	14.467	12.189	10.559	994.9	4.393	2,613
۲. ج	7.83796	7.88883	7.93904	7.98885	8.03847	A-13732	8.23568	6.43209	8.62762	9.0124H	9.34640	10,76541	13,10425	16.82987
X • Z	.23376	.21655	19926	.14205	•16556	•13469	.10322	26770.	00806	(13×89	173H1	-,34128	60404	H3174
STRM FNCT	000.0	+00+	•008	-012	•016	.023	.031	1.00	.062	440.	.125	.250	.500	1.000
	8.000	8.002	8.004	A.006	80.08	A.012	8.016	8.023	6.031	F.047	8.063	8,125	H. 250	8,500
	. ,					1	8	3						

SUB.	•										•					SU8	i ·						:								:	
·	PT/PT0	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000		PT/PT0	1.000	1.000	1.000	1.000	1.000	1.000	000-1	1.000	1.000	1.000	1.000	1.000	1.000	1.000	
•	APEA	193,415	195.924	198.441	200.965	203,490	208.551	213,633	223,925	.34*388	255.669	277.239	364.435	539.738	890.036		APEA	193.617	196,125	198,638	201,156	203,682	208,748	213.836	224.131	234.588	255.852	277.407	364.564	539.836	890-111	
	HACH	.7723	.7923	.8599	.9225	-9445	9916*	.8808	.8319	. 8054	. 7824	67120	.7725	.7821	.7889		MACH	.9501	1976.	6696	.9912	.9691	9116.	.8822	.8356	.8088	.7848	.1765	.7731	.7823	.7889	
	3	.061	.017	132	269	316	261	178	071	012	•039	• 056	190.	040.	.025		9	329	320	-,371	416	-,369	245	182	079	019	• 634	•052	• 060	•039	• 022	
	11/51	.893	.888	.871	.855	678.	.856	.866	.878	•8A5	169.	.893	.893	.891	. 889		15/11	.847	848	.842	.836	-842	.858	.865	.877	.8A4	068.	-892	.893	.891	688	
	PS/PT	419.	661	219.	.577	.563	574	• 004	•635	.652	199.	.672	•674	.668	.663		PS/PT	.559	.562	.547	.534	.547	584	.603	.633	.650	• 666	.671	•674	R99.	.663	
	PS/PO	1.027	1.008	.941	.879	858.	EHB.	.920	896.	566.	1.017	1.025	1.027	1.018	1.011		PS/P0	.853	158.	. 834	418.	. 835	9 9 9	616.	. 965	.991	1.015	1.023	1.027	1.018	1.011	
	CURV	•42414	-1.10507	-1.43091	78040	05304	.38032	.31418	.18201	.10597	• 03454	.01257	00606	00319	6+100		CURV	.45174	24346	46702	13111	.15274	.26377	.28215	18196	.10787	•03694	01410	00575	00308	00147	-
S- EXT	PHI	17.788	17.211	16.876	16.708	16.689	16.580	16.410	15.439	14.230	12.115	10.534	6.991	4.401	2.617	S- EXT	PHI	17.446	17,483	17,463	17,051	16.524	16,327	16.169	15.287	14.138	12.084	10.522	4.986	4.403	2.618	
CHANNELS-	¥•R	7.84639	7.89712	7.94769	7.99808	8.04816	8.14763	8.24630	. R.44261	8.63760	9.02119	9.39404	10.77048	13.10740	16.83174	CHANNELS-	Y.R	7.85049	7.96118	7,95163	8.00188	8.05195	8,15147	8.25023	8.44649	8-64128	9-02443	9.39688	10.77238	13.10859	16.83244	-
STATION COORDINATE, XII= 16.352	X • Z	.25947	.24343	.22785	*515*	.19720	.16774	.13851	. 68255	• 03045	05846	13283	33987	56303	-,79082	XII= 16.363	X+Z	.27237	.25639	.24055	.22488	. 209FB	.18075	.15195	.09668	•04554	04334	11752	32434	54765	77537	
DORDINATE,	STRM FNCT	0.000	,004	÷009	.012	.016	.023	•031	1,047	• 062	•60•	.125	• 250	.500	1.000	COORDINATE.	STRM FNCT	00000	700	.003	-012	910.	.023	.031	.047	÷062	750.	.125	•250	. 500	1.000	
STATION CO		8.000	8.002	8.004	900.8	8.008	6.012	8.016	8.023	8.031	8.047	•	٠1۶	•	8,500	STATION CO	X12 S.	B.000	8.002	9.004	8,006	8008	8.012		8.053	8.031	8.047	8.063	8.125	8.250	8.500	

CONFIGURATION NO.

(DENT=

PT/PT0 00000 AREA 193,815 196,328 198,854 201,384 201,384 214,090 224,389 224,389 234,840 256,085 257,620 364,727 890,206 AREA 194.575 197.097 199.624 202.155 AREA 195.295 197.829 200.366 202.907 210.556 215.683 226.443 226.443 227.992 279.017 365.813 9905 9707 9543 9420 18CH 9661 9571 9571 9571 9577 9058 8882 8882 8573 17904 77904 CP • 373 • 338 • 311 841 841 846 846 849 849 5/PT .534 .546 .557 .557 5/P0 -814 -833 -849 -861 98.63 98 CURV .08651 .08651 .04082 .06088 .06088 .16166 .25644 .18022 .18022 .11042 .016014 .016014 CURV -22860 -11049 -23038 -10926 -17821 -17821 -17821 -17821 -15408 -05394 29260 29260 32425 21663 20928 PHI 15.991 15.856 15.856 15.856 5.596 PHI 55.206 56.206 56.173 56.109 76.200 76.20 EXT CHANNEL S-CHANNEL CHANNEL Y•R ••86989 ••92073 ••97133 1•02172 7.8 7.85451 7.95526 7.95595 8.00640 8.05662 8.25512 8.4592 9.00253 9.1010 7.88443 7.93543 7.93543 7.98615 8.03662 8.03662 8.481871 XII= 16.375 = 16.469 XII= 16.422 33718 32263 30819 29397 .34160 .34796 .33430 .28213 .28213 .18355 .183562 .10198 .17430 26986 255497 24029 22594 19726 116896 06405 06405 09804 52807 75585 STATION COORDINATE. 0.000 .250 .509 .750 COORDINATE COORDINATE 8 .000 8 .000 8 .000 8 .000 8 .000 8 .000 STATION STATION 8.016 8.023 8.023 8.047 8.063 8.125 8.250 8.008

NASA INLET CONFIGURATION

IDENT=

AREA 199.143 204.283 209.431 219.771 240.601 261.669 262.897 368.990 543.233 196.651 201.756 205.876 212.005 217.148 227.496 227.496 259.020 289.364 366.886 541.608 AREA 203.437 224.245 224.694 245.175 266.233 373.045 546.398 MACH 9961 9776 9776 8964 89775 8953 7917 7917 4ACH 9515 9343 9343 99175 9062 8669 8168 8168 8168 7827 4ACH 9220 9220 8957 8841 8736 8553 8668 7952 CP 2332 11111112338 1101111148 0033 858 858 862 862 868 868 876 876 876 888 7.2. 9.2. 9.2. 9.2. 9.2. 9.2. 9.3. 5777 586 594 601 608 620 629 629 57 PT 55 PT 888 888 889 905 927 945 959 0.00 P. 0.00 P CURV 14149 14969 14175 14175 111962 009942 00008 00008 06332 06048 05906 05455 05657 01583 01583 05575 05575 05575 05537 05691 05691 05691 05691 05691 2.603 2.653 2.285 2.285 3.264 3.264 2.653 2.653 PHI 0.371 0.182 9.766 9.766 9.028 8.524 6.688 CHANNELS- EXT CHANNEL 8.21482 8.31386 8.50966 8.50966 8.70256 9.08012 9.44684 10.6664 13.13009 7.96173 8.06382 8.16480 8.36393 8.75133 9.1260H 9.46941 10.8375H 8.04711 8.25004 8.44864 8.64324 8.63412 9.20509 9.56484 STATION COORDINATE, XII= 16.563 XII=.16.750 . 09235 . 09235 . 09231 . 09306 . 93006 . 93006 . 93006 . 93006 . 93006 . 93006 . 93006 . 93006 . 93006 . 93006 . 93006 70469 68179 65941 51691 53762 46486 STRM FHCT 0.000 0.000 0.006 0. STATION COORDINATE. STRM FNCT 0.000 0.008 0.016 0.023 0.047 0.052 0.052 0.052 STATION COORDINATE 578# FNCT 0.000 0.001 0.052 125 125 187 187 180 180 180 180 8.016 8.008 8.612 8.023 8.047 8.047 8.063 8.125

SUB		SUB			i .	•. 1 •	SUB	
	71/P100000000000000000000000000000000000		1.000				1.000	74/74 1.000 1.000 1.000 0000 0000
	AREA 216-203 226-742 237-294 258-434 279-621 300-853 386-160 558-101		AREA 218.668 229.242	239.824	303.489 303.489 386.830 560.674	00000	8575-163 11364.950	AREA 223.167 233.774 265.638 308.217 393.656 565.421
4	MACH .8931 .8835 .8836 .8751 .8677		.8821 .8787	.8763	. 8613 . 8613 . 8733	2	.8001	8724 8699 8634 8634 8639
	CP CP CP CP CP CP CP CP CP CP CP CP CP C		CP 181	-169			000	CP
	75/11 . 862 . 865 . 865 . 867 . 871 . 876		15/11 • 865 • 866	.868 .868	. 875 . 881		689. 788.	. 868 . 869 . 869 . 870 . 872 . 872
	PS/PT • 5596 • 500 • 600 •	, ,	PS/P1 .603	909	628	• • • • • • • • • • • • • • • • • • •	• • • • • • • • • • • • • • • • • • •	75/7 1000 1000 1000 1000 1000 1000 1000 10
	95/P0 . 9918 . 9917 . 9926 . 933 . 9450		.919	924	957	1.000		PS/P0 .928 .931 .937 .957
	CURV .02352 .02447 .01992 .01758 .01758		CUKV •01426	.01836	.01047		0000000	CURV • 01201 • 01271 • 01036 • 01022 • 00925
S- EXT	6.530 6.320 6.320 6.320 5.023 5.008	S- EXT	PHI 6.018 5.932	5.405 5.660	0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.0	00304 00000	.331 .263 S- EXT	PHI 5.328 5.203 4.939 4.031 4.130
CHANNELS	Y.R 8.29575 8.49554 8.69097 9.06984 9.43431 9.78593 11.08687	CHANNELS	Y+R 8.34292 8.54226			2.5841 2.8841 2.3840 2.9135	52.24518 60.14629 CHANNELS	7.8 8.42431 8.62627 9.19539 9.40498 11.19395
XII= 18.625	X;Z 2.84284 2.82014 2.75689 2.75689 2.56246 2.56246 2.56035	XII= 19.000	4,2 3,27325 3,25243	3.23216		2235 1736 1736	Z.10940 Z.06866 XII= 19.750	7.2 4.1350 4.06632 4.06690 3.50839
COORDINATE.	STRM FNCT 0.000 0.031 0.62 1.25 1.25 1.87 1.000	STATION COORDINATE.	STRM FNCT 0.000	000	9000 9000 9000	37.0	• 141	STRM FACT 0.000 031 125 125 1.000
STATION CO	8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8	STATION C	× 12 000 000	03	6 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6	2 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	14.000 16.000 STATION CC	8.000 8.000 8.000 8.031 8.063 8.125
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	IDENT = NASA INLET CONFIGURATION NO. 8		
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	PT/PT0	9	00.	90	00.	.00	.00	00.		PT/P10	90	00	1.000	00.	00.	00.	00.	900	9	0	0	ခ		•	191	00.	9	0	8	9	00.	00	8	0	00	1.000	00	
	AREA	•		•			569.686	•	- -	ARFA	ž	276.927	319,654	405.293	577,082	922,136	615	900	809°66E+	5793,516	8582,176	37			AHEA	244.930	87	0	Ð	AD.	~			407	_	8588.903	~	
	MACH	.8654	.8640	.8598	.8535	.8435	.8297	.8160		MACH	.8618	.8563	.8517	.8441	.8334	.8207	.8097	.8039	.8022	.8014	00	00	-		MACH	.8555	.8513	.8478	.8421	.8337	.8233	.8132	.8060	.8035	.8024	6	6008	
	٠.	_	141	132	7	960"-	066	035		d)	137	-125	-,114	860		-,046	-,022	600-	005	003	002	•			<u>م</u>	-,123	114	-,106	-,093	-,075	-,052	-,029	013	800	-, 005	003	002	
	11/21	.870	.870	.871	.873	.875	61R*	. 8P.2		11/51	.871	.872	.873	.875	.878	.881	. 8A4	.886	.886	988.	8P6	.886		,	11/51	.872	.873	.874	.876	.878	.681	.883	.885	.886	.886	.886	• 886	
•	PS/PT	.614	•614	.617	.621	.628	.637	.046		PS/PT	9	5	.622	.627	.634	40	65	•654	•655	. 655	•656	• 656			PS/PT	.620	.623	. 625	629.	.634	.641	149.	.652	•654	.654	. 655	•655	
	PS/PO	. 935	.937	.941	. 947	.957	176.	986		PS/PO	666	776	676	956	.967	616.	066	966.	866	666	666	1.000			PS/PO	5965	676	.953	.958	. 967	116.	.987	766	966	866	666	666	
	CURV	.0100	08700.	. 00942	.00863	•00748	• 00555	.00266		CURV	.00777	.00700	.00653	.00573	.00452	.00308	.00134	-00042	.00021	-00012	500000	.00003			CURV	• 100619	•00539	. 00505	.00448	.00365	• 00256	.00147	•00028	.000030	.00018	80000	50000	
S- EXT	PHI	4.779	4.768	4.445	4.156	3.705	3.055	2*5*5	S- EXT	III	•		3,395				•	.780	.567	.450	325	. 260	S- EXT		PHI		•	2,236	•	•	•	•	.675	. 513	614.	.311	152	
CHANNELS-	¥ .	8.50451	8.70117	9.26667	9.47216	11.25451	13.46613	17.06605	CHANNELS	Y•R	8.63543	9.38875	10.08708	11,35807	13,55327	17,13257	22,67552	30.93494	37.42244	433	52,26654	,1632	CHANNELS		Y . R	.8296	69695.6	10.25723	11,51151	13,68395	17,23578	22,74906	30,98164	37,45716	42,97134	52,28702	60.17973	
x11= 20.500	X • Z	4.99761	4.94117	4.93554	4.84270	07762.7	4.65487	4.49805	XII= 22.000	X.2	6.72459	6.67496	.6321	6,56092	45444	6,31573	6,16016	6.01697	5.94043	5.89223	5.82976	5.78973	XII= 25.000	٠	Z•X	5	٦.	10,12315	٦,	10.00668	9.91251	60661.6	9.6810H	9.61405	9.56960	.510	9.47234	
COORDINATE. XII=	•	000.0	•016	- 062	.125	• 520	•500	1.000	COORDINATE.	STRM FNCT	000.0	700	.00B	.016	.031	-062	.125	.250	.375	.500	.750	1.000	COORDINATE.		STRM FNCT	000.0	*00*	.008	910.	.031	- 062	.125	.250	375	. 500	.750	1.000	
STATION C	X12	00.	90.	.03	• 06	٠١٤	8.250	• 50	STATION CO	x 12 S	03	.03	8,063	77	25	50	00.	00.0	00.	ς.	00	6.00	STATION C	7	x 12 S	о В	9	્	~	ď	ŝ	9	9	٠,	2.00	٥.	Ð	

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	71111111111111111111111111111111111111	100000		# T T T T T T T T T T T T T T T T T T T	•
÷	AREA 251.580 294.430 337.330 423.553 940.834 1633.647 3023.102 4414.992 5807.943	AREA 254-469 297-803 341-138 427-817	948.248 1642.970 3034.069 4426.447 5619.476 6606.481	AREA 254.469 298.021 341.573 428.676 602.883 951.296 1648.119 3041.759 448.119 3041.759 448.119 11403.615	
	MACH . 8517 . 84475 . 84475 . 8304 . 8217 . 8029 . 8029	MACH . 8157 . 8156 . 8156	8087 8054 8039 8030 8022	# # # # # # # # # # # # # # # # # # #	
	CP (CP (CP (CP (CP (CP (CP (CP (CP (CP (6,00000	111111	### CP	ENTUM FLUX
	75/ 678. 678. 678. 687. 688. 688. 688. 688.	15/11 .883 .883 .883		\$	甘.
	PS/PT PS/PT	PS/PT	6 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	7.7.2 4.80.	T0T
	PS/P0 9499 9499 9499 9499 9499 9499	04/86 04/86 04/86 04/86 04/86 04/86	88.1.00000 00000000000000000000000000000		•
	CURV 00586 00597 00529 00529 00511 000124 000126 00010	CURV .00000 .00012 .00028	.000033 .000033 .000014 .00006	NOOOOOOOOOOOOOOOOOOOOOOOOOOOOOOOOOOOOO	· ·
S- EXT	PH1 1.386 1.256 1.202 1.012 1.		250 250 250 250 250 250	PHI 0020 0020 0036 0036 0036 0036 0036 0036	•
CHANNELS-	Y.R 8.94877 9.68090 10.36221 111.60714 13.76746 17.30540 22.80364 31.62669 37.48781 42.99681 52.30632	CHANNELS- Y.R 9.00000 9.73620 10.42053 11.66954 13.83385	17.37345 22.86861 31.07691 37.53641 43.03948 52.34050	Y+R 9-00000 9-73976 10-42717 11-64126 13-85293 17-40135 22-90442 31-11626 31-11626 31-11626 31-11626 31-11626 31-11626 31-11626 31-11626 31-11626 31-11626 31-11626 31-11626 31-11626 31-11626	00.6666
XII= 28.000	X.Z 13.64475 13.62826 13.61366 13.58845 13.58841 13.54841 13.54841 13.54841 13.54841 13.26830 13.22559 13.17180	X X X X X X X X X X X X X X X X X X X	20.54298 20.45625 20.41642 20.31525 20.33951 20.30726		NTUM FLUX =
COORDINATE.	STRM FNCT 0.000 0.004 0.015 0.031 0.052 0.	STRM FNCT 0.000 .004 .008 .016	125 250 250 375 500 1000	ON COORDINATE, XII= 40. 12 STRM FNCT	XIAL MOME
STATION CO	x x x x x x x x x x x x x x x x x x x	10N 000 0031 063 125 250		X12 STATION CO 8.000 8.053 8.053 8.250 8.250 9.000 10.000 11.000 12.000 16.000 16.000 16.000 16.000	101

IDENT = NASA INLET CONFIGURATION NO. 8

ROUNDARY TO CHN=W2

LOWER

STREAMLINE COORDINATE, XIZ= 0.000.

PT/P1	-	-	-	-	-	-	-	-	7:0	7:	7.	~	-	7:	-	~	7:	-	_) · [7	=	~	7	-	-	-	
AMAX-A)/AMAX	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	F. 000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	
_	0.000.0	000000	000000	000000	0.0000	000000	0000.0	000000	0.0000	000000	000000	000000	0.000	0000-0	000000	0.0000	000000	0.0000	000000	000000	0.0000	000000	00000	00000	000000	00000	000000	
MACH	. 7979	. 7902	.1754	. 7585	.7274	.7000	.6847	.6677	9159.	.6437	.6367	.6306	.6250	.6216	.6176	2419.	8609	-6062	.6031	.6000	6965	.5899	.5708	.5434	.5108	.4782	.4211	
PS/PT	.657	299•	-672	.683	.703	.721	.731	277.	.752	.757	.761	.765	.768	.771	.773	.775	.778	.780	-782	. 784	.786	.790	-802	.81a	.837	.855	•882	
g S	• 005	.022	• 054	-092	.161	.221	•254	.291	.326	. 343	.358	.371	.383	. 390	.398	905	514.	.422	625	.435	2445	.456	965.	.551	.615	.677	.780	
PS/P0	1.002	1.010	1.024	1.041	1.072	1.099	1.114	1.130	1.146	1.154	1.160	1.166	1.171	1.175	1.179	1.182	1.186	1.189	1.192	1.195	1.198	1.204	1.222	1.247	1.276	1.304	1.349	
CURVE	000000	00000.0	00000-0	0000000	00000.0	00000-0	0000000	0000000	00000 0	0000000	0000000	0000000	0000000	0.0000.0	0.000000	0.0000.0	0000000	000000	0.00000	0.00000	0.00000	00000.0	0000000	0000000	0.00000	00000-0	0000000	
ANGE	00000	000.0	0.000	000-0	000.0	000.0	070.0	0.000	000.0	000.0	0.0.0	000.0	00000	000.0	0.000	0.000	000.0	000.0	00000	0.000	00000	00000	00000	00000	000-0	000.0	0.000	
YW.RW	0.0000.0	0.0000.0	0.00000	0.0000.0	0.0000.0	0.0000.0	0.0000.0	0.0000.0	0.0000.0	0.0000.0	0.0000.0	0.0000.0	0.000.0	00000.0	09000.0	0.0000	00000.0	0.0000.0	00000-0	0.0000.0	00000.0	09000	00000.0	00000.0	0.0000.0	0.0000	0.0000.0	
WY-ZW	-24.99559	-55.47846	-14.95078	-11.17825	-7.37215	-5.45549	72484.4-	-3.51183	-2.54305	-2.06163	-1.58640	-1.12267	67557	26422	.01233	46833	1.07623	1.65330	2.21656	2.77223	3,32855	4.44541	6.71657	9.02165	11.30721	13.54280	17.95253	
S 1 %	00000	7.517	15.045	18.817	22.623	24.543	25.511	56.444	27.453	27.434	28.409	24.973	29.320	29.731	30.00B	30.464	31.072	31.649	32.212	32.768	33.324	34.441	36.712	39.017	41.303	43.538	47.948	
X I 1	00000	000.7	8.000	10.000	12.000	13.000	13.500	14.000	14.500	14.750	15.000	15.250	15.500	15.750	16.000	16.250	16.500	16.750	17.000	17.250	17.500	18.000	15.000	20.000	21.000	22.000	24.000	
																				•						_		

1.000

BOUNDARY TO CHN=#2

UPPER

STREAMLINE CUORDINATE. XIZ= 8.000.

PT/PT0	1.000	1.00	1.000	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	1.00	7.00	1.00	1.00	1.000	1.00	1.00	1.00	7.00
(AMAX-A)/AMAX	014.	804.	707.	004.	1.66.	.383	.377	.369	.359	.353	345	336	.325	916	.311	.307	301	962.	562.	162.	682.	.287
COPI	000000	0000	-0002	*000*	.0014	.0027	.0038	.0055	.0082	.0101	.0126	.0159	.0208	.0241	.0287	.0318	.0358	.0384	.0415	.0455	• 0479	.0508
MACH	.7979	. 7905	.7773	.7634	.7389	.7213	.7081	.6920	.6707	.6568	9869*	.6152	.5742	.5477	4952	9957	9368	.3477	.2855	.1862	.1112	0000-0
PS/PT	.657	799.	.671	.680	969.	.707	.716	.726	.740	672.	.766	.775	.800	.816	.846	.867	868.	.920	. 945	916.	166.	1.000
చి	• 005	.021	.050	.081	.135	•114	.203	.238	.285	315.	.354	.403	£84°	.543	5.645	7117	458	16R.	EBY.	1.089	1.141	1.170
PS/PO	1.002	1.009	1.023	1.036	1.061	1.078	1.001	1.107	1.128	1.141	1.158	1,181	1,219	1,243	1.289	1,321	1,369	1.402	1.440	1.488	115.1	1.524
CURVE	000000	00011	00073	0014B	00454	00964	00840	01651	01639	03431	02671	04957	07431	90060-	22723	-,17157	-,51384	52294	- 78494	-1.08081	-1.91520	4.74546
ANGW	. 074	260.	.277	.514	1.102	1.872	2.330	3.054	3,993	4.675	2.447	6.523	8.191	6.297	11,433	12,774	15.082	16.826	19.024	22,169	24.691	-16.188
7 E + 72 E	6.91374	6.92448	6.94608	6.97113	7.02250	7.67103	7.10549	7.14546	7.20676	7.24193	7.28371	7.33247	7,39216	7.42779	7.46943	11757.1	7.52195	7,53813	7,55613	7.57670	7.58832	7.50143
MZ · MX	-30.00007	-22.48443	-14.96881	-11.21107	-7.45362	-5.57534	-4.63652	-3.69807	-2.76041	-2.29201	-1.82414	-1.35646	89106	-,65892	-,42778	-,31298	-, 19891	-,14246	0H657	03159	00463	.02163
3 S	0.000	7.516	15.031	18.749	22.547	24.426	25.365	26.305	27.244	27.714	24.1P4	28.653	29.123	29,358	24,593	29.716	29.828	29.846	59.945	30.004	30.033	30.063
x I 1	00000	4.000	8.000	10.000	12.000	13.000	13.500	14.000	14.500	14.750	15.000	15.250	15.500	15,625	15,750	15,812	15,875	15,906	15,934	15,969	15,944	16.000

IDENT = NASA INLET CONFIGURATION NO. 8

~	UPPER AC	UPPER ROUNDARY TO CHN=W2	CHN=NS .	STREAML INE	•	COORDINATE. X12=	8.000.						
	x 11	SIW	XW.ZW	YWORK	ANGE	CURVW	PS/PO	მ	PS/PT	MACH	(AMAX-A)	YAMA'	1/PT0
	16.000	0.000	.02163		-16,188	4.74546	1.524	1.170	1.000	00000	.0508	.287	1.000
	16.016	• 035	.04043	7.57254	-52,792	-3.90349	1.504	1.126	.987	.1370	.0445	252	1.000
	16.031	690.	•06296		-45.845	-3.13274	1.463	1.034	096.	.2429	.0393	.297	1.000
	16.047	.104	.08818	7.52292	-40.439	-2.38516	1.419	.936	.931	.3207	.0350	301	1.000
	16.062	.138	.11529	7.50159	-36.076	-2.02090	1.376	.839	.903	.3855	.0315	305	1.000
	16.094	.207	17351	7.46405	-28.929	-1.63441	1.289	949.	.846	6767	•0264	.312	1.000
,	16,125	.276	.23555	7.43451	-23.108	-1.34733	1.224	667.	.803	2695	.0232	.318	1.000
	16.156	.345	.30014	7.4102H	-16.145	-1.15462	1.163	.364	.763	.6338	.0213	.322	1.000
	16.197	414.	.36645	7.39127	-13,983	4.4429	1.120	.269	.735	.6781	.0202	.326	1.000
	16.250	.582	.5014R	7.36567	-7.774	64903	1.096	\$12	.719	.7026	.0191	330	1.000
	16,375	.828	.11725	7.34777	764	07177	1.121.	.271	.736	.6770	.0183	333	1.000
	16.500		1.05324	7.34661	•	05454	1.147	.328	.752.	.6507	.0182	334	1.000
•	16.750		1.60517	7.35544	-	01992	1.170	379	.767	.6268	.0188	.332	1.000
	17.600		2.15698	7.37033	-	.61471	1.188	614.	.779	.6678	.0199	.329	1.000
	17.250	2.760	2,70887	7.38163	•	00013	1.191	124.	.781	2409.	.0207	.327	1.000
	17.500	3.312	3.26079	7.39125	-	00013	1.193	.430	. 783	•6024	.0215	.326	3.000
	18.000	4.416	4.36463	7.41061	-	00013	1.197	044.	. 785	.5979	.0230	.322	1.000
	19.000	479.9	6.57212	7.45788	'n	01403	1.197	144.	.786	.5975	•0268	.313	1.000
	20.000	8.832	8.77707	7.57223	m	01321	1.225	.501	.803	.5682	.0368	.292	1.000
	21.000	11.040	10.97791	7.74954	'n	00874	1.263	.587	. 829	.5253	.0551	.259	1.000
	22.000	. 13.248	13,17521	7.96680	ហ	00063	1.304	.678	.855	.4780	.0818	.216	1.000
1	24.000	17.664	17,57273	8.37065	4.068	.01127	1.351	.783	.886	.4190	.1413	135	1.000
9												,	

(AXIAL FORCES ONLY)
134-4362
0-0000
16.1054
150.5416
150.6166
-.0750

INTEGRAL MOMENTUM BALANCE. CHN=W2
ENTERING MOMENTUM
LOWER BOUNDARY PHESSURE FORCE
UPPER BOUNDARY PHESSURE FORCE

1.000

= 011/11

SUM OF AHOVE

LEAVING MOMENTUM ERROR

LOWER

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BOUNDARY TO CHN=EXT

		B0<0.	00000	000	1.170	1.524	4.14546	13.827	7.60143	.02163	30.063	16.000
000	.289	0479	1112	166	1.141	1.511	-1.91520	24.691	7.58832	00463	30.033	15,984
		0455	.1862	916	1.089	1.488	-1.08081	22,169	7.57670	03159	30.004	15,969
		0415	.2855	.945	. 983	1.440	78494	19,028	7,55613	08657	546.62	15,938
		0384	.3477	.920	168.	1.402	52294	16,826	7,53813	-,14246	29,886	15,906
		035R	.3948	.898	.824	1.369	51384	15.082	7,52199	16861-	29.828	15,875
		0318	.4566	.867	.117	1.321	17157	12,774	7.49411	-,31298	29.710	15,812
		0287	.4952	.846	. 645	. 1.289	-,22723	11,433	7.46943	-,42778	29.593	15,750
		0241	.5477	.816	.543	1.243	90060*-	9.297	7.42779	65892	29,358	15,625
	•	0208	.5742	.800	647.	1.219	07431	8.191	7.39216	A9106	29.123	15.500
		0159	.6152	775	.403	1.181	04957	6,523	7,33247	-1:35696	28.653	15,250
		0126	.6386	.760	. 354	1.15H	02671	264.5	7,28371	-1,82414	28.144.	15.000
		0101	.6568	.749	.315	1.141	03431	4.675	7.24193	-2,29201	27,714	14.750
		0082	.6707	.740	.285	1,128	01639	3,993	7,20676	-2,76041	27.244	14,500
		0055	.6920	.726	.238	1.107	01851	3,054	7.14886	-3,69867	26,305	14.000
		0038	.7081	.716	.203	1.091	0.800	2,330	7,10549	-4.63652	25,365	13,500
		0027	.7213	.707	.174	1.078	00864	1,672	7.07103	-5,57534	24.426	13,000
		0014	.7389	969*	.135	1,061	+5+00	1,162	7.02250	-7,45362	22.547	12,000
		0004	.7634	.680	.081	1.036	00148	.514	6.97113	-11,21107	18.789	10.000
		0002	.7773	.671	0.50	1,023	00073	.277	6.94608	-14.96881	15,031	8,000
		0000	. 1905	.662	.021	1.009	00011	160.	6.92448	-22,48443	7.516	0000*
		000000	. 1979	.657	.005	1.002	0000000	. 074	6.91374	-30,00007	0.000	00000
Œ	CAMAX-AI/	COPI	MACH	PS/PT	a a	PS/PO	CURVW	ANGM	YW. RW	WZ.WX	SIN	x11
			-		,*							

TT/TT0 = 1.000

ADDITIVE DRAG = -.0508

UPPER ROUNDARY TO CHN=EXT , STREAMLINE COORDINATE, XI2= 16.000.

PT/PT0	1.000	1.000	1,000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000
X-A)/AMAX	-43.482	-43,514	-43,552	-43,572	-43,594	-43,616	-43,635	-43,661	-43,687	-43,711	-43.734	-43.777	-43.813
CDPI (AMA	000000	.0001	.0003	.0003	*000	*000°	*000	*000	*000	*000	.0003	• 0005	·0000·
MACH	. 7979	. 7983	. 7986	. 7988	.7990	7661	1661.	.6001	9008	.8009	.8012	.6017	.8024
PS/PT	.657	.657	.657	.657	.657	.656	•656	959*	•656	.655	.655	• 655	• 654
a 5	• 005	*00	.003	.003	200°	100.	.001	000.1	001	002	003	004	005
PS/PO	1.002	1.002	1.001	1.001	1.001	100.1	1.000	000.1	1.000	666	666	856	866
CURV	00000	00007	-,00008	P0000*-	00007	50000-	u0003	00000.	.00003	\$0000	.00000	.00007	00000-
ANCM	.163	.179	.211	.227	242	.253	.260	. 263	.260	.251	.239	.213	.198
YW.RW	60.02524	60.04721	60.07234	60.08625	60.10084	60.11558	60,12845	60.14629	62691.09	60.17973	20561-09	60.22376	60.24851
XW.ZW	-30.17272	-22,68958	-15,29995	-11.66093	-8,10485	-4.69911	-1. H3106	2.06866	5,78973	9.47234	13.13518	20.30726	27.28820
SIW	00000	7.483	14.873	18.512	22,043	25.474	246,342	32,242	35,463	39.645	43,398	56.480	57.461
		000.4											

11/110 = 1.000

INTEGRAL MOMENTUM BALANCE. CHNZEXT	(AXIAL	(AXIAL FORCES ONLY)
ENTEPING MOMENTUM	9999.0358	
LOWER BOUNDARY PRESSURE FORCE :	-1,1715	
UPPER BOUNDARY PRESSURE FORCE	.0051	
SUM OF ABOVE	9997.8694	
LEAVING MOMENTUM	1166.8666	
acaas	C451 1.	

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12.0 PROGRAM INPUT SHEETS

Page	of	
STC/	Sheet-1	

	ape? output tape F T or F	?			
1 STC					
Mach number, am	bient pressure and	temperature,	fluid prop	perties	
\$A	(1.)	(1.)	(1.)	(1.4	·)
MACHØ=,	TSØ=, PSØ	, RG=_	,	GAM=	,
Highlight radiu	s, maximum body ra	dius, body clos	sure tole	rance	
RHL=, R	M=, TTE=	,			
axisymmetric or (T) or F	planar?		•		
AXI=,					
spacial grid re	finement criteria,	see notes			
GR(1)=,	***************************************	_,, _	·	,	
NGR=,					
GZ(1)=,	· · · · · · · · · · · · · · · · · · ·	,	,	<u> </u>	
SGZ(1)=,		_,, _	,	·	
NGZ=,					.*
maximum Mach nu	mber increment bet	ween grid poin	ts		•
	normal				
direction (0.1)	direction (0.1)	•			`
VMG1=,	VMG2=	•			
maximum number	of refinements		:		
MAXIT=,					

Page	of	
STC/sh	eet-2	

Boundary Coordinates

	boundary name	channel name	
X47	4	A	•
BDŸ			
uį	per bounda T or F	ary? an	gle inpu -no, F-y
Α 1	JPPER=	, ZRØNLY=	
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Channel Flow Properties

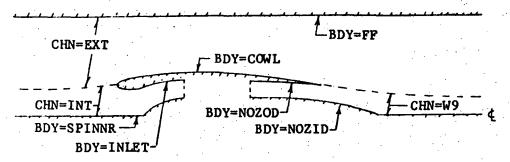
Page ___ of ___ STC/Sheet-3

channel		
$\frac{1}{2}$ name		•
3 CHN		
\$A		
ratio of	• •	flow rate
specific	gas	may be
heats	constant	adjusted?
(1.4)	(1.0)	(T) or F
	operties, see motes total pressu	
TTØ=	_, PTØ=	,
Mach no.	static temp	static pressure
MACHØ=	_, TSØ=	, PSØ=
flow area	normalized by	A _{HL} .
AØ=		

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General Instruction and Notes for Sheet-1 of the STC Input Forms

- 1) The STC Program computes the subsonic and transonic field of inviscid flow past (and within) arbitrarily shaped planar and axisymmetric bodies. Inlet and exhaust nozzle flows wherein there may exist jet streams with differing energies are typical applications.
- The total flow is composed of one or more streams, the properties of which are to be listed on Sheet-3 (except as noted below). Each stream occupies a "channel" which is identified by a one to six character alphanumeric word. Each channel must be bounded, at least in part, by an "upper boundary" and a "lower boundary". Each boundary is also given an identifying one to six character name and the coordinates are listed on Sheet-2. The following sketch illustrates the naming of channels (CHN) and boundaries (BDY).



An external flow channel must be named EXT, the recommended name for the inlet capture flow channel is INT, and the far-field interface boundary must be named FF. Otherwise the selection of the channel and boundary names is arbitrary. The special channel names EXT and INT cause extra streamlines to be placed in the first refined grid. The boundary name FF indicates that the boundary condition on FF is to be obtained from an analytic far-field solution.

There is no specific limit to the complexity of the flow field in regard to the number of channels or the number of boundaries. Limits are set on the total amount of data which may be input. 3) The solution method consists of constructing a grid of streamlines and orthogonal lines. Starting with two streamlines per channel (one for each boundary) and an orthogonal passing through the first and last point of each boundary, the grid is automatically refined by dividing the grid intervals in half and in half again as required. The numerical resolution, the solution accuracy and the computer execution cost are all directly related to the extent of grid refinement. The input variable MAXIT determines the maximum number of refinements. Providing this limit is not exceeded, the grid will be refined, locally as required, until the spacing of orthogonals and streamlines is less than the value determined from the SGR and SGZ tables and the Mach number difference between any two points on a streamline or an orthogonal line is less than VMG1 and VMG2, respectively. Grid size values versus radius (or y-ordinate) are to be tabulated after SGR and GR, respectively. NGR is the number of entries in each list. Grid size versus the axial coordinate is to be tabulated after SGZ and GZ, respectively. NGZ is the number of GZ values. If dimensional values of RG, TSO and PSO are input (see Note 6), then VMG1 and VMG2 must have units of velocity rather than Mach number. See supplemental notes for additional details.

A partially refined grid may be saved on tape by specifying a T in column 24 of the first card, or read from a previously created tape by specifying at T in column 14.

If TAPE 1 and/or TAPE 2 are not assigned via a REQUEST card, they are assigned to disc. This allows the user to obtain output for a given refinement level and provides the option of changing input parameters on the restart. For the restart case, specify a T in column 14 of the first data card and include in the \$A list only those input quantities (viz; MAXIT) which differ from those originally input.

4. In the initial calculation grid, an orthogonal line will pass through each leading and trailing edge point and through each sharp corner point (i.e. a point on the boundary with an angle discontinuity). It is not possible to analyze a configuration in which two or more of these points

- are approximately opposite to each other. For example, if a configuration contains more than one leading edge, the edges must be staggered relative to the streamwise direction.
- 5. A free stream Mach number is specified by supplying a value of MACHØ.
- 6. Perfect gas assumptions are employed and the levels of ambient pressure and temperature may be dimensionless (TSO=PSO=RG=1) or dimensional.

 Dimensional values in a consistent set of units as described in Reference 5 should be supplied if boundary layer calculations are requested.
- 7. A reference (or highlight) area is calculated from the input value of $R_{\rm HI.}$ as follows:

axisymmetric:
$$A_{HL} = \pi R_{HL}^2$$

planar:
$$A_{HL} = \Delta y_{HL} = R_{HL}$$

This reference area (or Δy in the planar case) is used for defining the mass flow for each channel. See STC/Sheet-3 note ____.

8. Computed pressure drag forces are normalized by the (maximum) body area where

axisymmetric:
$$Am = \pi R_m^2$$

planar:
$$A_m = \Delta y_m = R_m$$

- 9. Finite trailing edge thickness is permitted; the maximum thickness, or body closure tolerance, is to be supplied after TTE.
- 10. On this and the following input sheets, the values in parenthesis are used if other values are not input.

Notes for Sheet-2 of the STC Input Forms

Use one of these sheets for each boundary. Supply a one to six character name to identify the boundary in column 14 of the first card. Also indicate the name of the channel to which the boundary is adjacent in column 24. On the second card indicate whether the boundary is above (UPPER = T) or below (UPPER = F) the channel.

- 2. The upper or lower "contour" which bounds a given stream may be composed of several "boundaries". In this case an input sheet must be completed for each boundary; the last point of the first boundary must have the same coordinates as the first point of the second boundary, and so forth. This option is useful when considering variable geometry configurations such as flaps or movable nozzle parts. The movable part may be translated and rotated, as indicated by Note 8, while the fixed part is held stationary.
- 3. List values of Z (or X), R (or Y) and the surface angle in degrees at discrete points along this boundary contour after the symbol "B(1)=". Points at sharp corners must be listed twice, one time for each angle which exists at that point. In each interval, the STC Program fits a locally rotated cubic polynomial. The input points must be smooth and consistent with the specified angles.

All points are to be listed in the streamwise direction. For an inlet lip, the points are listed by starting at the highlight point and then proceeding around the nose to the trailing edge or downstream boundary. The internal and external surfaces are listed separately under different boundary names. However, the coordinates of the first point must be the same with ANGD equal to +90° for the external surface and -90° for the internal surface.

It is recommended that the boundary coordinates and angles be obtained from an analytic definition of the contour, and that around the nose, angle variations between points be 20° or less.

- 4. Pressure and Mach number distribution data will be printed at each orthogonal intersection with the boundary, and not at each input boundary point. Orthogonal stations, however, will be placed at any repeated point in the boundary table. List the same points twice if it is desired to have an orthogonal placed in that position. (This option is modified slightly when ZRONLY = T.) Orthogonal stations are always placed at the beginning and end of a boundary and at a juncture point between boundaries along the same contour.
- 5. If the coordinates but not the angles are known, the third column in the B-input array may be omitted. In this case specify ZRONLY = T and list the

coordinates twice at any point where a curvature jump or an angle jump exists. The double points will later be deleted if the angle discontinuity is less than 0.01 degrees. These double points are removed because extra calculation stations (see Note 5) are usually not desired at such points. However, the double point angle tolerance, DBLPTS, preset as 0.01, may be input as zero if such double points are to be retained.

- 6. With either input option, care must be taken to specify the coordinates with precision. The round off or reading error of the coordinate data should be less than $\Delta S^2/(10*L)$, where ΔS is the local distance between points and L is some characteristic length, say the length of the cowl. Conversely, the spacing between points should not be less than $(10 \ \delta L)^{1/2}$ where δ is the relative accuracy of the coordinate data. The tabulated output curvatures may be consulted to verify the smoothness of the input data.
- 7. NACA Series 1 Cow1 coordinates are stored internally. With the ZRONLY = T option they may be selected by listing:

where X_1 , Y_1 are the highlight coordinates and X_2 , Y_2 is the position of the maximum diameter at the end of the Series 1 contour segment.

8. The input coordinates of a boundary may be adjusted by supplying the following input quantities not shown on the front of this sheet:

ROTATE	angular rotation in degrees					
ZPIVOT RPIVOT	pivot coordinates					
SCALE	multiplicative constant to be applied to the coordinate data					
ZTRANS	translation increment in the axial direction					
ው ሞው ለአነር	translation on increment in the radial/vertical direction					

The order of transformation is rotation, scaling and translation. Hence, the pivot coordinates are in the same coordinate frame as the input data and the translation increments are in the rotated coordinate frame after scaling. It is only necessary to input data for the transformation operations to be executed.

Notes for Sheet-3 of the STC Input Forms

- 1. Use one of these sheets for each channel to supply entrance flow properties.

 (See exception under Note 5).
- 2. Of the input items shown on the face of the input sheet, use only those which are required for the selected options.
- 3. The total pressure and total temperature may be input by either of the following two procedures:
 - a) Specify TTO and PTO if the stagnation properties are known.

 These values may be normalized by the free stream ambient temperature and pressure.
 - Specify MACHO, TSO and PSO if the static properties and Mach number are known. Again TSO and PSO may be normalized by the free stream ambient values. If only MACHO is supplied (TSO & PSO are omitted) the TSO and PSO values from STC/Sheet-1 will be used.

If neither of the above is input, free stream values as supplied on Sheet-1 are used for MACHO, PTO and TTO.

- 4. If the gas constant, RG, is different from the value supplied on STC/Sheet-1, supply the value which applies to this channel. RG, TSØ TTO, PSO and PTO may all be given as dimensionless (normalized by free stream ambient) or dimensional using a consistant set of units.
- 5. Input a value AO for the determination of the channel flow rate. AO is an area fraction mormalized by $A_{\rm HL}$ as defined under Note 7 of Sheet-1; the (dimensional) channel flow area is then the product $AO*A_{\rm HL}$. The flow rate for the channel is computed by using one-dimensional relations from the total properties (as determined under Notes 3 & 4), the supplied Mach number, MACHØ, and the flow area. For internal inlet channels, specify $R_{\rm HL}$ as the highlight radius and AO as the mass flow ratio.

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- 5. If for any channel the input data on this sheet is not supplied, the reference properties on STC/Sheet-1 will be employed and the frontal area calculated at the entrance station will be used. This option is suggested for an external stream.
- 7. Although approximate flow rates must always be supplied according to Note 5, the program will adjust channel flow rates as required to meet the zero pressure loading conditions at a trailing edge or to meet a maximum (choked) flow rate. The number of channels which require flow rate adjustment is equal to the number of trailing edges. If the flow rate is not to be varied for this channel, specify VARY = F.

Grid Refinement Criteria - Supplemental Notes

One of the important controls that the user should exercise in operating the STC program is the Grid Refinement Specification. In simpliest terms the user is required to input the following three quantities:

SGR = ____, Nominal distance between streamlines and between orthogonal lines

VMG1 = ____, Nominal Mach number (velocity) difference between points along a streamline

VMG2 = ____, Nominal Mach number (velocity) difference between points along an orthogonal line

Note, if dimensional values of the perfect gas constant and temperature are input then VMG1 and VMG2 are velocity differences; otherwise VMG1 and VMG2 are to be input as a Mach number difference.

To illustrate the function of these input items, consider the question of whether or not a new orthogonal line should be inserted between existing orthogonals as shown in Figure 1a. To answer this question, the program computes, say, between the (i) and (i+1) orthogonals, the following quantities at each streamline:

(1a)
$$R_{s_1} = \frac{\Delta S1}{SG}$$
 (SG = SGR) (1a)

(2a)
$$R_{v_{j}} = \frac{|v_{j+1,j} - v_{j,j}|}{VMG1}$$
 $j = 1, 2, 3,...$ (1b)

Figuratively speaking, these values are then plotted on Figure 2.

If all the Rs_j,Rf_j points fall outside of Region (1) a new orthogonal will <u>not</u> be inserted into the i,i+l interval. But if one or more points do fall in Region (1), a new orthogonal is required. The new line will be extended to all streamlines for which the rs_j,rv_j values fall in Region (2), or to a minimum of five streamlines.

Thus, according to the criteria illustrated in Figure 2, the maximum distance between any two points along a streamline is SG (=SGR). If a velocity gradient exists along the streamline, the maximum distance between points is reduced. When the spacing ratio Rs becomes very small (Rs < 0.24) relatively large velocity differences between points is allowed, a feature which is intended to eliminate excessive refinement near stagnation points.

A similar criteria is used for determining when additional streamlines are required. The only variation is that Eqs. (1a) and (2a) are replaced by Eqs. (1b) and (2b):

$$R_{s_{i}} = \frac{\Delta S2_{i}}{SG}$$
 (1b)

$$R_{v_{i}} = \frac{|v_{i,j+1} - v_{i,j}|}{VMG2} \qquad i = 1, 2, 3...$$
 (2b)

Streamlines and orthogonal lines are inserted until the above criteria is satisfied (or until the number of refinements equals MAXIT). The internal values of VMG1 and VMG2 (0.1) are appropriate for most configurations, and unless these values are to be altered the VMG1 and VMG2 input may be omitted. However, the user must always supply a value for SGR. In selecting this value care must be taken to ensure that a moderate grid will develop so that reasonable accuracy is obtained without sacrificing computing efficiency with an excessive number of grid points.

As a guide to the selection of SGR it is suggested that SGR be set to about twice the expected grid spacing. Because new grid intervals are always obtained by halving existing grid intervals, the average grid size will be less than that required to satisfy the criteria given in Figure 2.

Spatial Variation of Grid Size

For external flow problems, and some internal problems as well, it is necessary to input a spatial grid size variation. The additional input required is:

GR	=	•	,	,	,	,
SGR	=	,	,	,	,	,
GZ	=	•	,	,	,	
SGZ	==	,				

GR and SGR is a table of grid size (SGR) with radius (GR); likewise GZ and SGZ is a table of grid size (GZ) with axial position (SGZ). The value of SG in Eqs. (la) and (lb) at any point, z,r, is then taken as the maximum of the SG's found by linear interpolation in the two tables of radial and axial variations.

Special rules which apply to these input items are as follows:

- 1) If a radial variation (but no axial variation) of grid size is desired, the user must input pairs of values in the SGR and GR lists. GR must be in ascending order. If grid size information is required beyond the limits of the input table, the closest values will be used. Also if the grid size is to be constant with radius no GR input is required and only one value of SGR need be supplied.
- 2) If an axial variation (but no radial variation) of grid size is desired, the user must supply pairs of values in the SGZ and GZ lists. Also he must input one value of SGR which is thy minimum of the SGZ values.
- 3) If both an axial and radial variation of grid size is desired, he should supply appropriate values in both tables. Remember that for any point, r,z, the r-coordinate will be used to obtain a grid size from the GR,SGR table and the z-coordinate will be used to interpolate in the GZ,SGZ table. The maximum of the two interpolated values will then be used in Eqs. (1a) and (1b). Generally, the SGR and SGZ values are set to small values close to a body, or region of interest, and increased to larger values as one moves away from the body.

Input Control of "Partial" Grid Lines

As noted previously, a new orthogonal lines and streamlines are not necessarily extended to the field boundary. Instead, the length of these lines is determined by the size of Region (2) in Figure 2. Notice that Region (2) is increased, and the length of the new grid lines is likewise increased, if CRX, the constant in the equation defining the lower boundary of the region, is decreased. If CRX = 0, then all new grid lines will span the field; that is, full grid lines rather than "partial" grid lines will be inserted.

Values of CRX are preset, but they may be altered by input cards as follows:

Input Name		Preset	Used for Extending
(a)	(b)	Value	
CRX(1)	CRXSL	.375	New Streamlines
CRX(2)	CRXOL	.375	New Orthogonal lines across
	:		a subsonic region
CRX(3)	CRXSS	.125	New Orthogonal lines across
•			a supersonic or mixed flow
			region
CRX(4)	CRXE	0	New orthogonal lines which
	* :		cross a sonic line
CRX (5)	CRXC	0	New Orthogonal lines which
			cross a supersonic to subsonic
			compression line

If two or more of the above values apply, the smaller value will be used.

Recommended Spatial Grid Variation for an Inlet Configuration

Typical input for the spatial variation of grid size for an inlet configuration is given in Figure 3. In this case all dimensions are normalized by the highlight radius. The quoted values of SGR, GR, SGZ, GZ should be scaled by the highlight radius for a given problem. Notice that the combination of the axial and radial variations yields contours of grid size which are roughly centered about the leading edge.

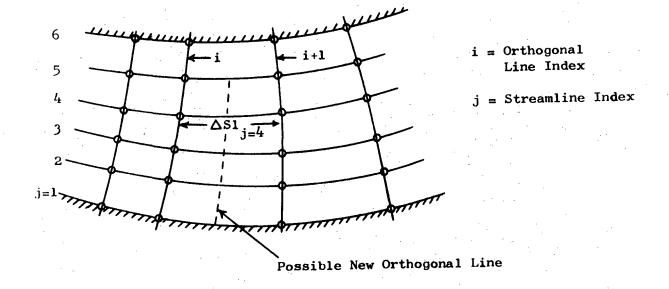


Fig. 12-la Insertion of a New Orthogonal Line

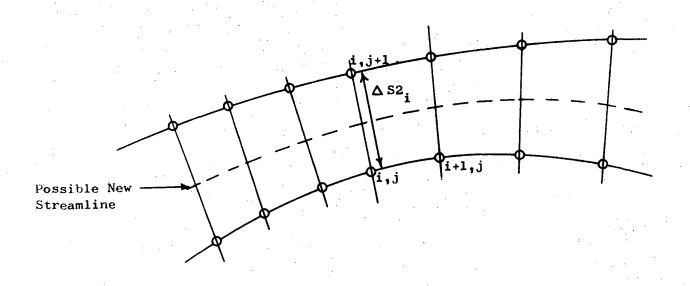


Fig. 12-1b Insertion of a New Streamline

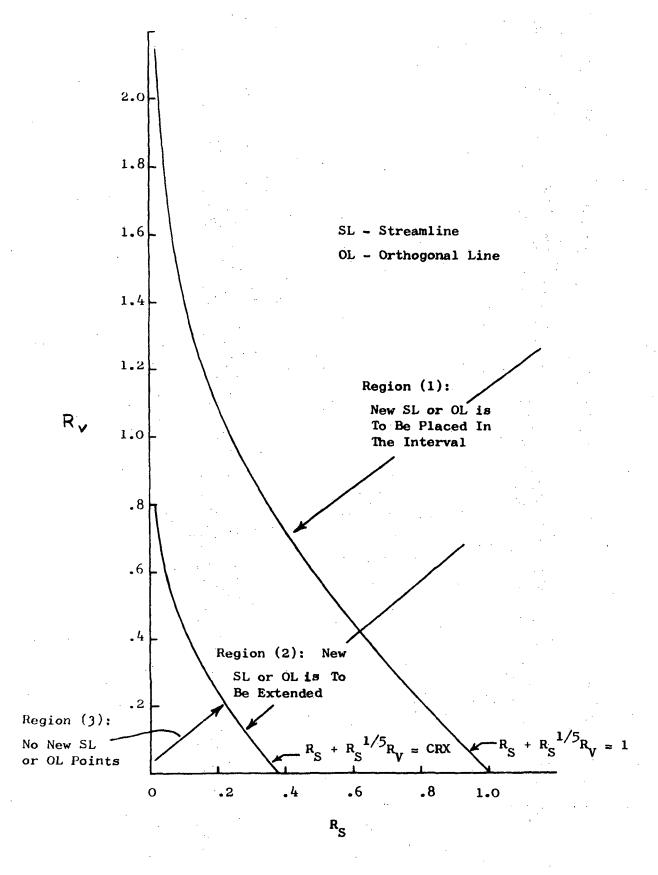
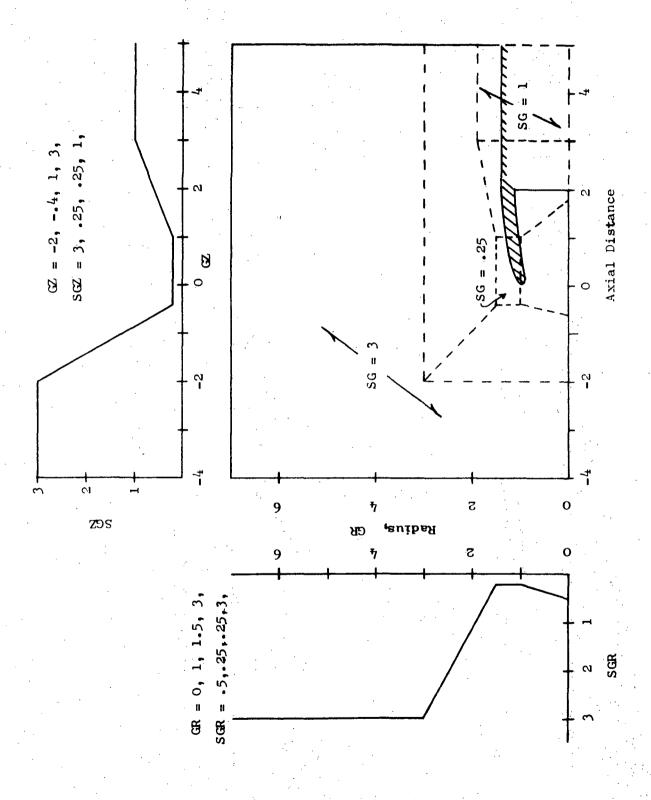


Fig. 12-2 Grid Refinement Criteria



Typical Spacial Grid Size Specification For An Inlet Analysis Fig. 12-3

13.0 REFERENCES

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